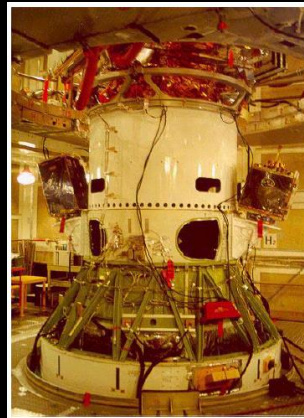
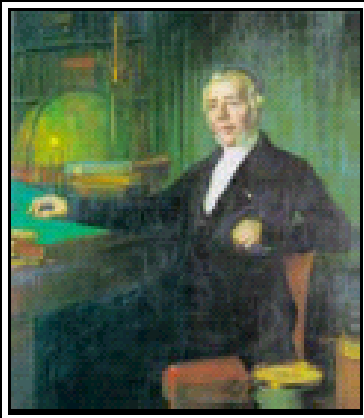


# Swarm, the “ultimate” magnetic mapping mission.

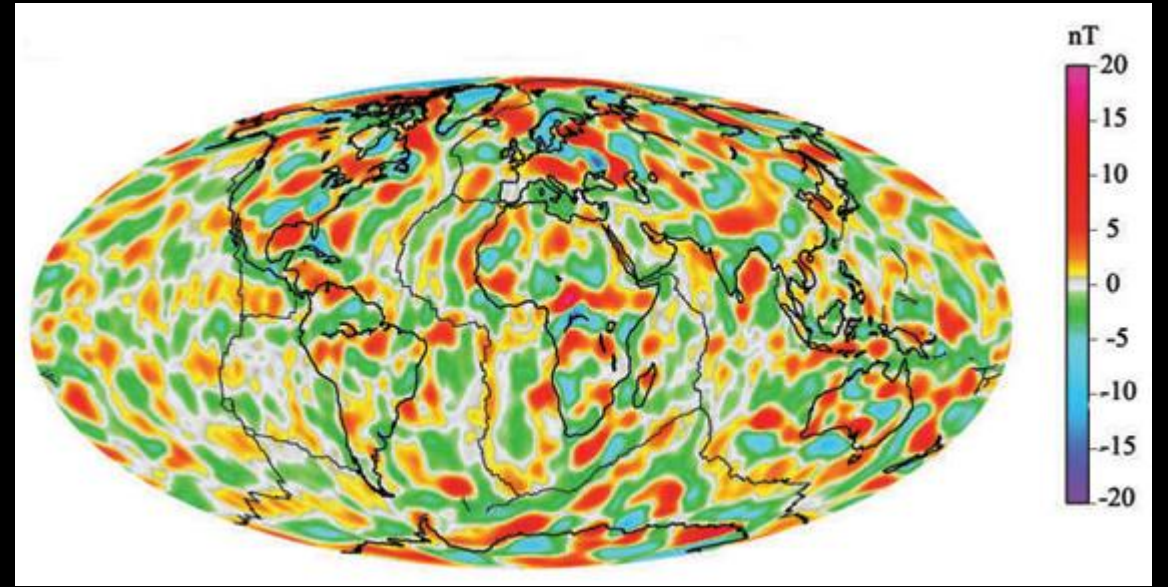
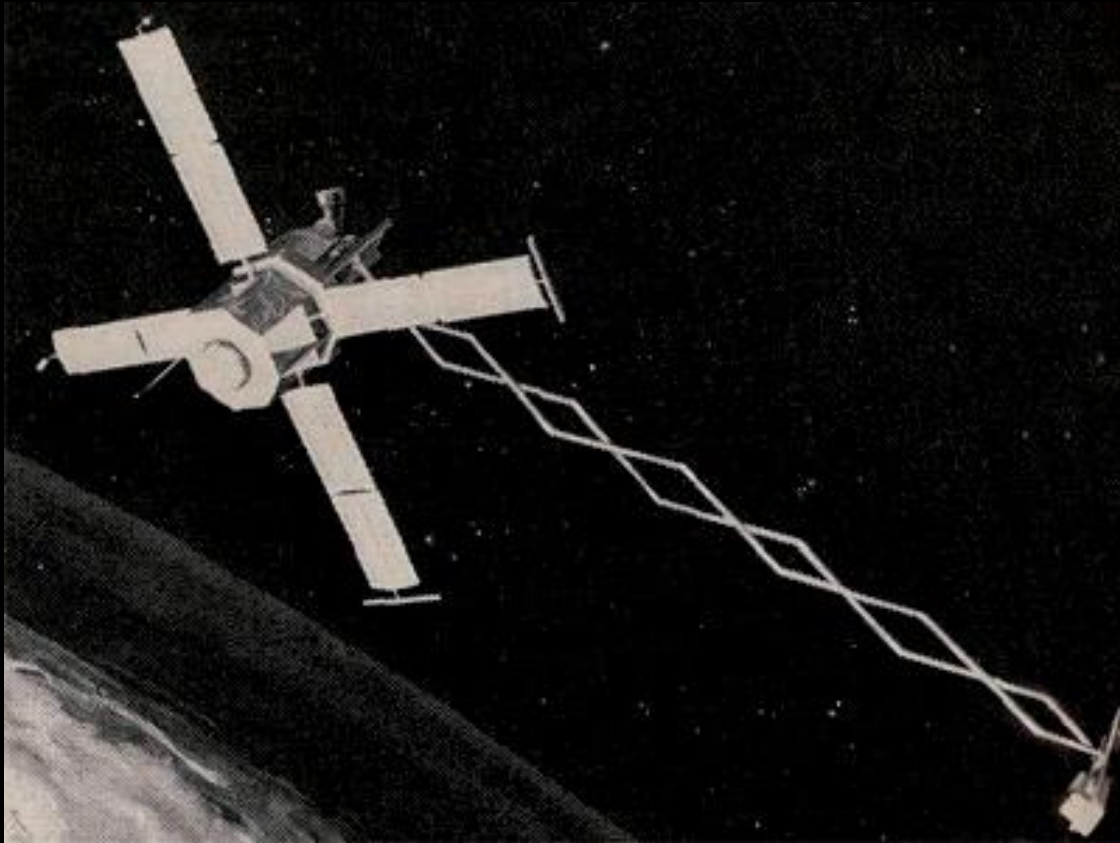
## Swarm 10Y: Past, Present and Future



Professor, John Leif Jørgensen  
DTU Space

10/04/2024

## 1979-1980 Magsat, GSFC, NASA



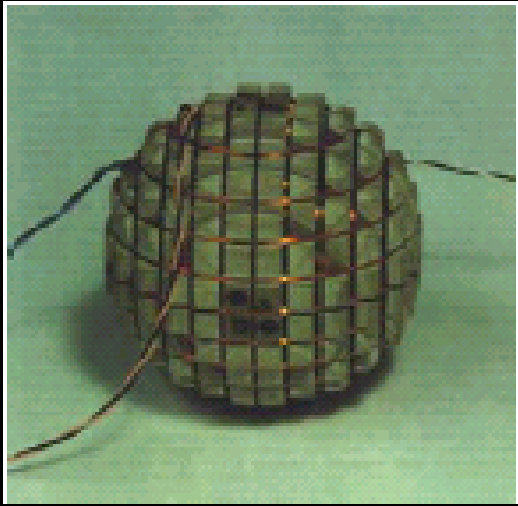
Magnetometer accuracy  $\sim 1\text{nT}$   
Attitude stability  $\sim 10\text{nT}$   
Attitude modelling  $\rightarrow 5\text{nT}$

# 1999-now Ørsted, DTU Space, Research Councils

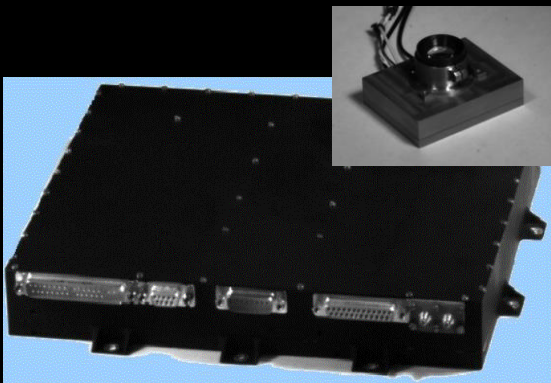


Magnetometer accuracy  $\sim 1\text{nT}$   
Attitude stability  $\sim 1\text{nT} \times 5\text{nT}$   
Attitude coverage 50%

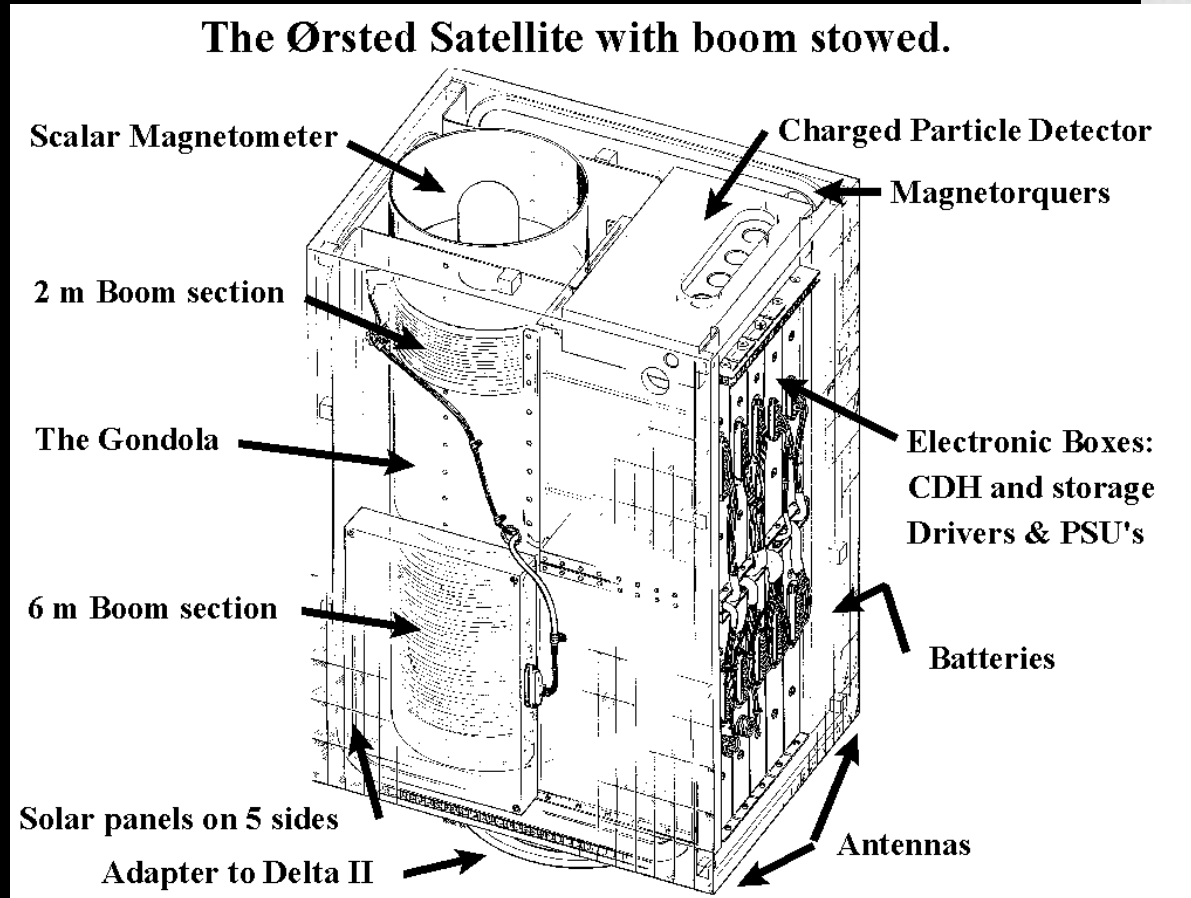
# Ørsted, instrument innovations



CSC Fluxgate magnetometer

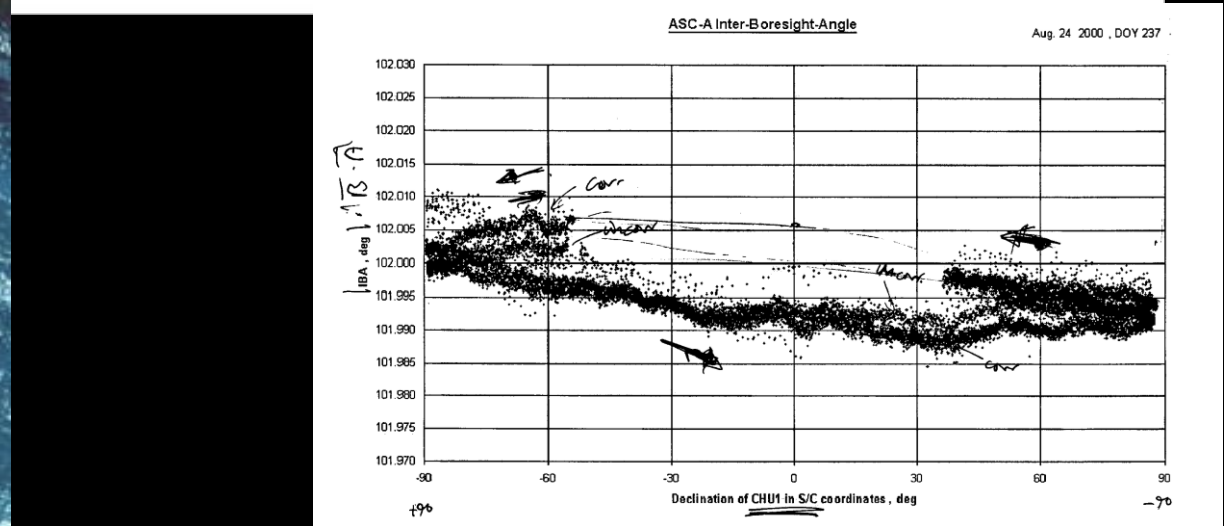
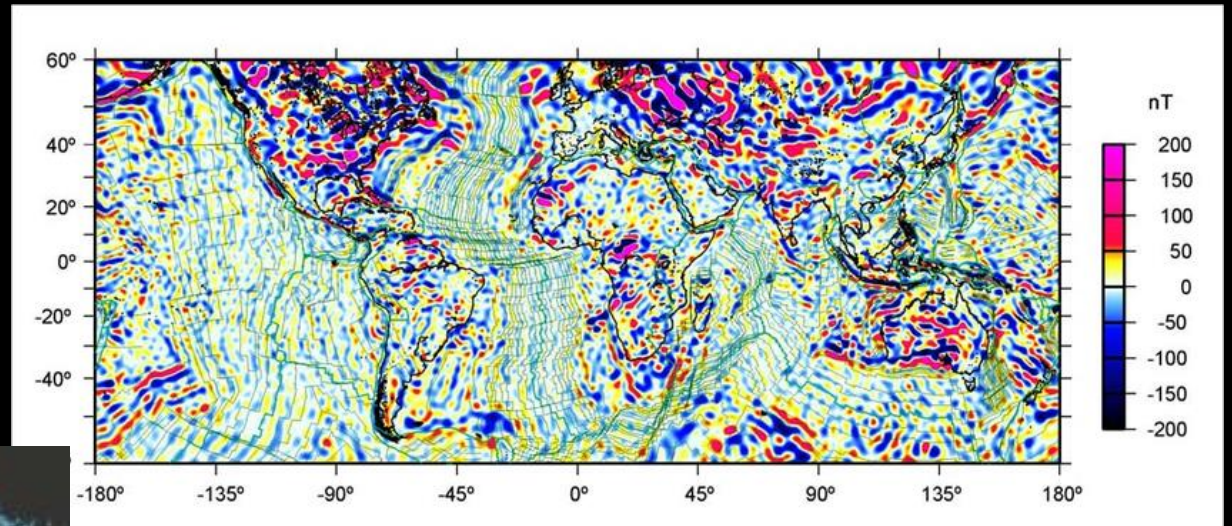


Autonomous Star Tracker



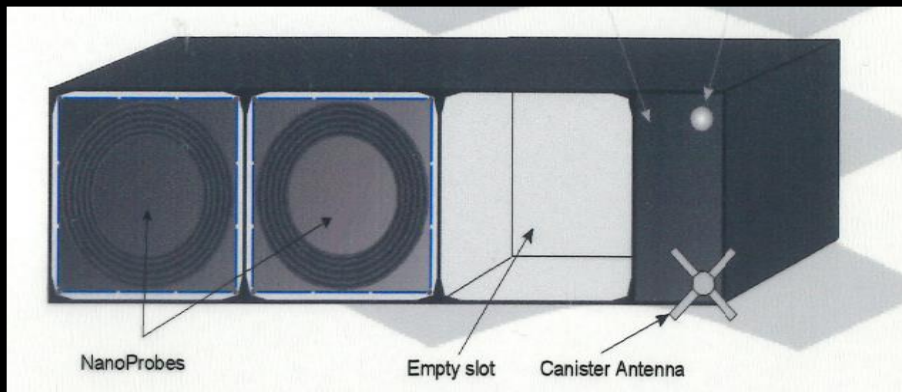
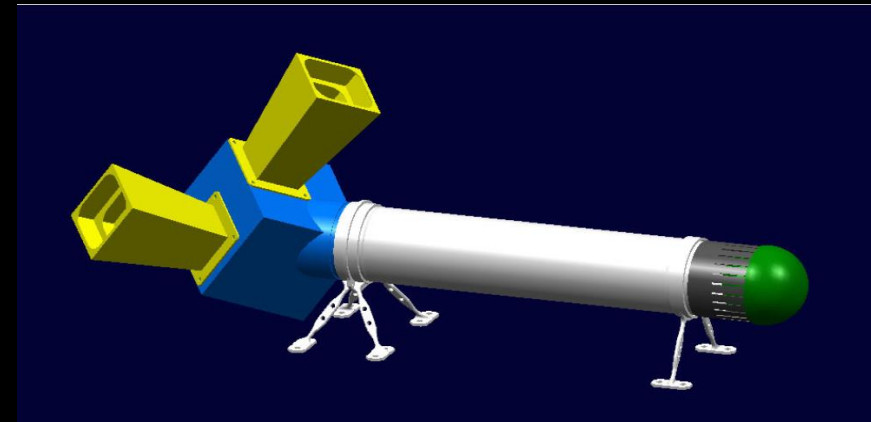
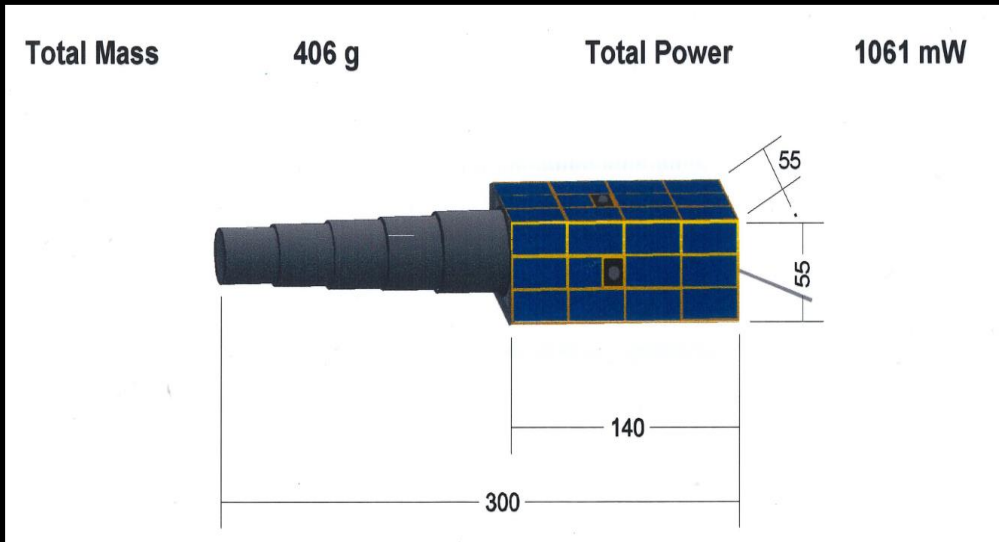


# 2000-2010 CHAMP, GFZ, DLR



Magnetometer accuracy  $\sim 1\text{nT}$   
Attitude stability  $\sim 1\text{nT}$   
Attitude coverage 98%

~2010 NanoProbe, DTU Space  
A swarm of observatories  
Main + 30 Nano'



Magnetometer accuracy  $\sim 5\text{nT}$  &  $1\text{nT}$   
Attitude stability  $\sim 100\text{nT}$  &  $1\text{nT}$   
Attitude coverage 100%  
Full temporal gradiometry locally

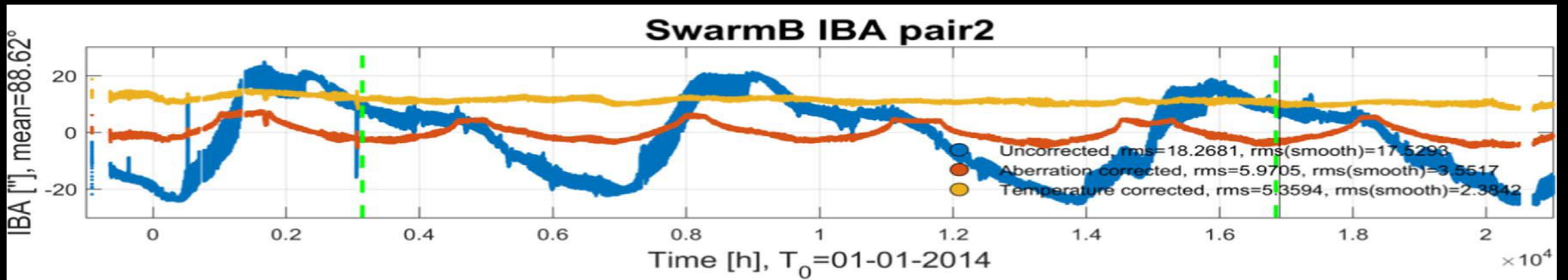
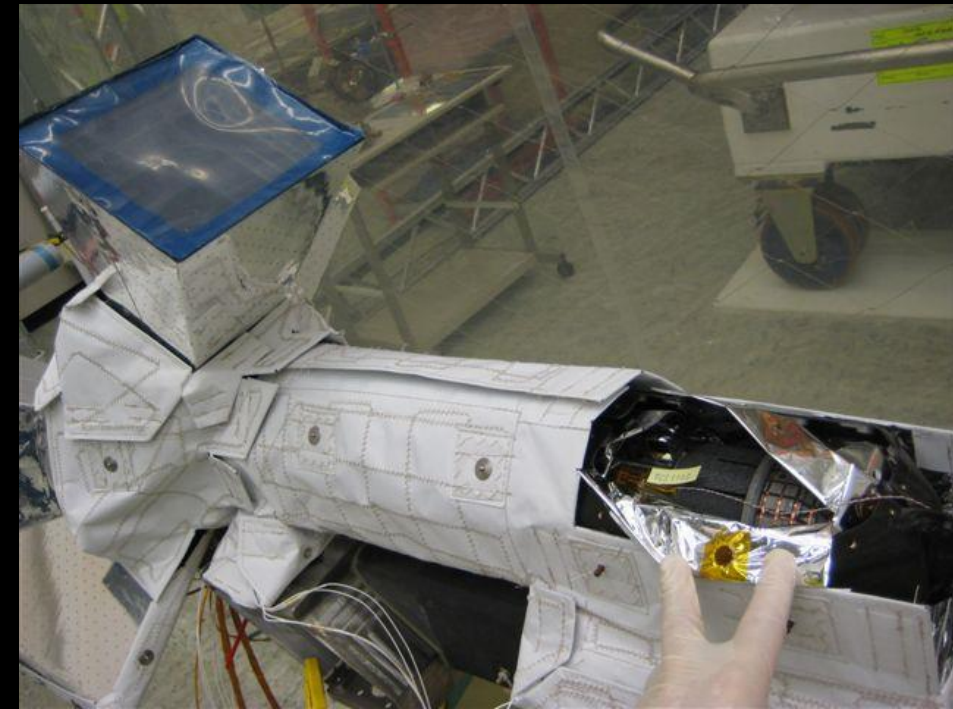
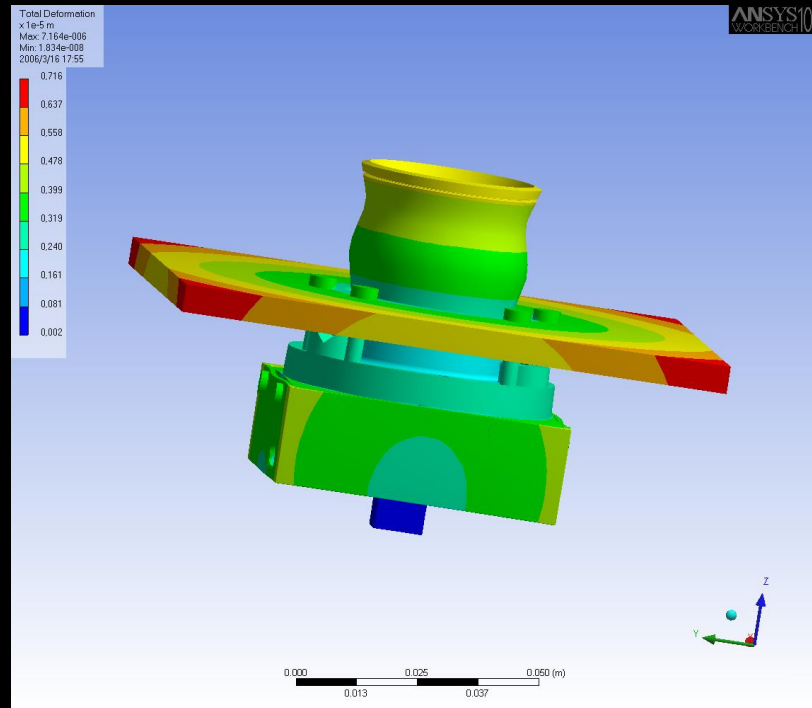
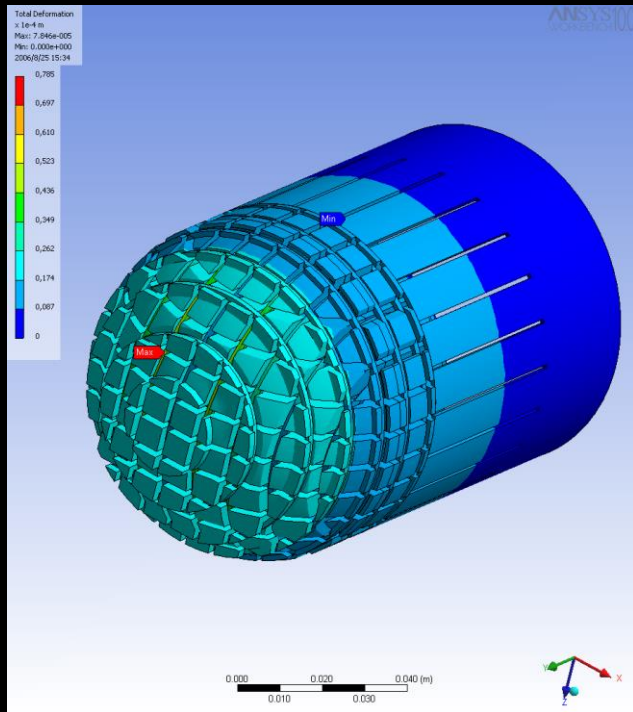
2013-now Swarm, Airbus & DTU Space, ESA



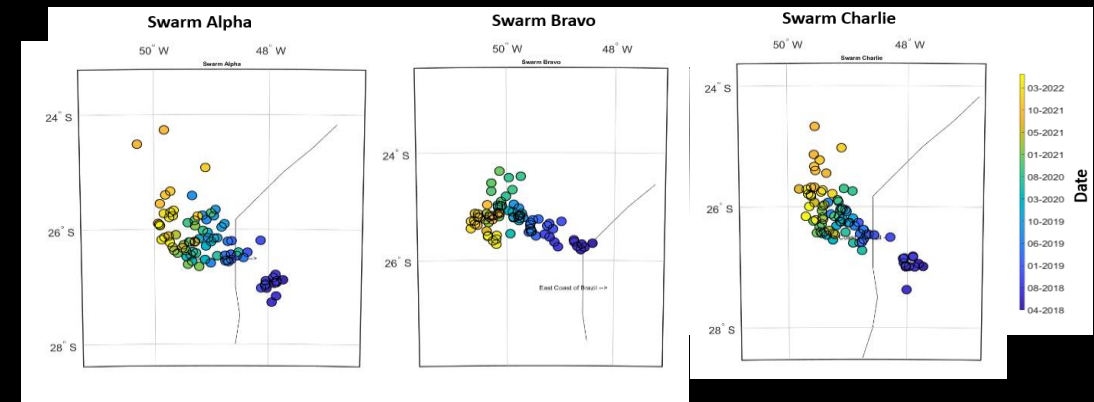
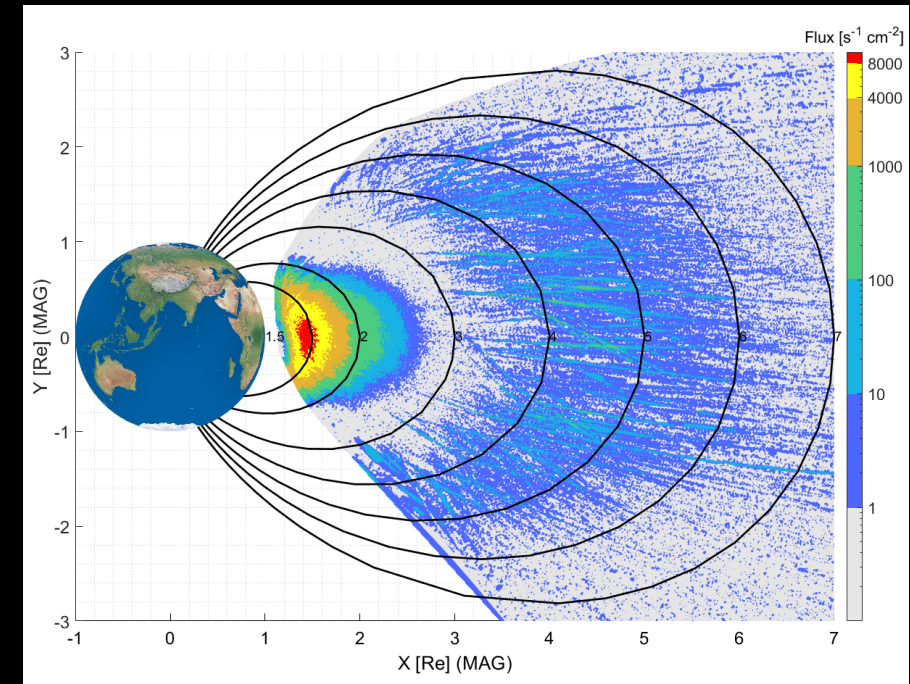
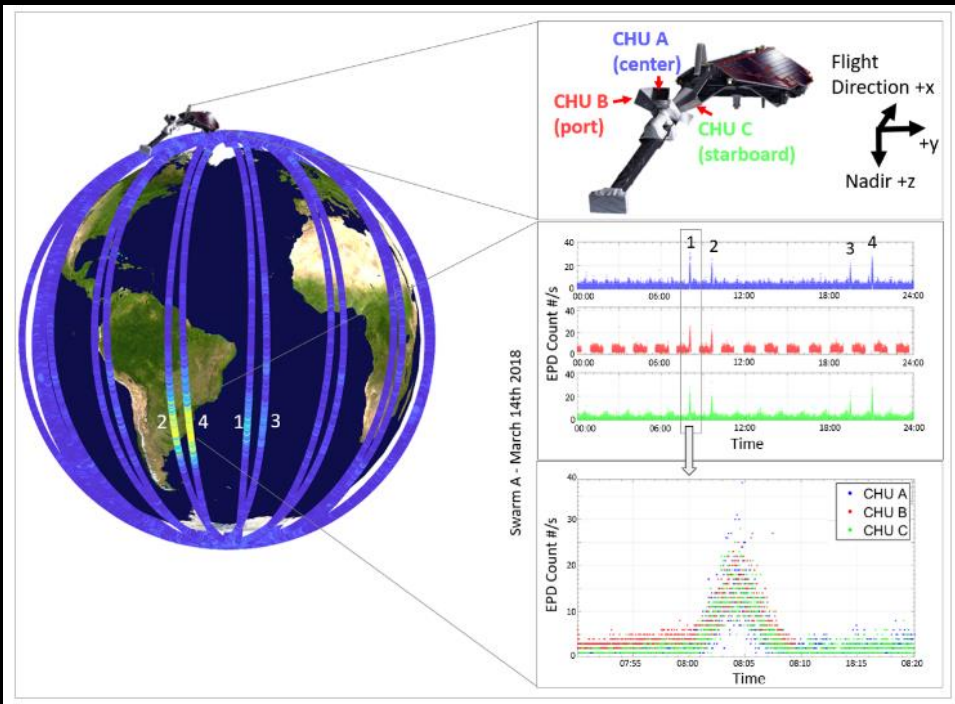
Magnetometer accuracy 1nT  
Attitude stability 3D 1nT  
Attitude coverage 100%  
Full patched gradiometry globally



# Stability, stability, stability



# Swarm is more, much more High Energy Particle Detector

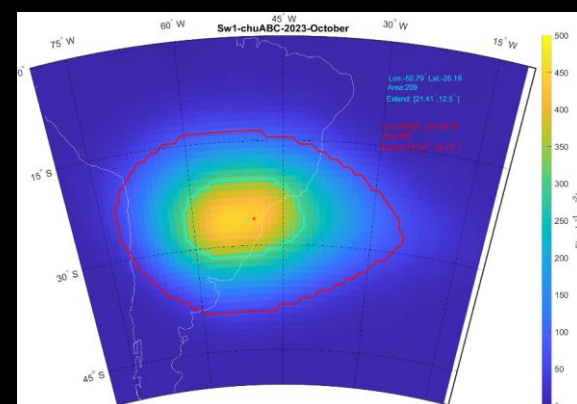
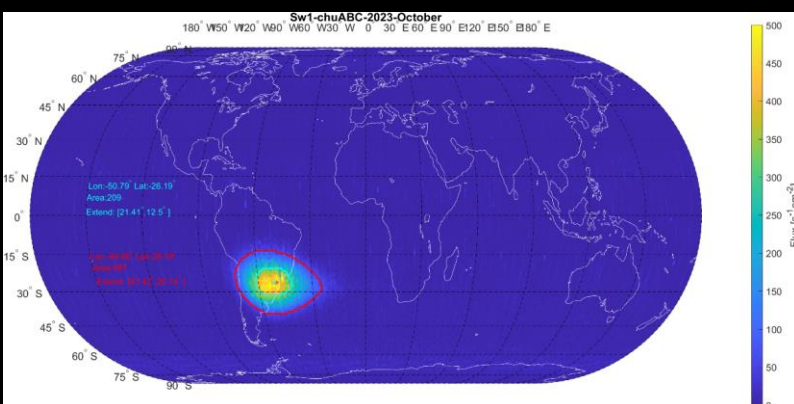


**Swarm Alpha/Charlie**

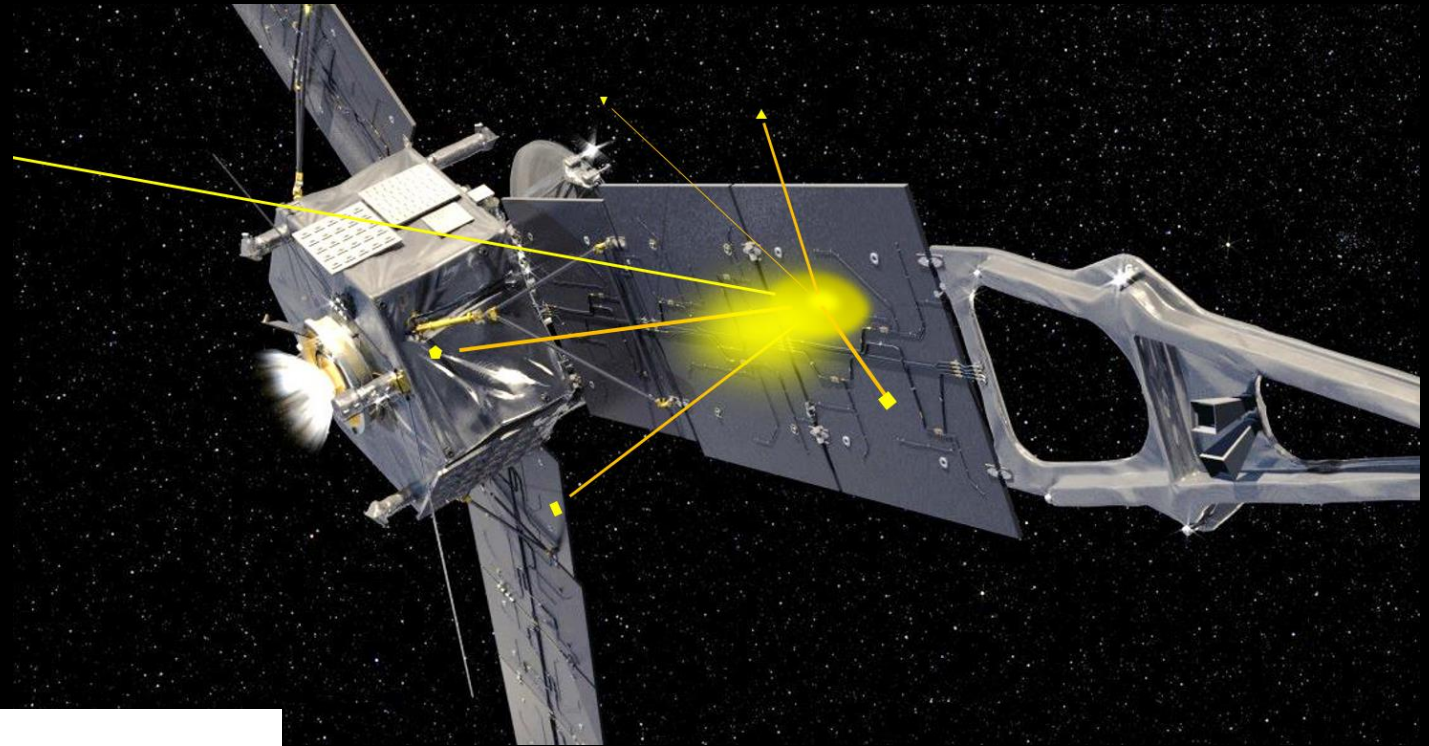
0.28-0.35 deg/year west and 0.21-0.22 deg/year North

**Swarm bravo**

0.325 deg/year west and 0.057 deg/year North



Swarm future is more - more  
Dust Particle Detector



Tails/debris:

Ion  
Dust  
Pebbles

