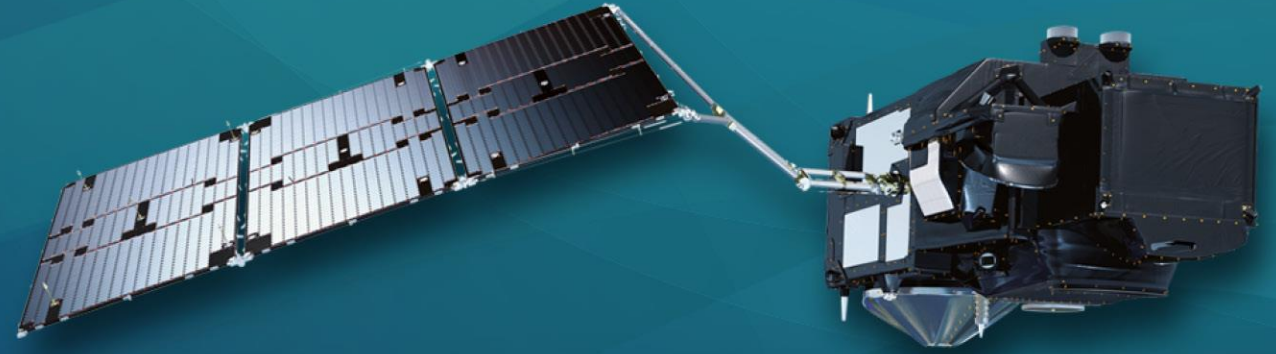




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# 9<sup>th</sup> Sentinel-3 Validation Team meeting 2026

30 March–01 April 2026 | ESA–ESRIN | Frascati (Rome), Italy

## Sci4MaST: Improvements to the SLSTR SST processor

*Owen Embury, Niall McCarroll, Lauren James, Claire Bulgin,  
Jon Mittaz, Chris Merchant, Caroline Ribere*

## University of Reading work in the framework of Activity 1: Improvement to Sentinel-3 SLSTR sea and sea-ice surface temperature product quality

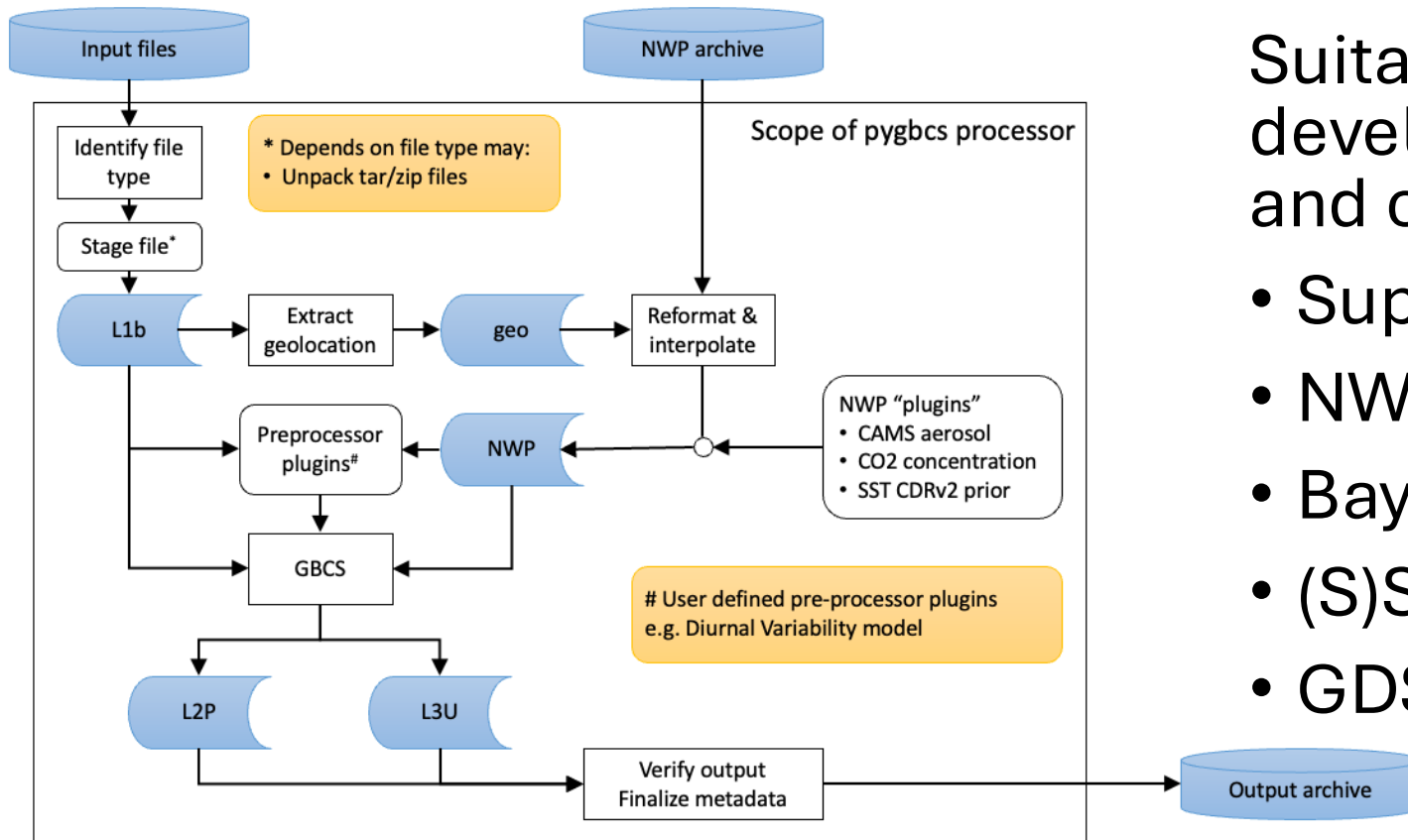
- Sci4MaST Prototype Processor
- Coefficient Generation Tool
- Investigate day-time use of 3.7 micron channel (see poster)

- Bayesian Cloud Detection and SST retrieval processor developed by U. Reading
- Same software as used in SST CCI – proven capability to generate CDR and ICDRs
- Software has been developed under several projects. Primarily:
  - 2005-2008 Thermal and Reflectance Imagery Cloud Screening (TRICS)
  - 2006-2011 ATSR Reprocessing for Climate (ARC)
  - 2011-ongoing ESA SST CCI
- Additional development:
  - EUMETSAT projects, C3S, ARC-Lake, Globolakes, GlobTemperature, CCI-Lakes, CCI-Land, Bureau of Meteorology, NCEO

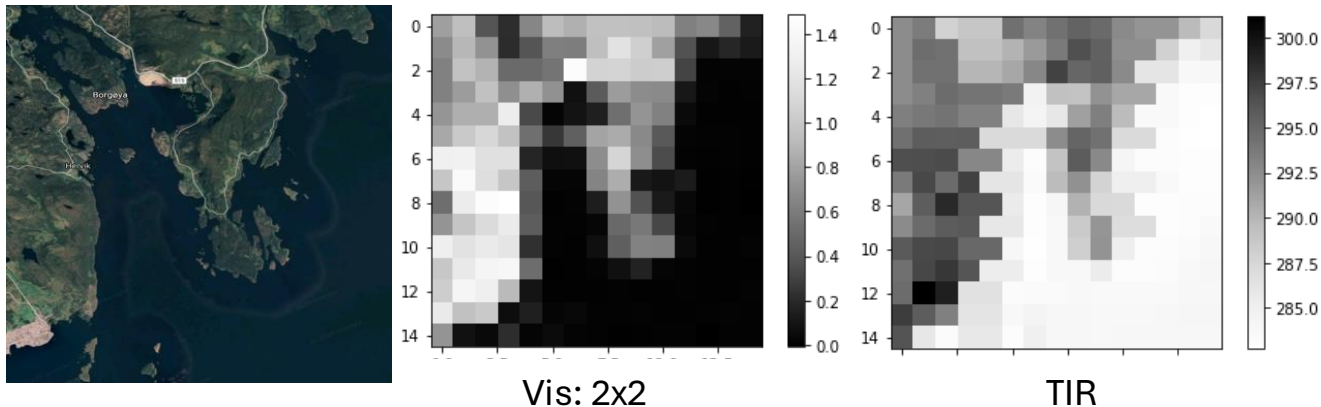
Modern Fortran 2003 and Python 3 code

Suitable for algorithm development, CDR production, and operational SST products

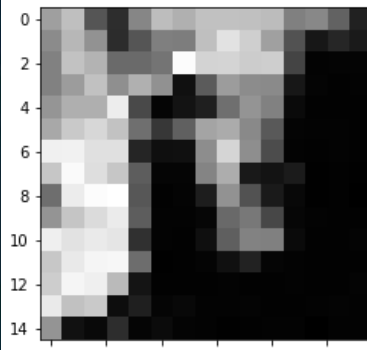
- Supports multiple sensors
- NWP interpolation
- Bayesian Cloud Detection
- (S)ST Retrieval
- GDS format output



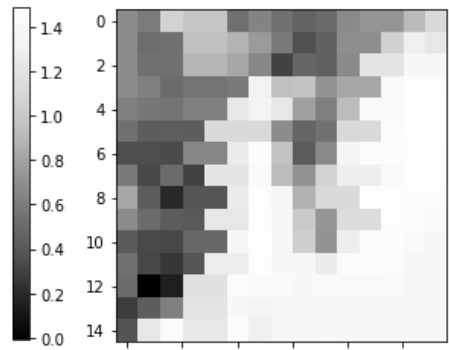
- SLSTR pixels are remapped from conical scan to regular grid aligned with sub-satellite track in Level 1b using nearest neighbour
  - Centre of “observation” can be up to  $\frac{1}{2}$  pixel from nominal location on grid
- Simple 2x2 averaging **cannot** be used to reduce Vis/NIR resolution to match TIR
  - Coastal example where alignment of TIR scan and nominal grid results in saw tooth edge as “best” IR pixel alternates  $+\frac{1}{2}$  and  $-\frac{1}{2}$  offset



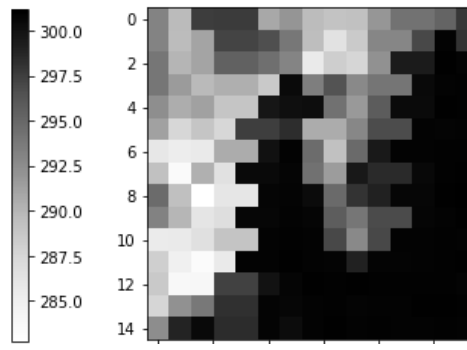
- SLSTR pixels are remapped from conical scan to regular grid aligned with sub-satellite track in Level 1b using nearest neighbour
  - Centre of “observation” can be up to  $\frac{1}{2}$  pixel from nominal location on grid
- Simple 2x2 averaging can not be used to reduce Vis/NIR resolution to match TIR
- K-nearest neighbour remapping gives correct alignment between channels
  - Can include orphan pixels and both a and b stripes



Vis: 2x2

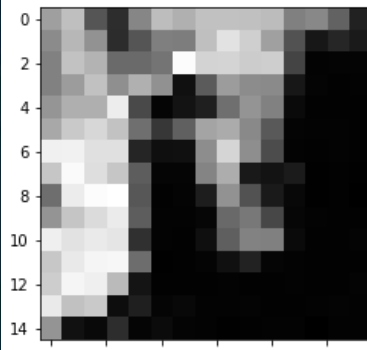


TIR

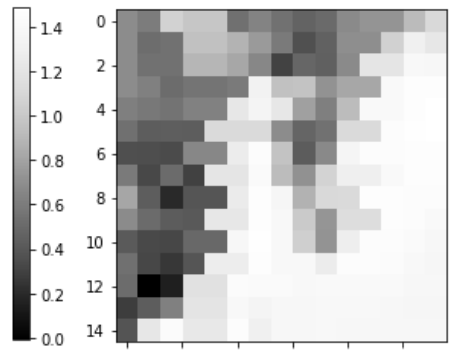


Vis: k-nearest

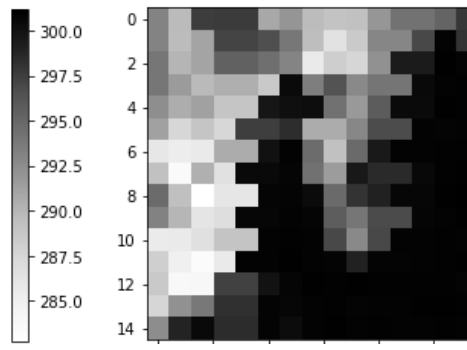
- PP supports k-nearest remapping with user defined k (default=5)
  - Includes options to calculate “sub-pixel texture” as used in previous work
- Can remap during data read or use pre-generated “SLSTR-Lite” files



Vis: 2x2



TIR



Vis: k-nearest

- Estimates the probability that a given pixel is clear from:
  - Observations:  $\mathbf{y}$
  - Expected observations under clear-sky conditions estimated using RTTOV:  $\mathbf{F}(\mathbf{x}_a)$
  - Uncertainties associated with observations ( $\mathbf{S}_\varepsilon$ ) and prior ( $\mathbf{S}_a$ )

- $$P(\text{clear}|\mathbf{y}, \mathbf{x}_a) = \frac{P(\mathbf{y}|\mathbf{x}_a, \text{clear})P(\mathbf{x}_a|\text{clear})P(\text{clear})}{P(\mathbf{y}|\mathbf{x}_a)P(\mathbf{x}_a)}$$

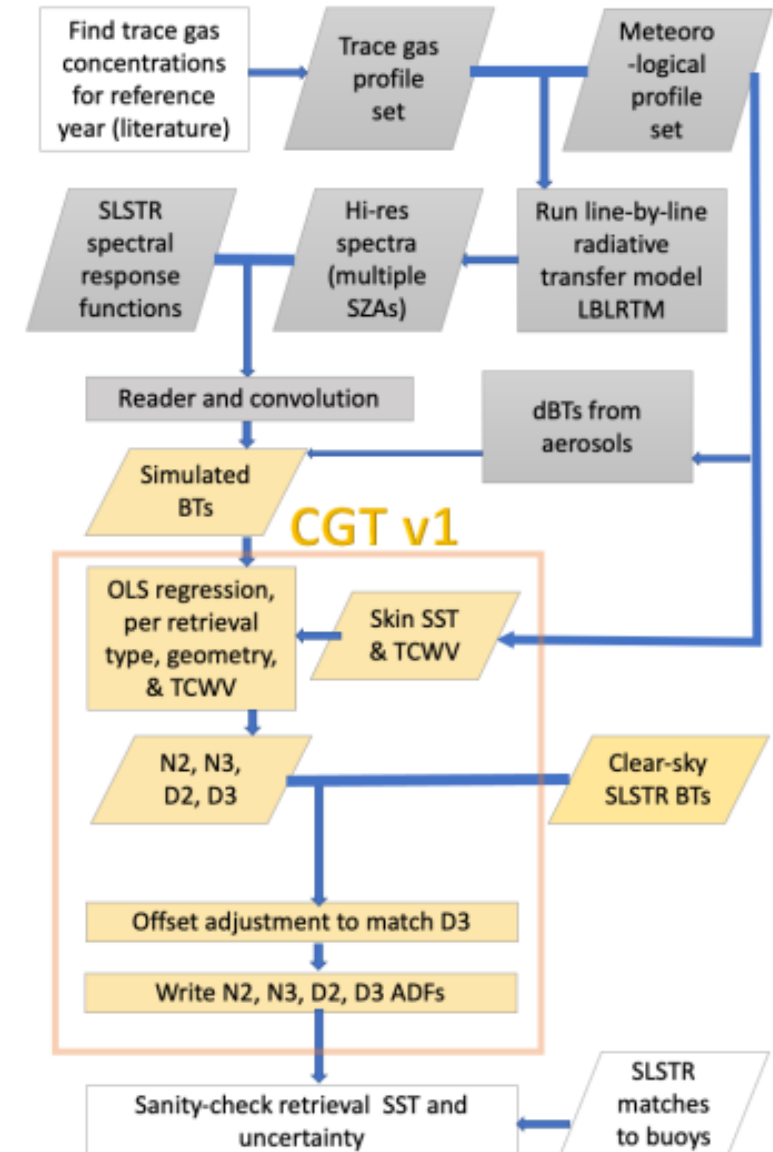
- Probability of observations assuming clear are calculated:

- $$P(\mathbf{y}|\mathbf{x}_a, \text{clear}) = \frac{\exp\left(-0.5(\mathbf{y}-\mathbf{F}(\mathbf{x}_a))^T (\mathbf{K}\mathbf{S}_a\mathbf{K}^T+\mathbf{S}_\varepsilon)^{-1}(\mathbf{y}-\mathbf{F}(\mathbf{x}_a))\right)}{2\pi^{n/2}|\mathbf{K}\mathbf{S}_a\mathbf{K}^T+\mathbf{S}_\varepsilon|^{1/2}}$$

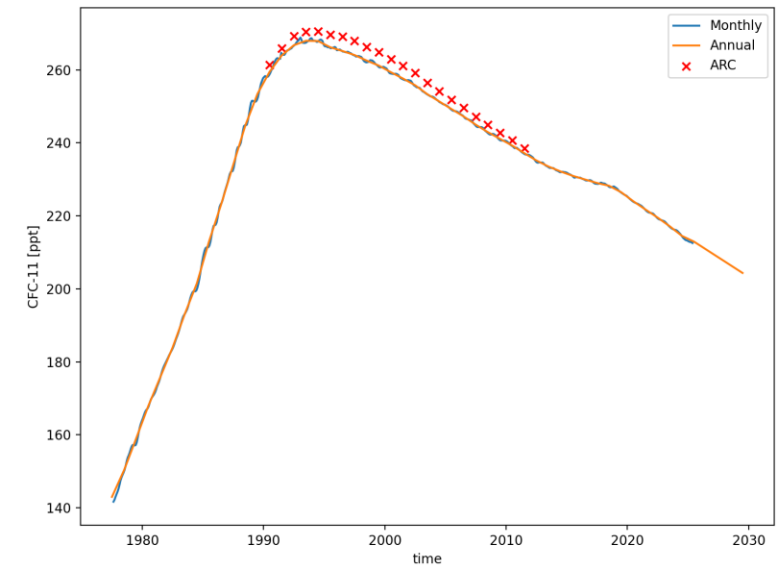
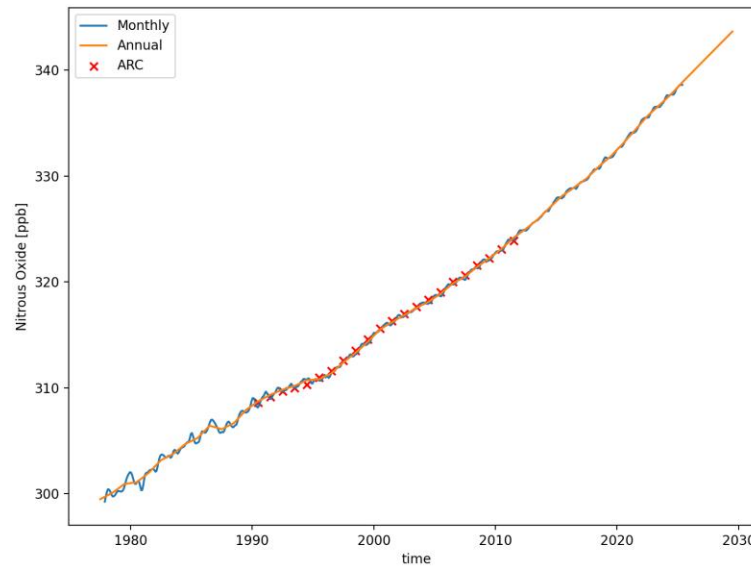
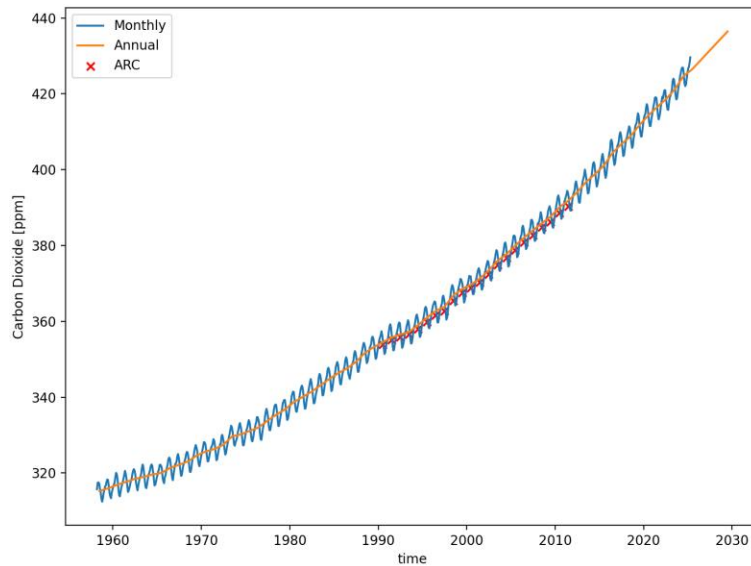
- Probability of observations assuming cloud are taken from lookup tables
- Can also include local measures (e.g. local standard deviation, sub-pixel texture) in Bayesian formulation

- **EUMETSAT Operational processor**
  - Nadir and Oblique view are cloud screened independently
  - Cloudy PDF lookup tables based on MetOp AVHRR observations
  - Dual-view is considered clear if both nadir and oblique classed as clear
- **SST CCI CDR v3 processor**
  - Dual-view Bayesian calculation includes both nadir and oblique view in observation vector
  - Better detection of small / optically thin clouds present in a single view
  - Cloudy PDF lookup tables based on AATSR observations
- **Sci4MaST prototype processor**
  - Full dual-view Bayesian from SST CCI CDRv3 configuration
  - New dual-view cloudy PDFs based on 9 years of SLSTR-A observations
  - Actual match to SLSTR viewing geometry

- Generates SLSTR retrieval coefficients
- Based on ARC and SST CCI software
- Rewritten in modern Python 3
- v1 created coeffs from pre-existing line-by-line radiative transfer output
- v2 extends scope to include:
  - Update trace gas profile set
  - Running line-by-line RTM
  - Convoluting with instrument spectral response functions (SRFs)



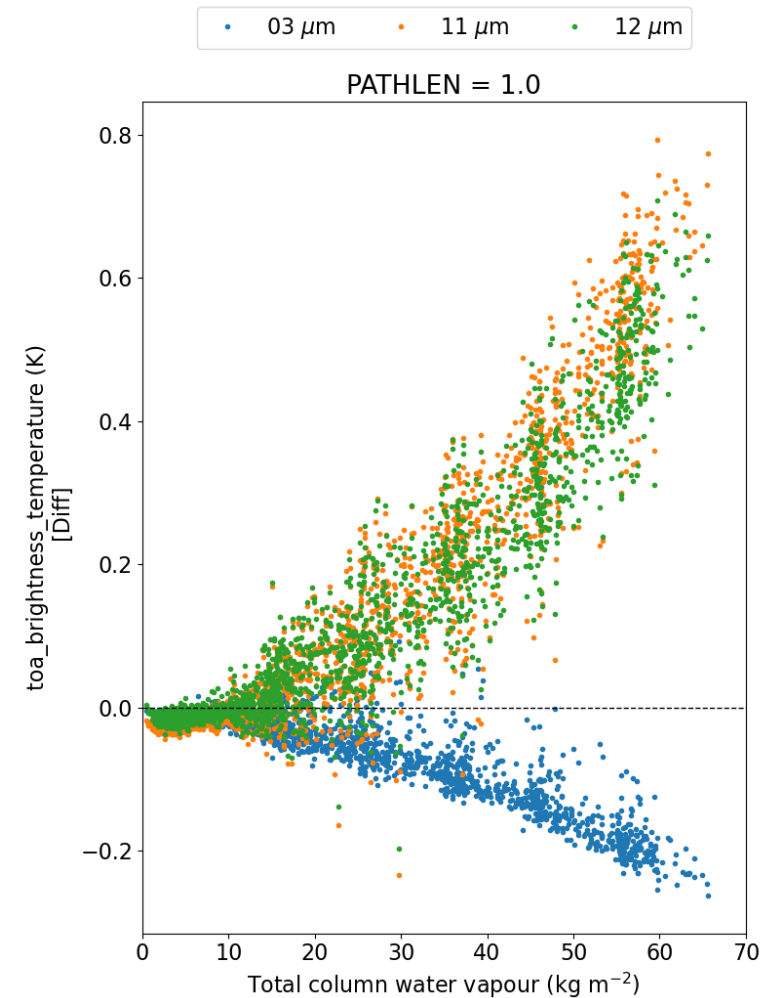
- ATSR / SLSTR retrievals account for changes in trace gas concentrations by generating new coefficients every 4 years
- Monthly trace gas data obtained from NOAA Global Monitoring Laboratory (GML)
- CO<sub>2</sub> CH<sub>4</sub> N<sub>2</sub>O CFC-11 CFC-12



- Coefficients are generated from radiative transfer simulations
- Requires accurate RTM – use line-by-line code LBLRTM
- Two versions supported:
  - LBLRTM 12.2\_cci – SST CCI used a modified v12.2 to match the WV continuum in earlier ARC work
  - LBLRTM 12.17 – current release

Right: LBLRTM 12.17 – LBLRTM12.2\_cci

- 11/12 microns shows differences over 0.5 K at higher water vapour. Due to changes in WV continuum.



Data:  
(1) ARC-coeff/data/bts/lauren/ARCBTS-ESACCI-SLSTRA-2020-LBLRTM-v12.17\_linux\_intel\_dbl.nc  
(2) ARCBTS-ESACCI-SLSTRA-2020-LBLRTM-v12.2a\_linux\_intel\_dbl.nc

# CGT: Line-by-line radiative transfer



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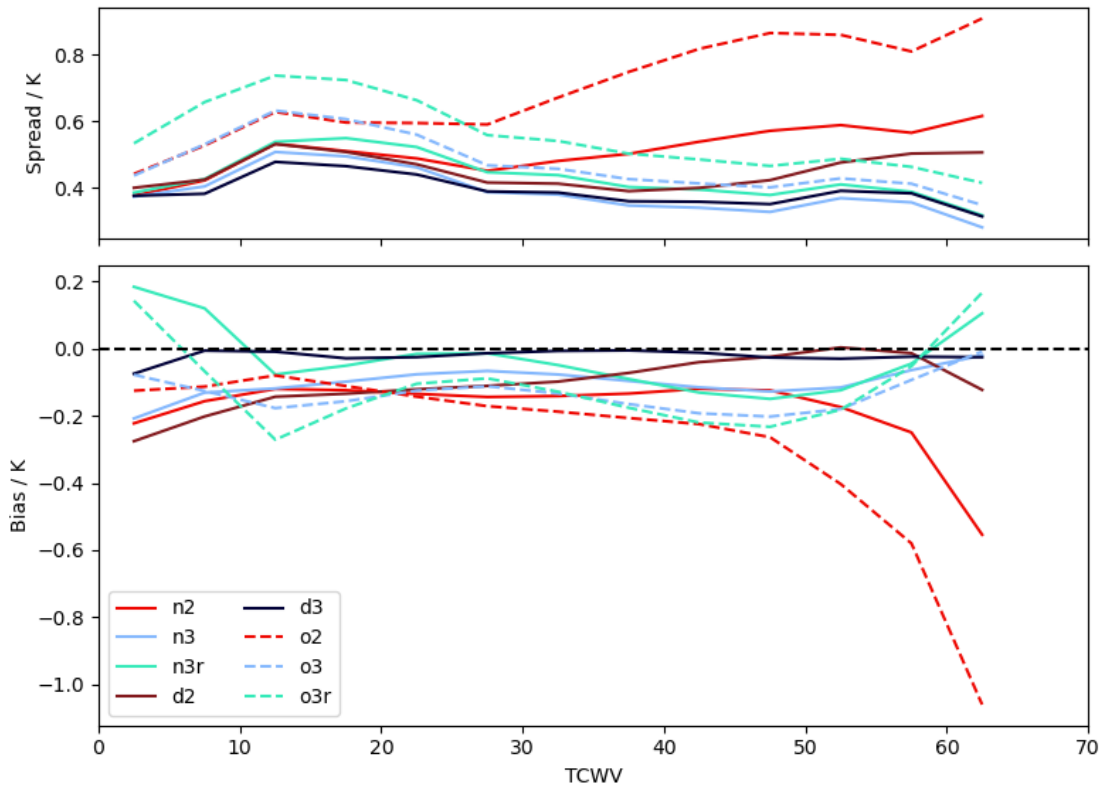


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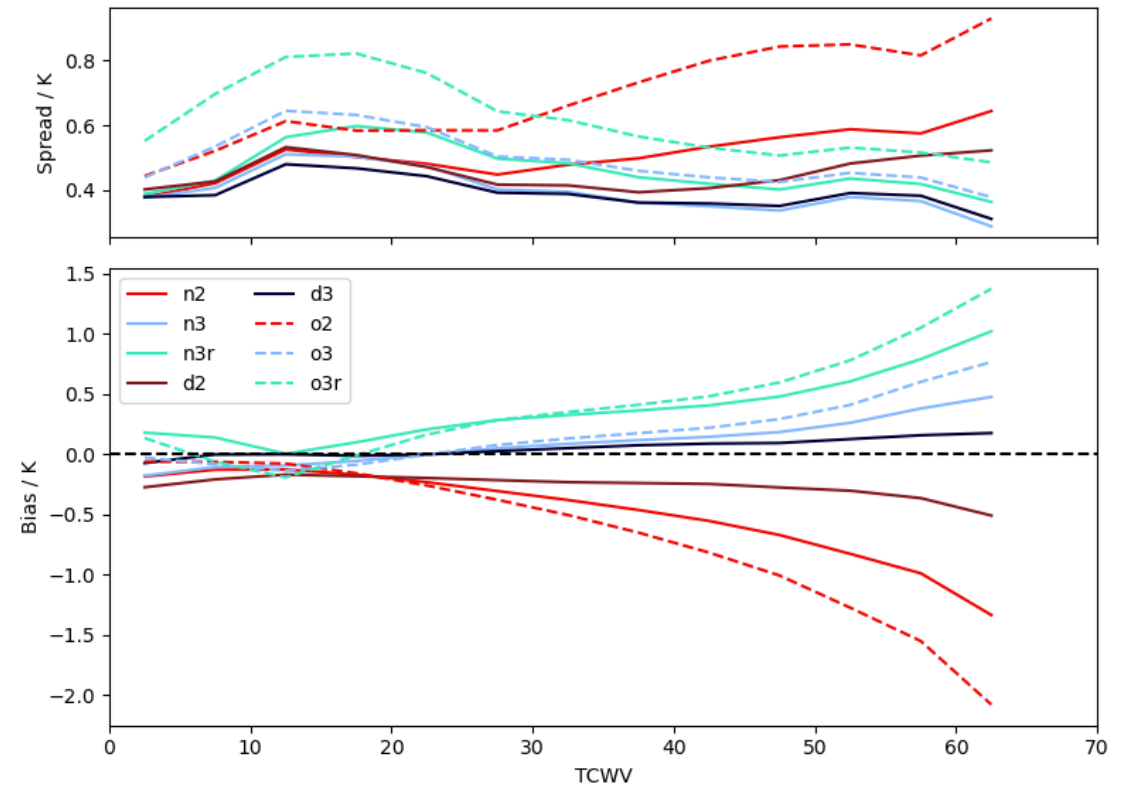


- LBLRTM 12.17 increases spread between retrievals, increases bias in D3 retrieval
- LBLRTM 12.2a is producing better (unadjusted) coefficients

## v12.2\_cci

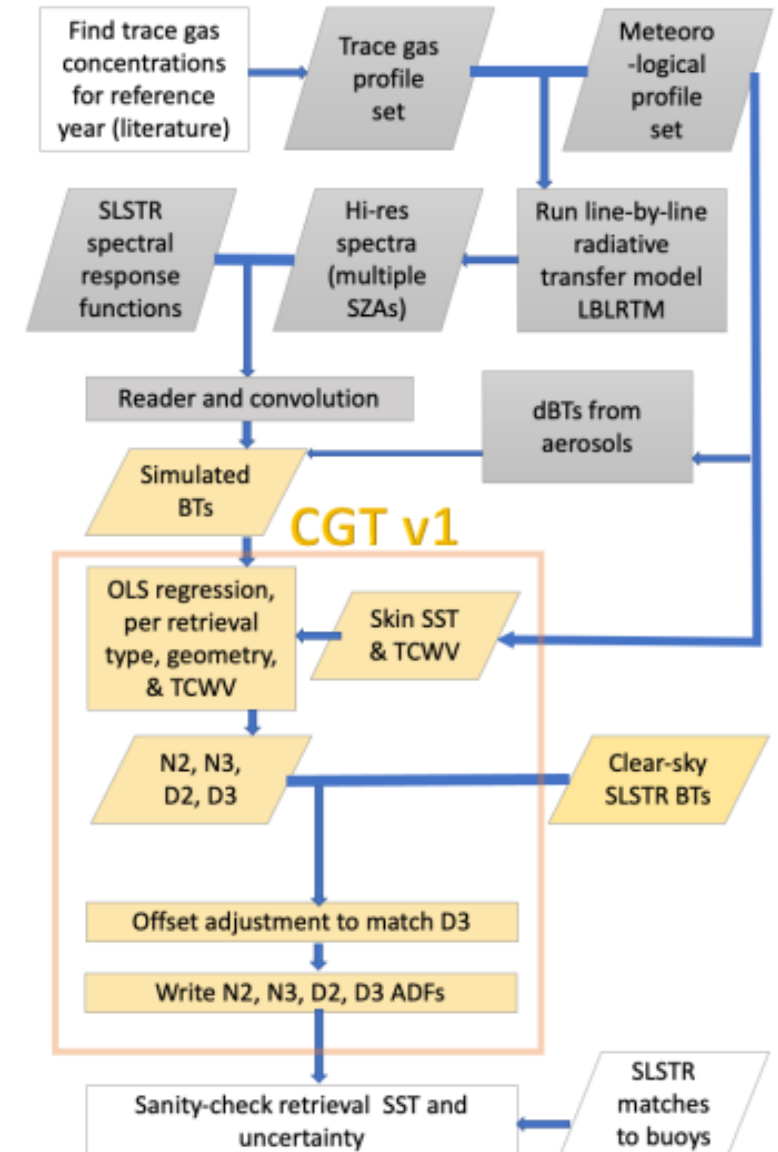


## v12.17



- Accurate line-by-line calculations are clear-sky only. No scattering
- Need to include aerosol impacts for:
  - Stratospheric aerosol from major volcanic eruptions
  - Tropospheric for marine aerosol etc.
- Aerosol delta-BTs calculated using RTTOV:
  - Wrapper provided to run RTTOV and
  - $\text{Aerosol delta-BT} = \text{RTTOV}(\text{aerosol}) - \text{RTTOV}(\text{aerosol free})$
- Generate coefficients from:
  - $\text{BT} = \text{LBLRTM}(\text{aerosol free}) + \text{Aerosol delta-BT}$

- CGT inputs:
  - Reference profile set
  - Trace gas concentrations
  - Instrument spectral response functions (SRFs)
- CGT includes steps for all RTM (LBLRTM, RTTOV), spectral convolution, and coefficient generation
- Output: retrieval coefficients for requested sensor
  - Easy generation of coefficients for new sensors
- Future work:
  - Compare coefficients from different RTM configurations
  - Investigate assumptions in profiles dataset / aerosol simulations



- Coefficient Generation Tool v2
  - End-to-end generation of new coefficients from profile set and SRFs
- Sci4MaST Prototype Processor
  - Updated to include all developments from SST CCI CDR v3
  - Support for RTTOV 13
  - New PDF lookup tables based on 9 years of SLSTR-A Level 1b