

Extension of the Complete Data Fusion algorithm to two-dimensional products





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INTRODUCTION

The CDF has been applied for at least 10 years to vertical profiles or scalar products from both simulated and real measurements (one-dimensional analysis, 1D-CDF). During these years the method has been developed and improved to extend its application to an increasingly large number of atmospheric products.

In this study, the CDF algorithm, used so far only for 1D analysis, has been extended to twodimensional products (2D-CDF). We applied the 2D-CDF to combine simulated ozone data of the Infrared Atmospheric Sounding Interferometer New generation (IASI-NG), a nadir looking sensor, with the Changing-Atmosphere Infrared Tomography (CAIRT), a limb sounder. CAIRT mission is one of the two candidates for ESA's Earth Explorer 11.

We will show results obtained with the rigorous approach of 2D complete data fusion for realistic simulations of CAIRT and IASI-NG.

THE CDF METHOD

The <u>Complete Data Fusion</u> (CDF) [1] is an a-posteriori algorithm to combine independent measurements of the same profile from different instruments into a single estimate for a comprehensive and concise description of the atmospheric state.

The CDF solution \mathbf{x}_{f} for the considered profiles $\hat{\mathbf{x}}_{i}$ (*i*=1,2,..,*N*) is given by:

$$\mathbf{x}_{f} = \left(\sum_{i=1}^{N} \mathbf{A}_{i}^{T} \mathbf{S}_{i}^{-1} \mathbf{A}_{i} + \mathbf{S}_{a}^{-1}\right)^{-1} \left(\sum_{i=1}^{N} \mathbf{A}_{i}^{T} \mathbf{S}_{i}^{-1} \boldsymbol{\alpha}_{i} + \mathbf{S}_{a}^{-1} \mathbf{x}_{a}\right), \qquad \boldsymbol{\alpha}_{i} \equiv \hat{\mathbf{x}}_{i} - \left(\mathbf{I} - \mathbf{A}_{i}\right) \mathbf{x}_{ai},$$

with the corresponding total error CM and AKM:



 \mathbf{x}_{ai} : a priori profile \mathbf{S}_i : noise covariance matrices (CMs) \mathbf{A}_i : averaging kernel matrices (AKMs). for the *i*-th retrieval;

x_a :a priori profile S_a: CM a priori for data fusion.

2D DATA FUSION of LIMB and NADIR MEASUREMENTS

CAIRT: CAIRT is a limb imager capable of sounding the atmosphere simultaneously from the middle troposphere to the lower thermosphere (5 to 115 km) with a horizontal sampling of 50 km along track, 25 km across track and vertical sampling of 1 km. It measures in the 718-2200 cm-1 spectral range.

In the case of retrieval products that are 2D fields, the retrieved atmospheric parameter is given on a 2D grid, in this case the 2D field can be seen as a set of vertical profiles, each profile located

 $\sum \mathbf{A}_i^T \mathbf{S}_i^{-1} \mathbf{A}_i$

IASI-NG: IASI-NG is a Fourier transform spectrometer with spectral bands from 645 to 2760 cm-1. IASI-NG measurements are organized in about 100 km x 100 km fields of regard each containing an array of 4x4 pixels, with the distance between the centers of two pixels of about 25 km (for central fields of regard). Two consecutive IASI-NG measurements (about 15 s distant) cover the region of the tangent points of the CAIRT measurements.

<u>CAIRT and MetOp-SG are assumed to fly on the same orbit, dephased of about 8 minutes in</u> <u>order to allow the nadir measurements to match the region of the limb tangent points.</u>

at a different value of the coordinate along the line of sight.

The 2D data fusion of CAIRT and IASI-NG has been performed on the CAIRT 2D retrieval grid. On this grid, we combined multiple ozone measurements of CAIRT and four ozone measurements of IASI-NG for each along-track position, according to its expected spatial resolution.

The simulated 2D distributions (2-indices quantity) for CAIRT and IASI-NG were arranged in a vector and the AKMs and CMs (4-indices quantities) have been arranged consequently in matrices.

The 2D data fusion was performed applying the standard CDF formulation to these input vectors and matrices.

<u>Results are presented for the 2D-CDF performance and for the improvement achieved with</u> <u>respect to the 1D-CDF in terms of total errors, degrees of freedom and Shannon information</u> content.

1D CDF

In the 1D case study, we applied the CDF to one CAIRT e one IASI-NG simulated ozone profile. The total error profile of the fused product is superimposed to that of CAIRT and more than 50% smaller than that of IASI-NG from nearly 8 km up to 60 km. In this altitude range, also the AK diagonal profile of CAIRT and fused products show the same values (from 0.3 to 0.75) with a peak around 15 km. IASI-NG profile shows a similar vertical behaviour but with lower values (<0.3). Below 8 km the fused product demonstrates the higher quality.



Total Error





along-track)

2D CDF

In the 2D case study, we simulated a 2D field of 51 CAIRT measurements and 4 IASI-NG measurements of ozone for each along-track (ALT) position, selecting an atmospheric region of 21 ALT (1000 km of horizontal extension), and we applied the CDF as described above. The maps for the 2D fields of the total error and AK diagonal elements, as well as the corresponding profile plots for the central ALT, show how the data fusion is able to enhance the information gain and reduce the total error in the fused product, in the whole altitude







AK diagonal elements

AK





Total error (left) and diagonal elements of the AKM (right) for CAIRT, IASI-NG and the fused product

The Shannon information Content (SIC) and the Degrees Of Freedom (DOF) values are shown on the right and demonstrate the enhanced quality of the fused product.

of the ARM (right) for CAIRT, IAST-NG and the fused		
SIC O ₃	DOF O ₃	
IASI-NG: 23.07 CAIRT: 70.62 FUSED: 75.05	IASI-NG: 5.97 CAIRT: 26.60 FUSED: 27.25	
$\begin{split} \textbf{SIC} &= 0.5 * (\log_2 \textbf{S}_a - \log_2 \textbf{S}_{tot,i}) \\ \textbf{S}_a \text{ and } \textbf{S}_{tot,i} \text{determinants of a priori and retrieved} \\ & \text{profile VMCs} \end{split}$		

Total error (left) and diagonal elements of the AKM (rights)) <math>Total error (left) = 0.00 for 10 for 10

Total error (left) and diagonal elements of the AKM (right) of the **central along track position** for CAIRT, IASI-NG and the fused product.

SIC O3	DOF O3
IASI-NG: 452.41	IASI-NG: 117.82
CAIRT: 642.46	CAIRT: 307.44
FUSED: 949.66	FUSED: 366.49

The SIC and DOFs values demonstrate that in the 2D case study the fused product quality is further enhanced.



Diagonal elements of the AK in the CAIRT 2D retrieval grid for (from the top) IASI-NG, CAIRT and the fused product (ALT: along-track)

1D vs 2D: Synergy Factor

The performances of the synergy can also be evaluated in terms of the synergy factor (SF), a quantifier used to evaluate the synergy of two or more independent measurements. The SF is equal to 1 when the combined measurements are complementary and greater than 1 when a synergy between the two individual data sets really exists. We calculated the error SF (SF_{err}) and the DOF SF (SF_{DOF}) as described below:







Conclusions

The results obtained demonstrate the feasibility of the application of the CDF method to two dimensional products. In particular, we showed that the first application of the CDF-2D method to simulated CAIRT and IASI-NG products provides fused products with enhanced quality in term of errors and spatial resolution with respect to the individual products, in the vertical and horizontal range considered in the analysis.

We also compared the results of the CDF method application to 1D and 2D products. The analysis of the total error and AK diagonal (profiles and maps of 2D fields), of the SIC and DOFs values demonstrates that, in both cases:

- <u>the fused product quality is enhanced with respect to that of the individual products, in terms of</u> <u>total error reduction and information gain.</u>

The analysis of the SF_{err} and SF_{DOF} shows that:

- only the CDF-2D is able to fully exploit the synergy between the measurements of the two

For 1D analysis, it is possible to take advantage of the synergy only below 8 km (SF_{err} and SF_{DOF}>1), in the remaining altitude range only complementarity can be exploited (SF_{err} and SF_{DOF}=1). For the 2D analysis the synergy is fully exploited over the whole altitude range.

sensors through the entire vertical range considered.

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REFERENCES

[1] S. Ceccherini, B. Carli and P. Raspollini, *Equivalence of data fusion and simultaneous retrieval*, Optics Express, **23**, 8476-8488 (2015).

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