

# Future Science Facilities and related campaigns relevant to polar science (CRISTALair, CIMRair, Altimetry)

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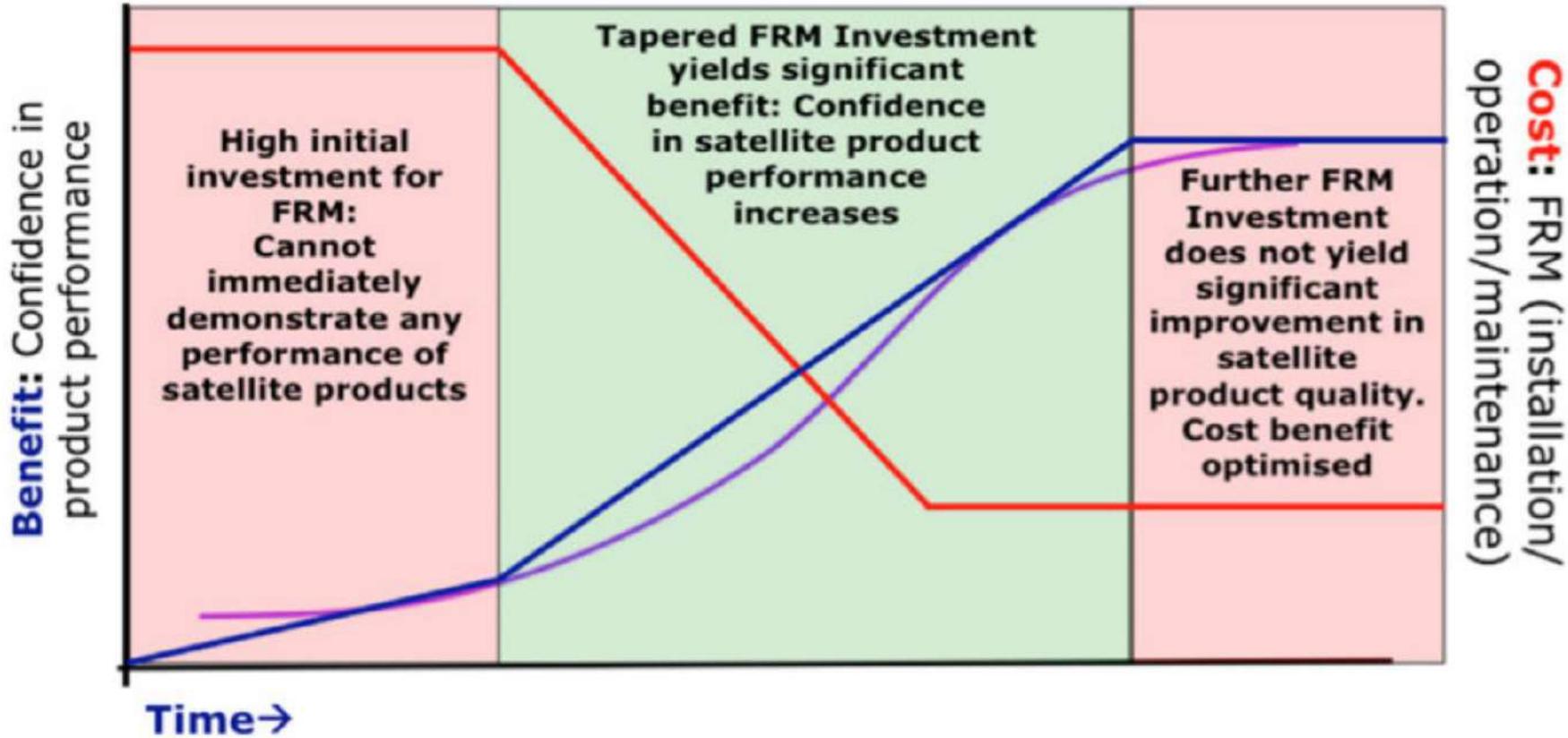
# Copernicus Polar Expansion Missions are **operational** missions but with a strong **innovation** component

They will show detailed

In situ measurements, international refinement, verification through

**Fiducial** reference anchors

ROSE-L



**IMR**  
Copernicus Imaging Microwave Radiometer



**CRISTAL**  
Copernicus Polar Ice and Snow Topography Altimeter

# Fiducial Reference Measurements

Fiducial Reference Measurements (FRM) are

the suite of **independent**  
**Investment for a**  
independent validation

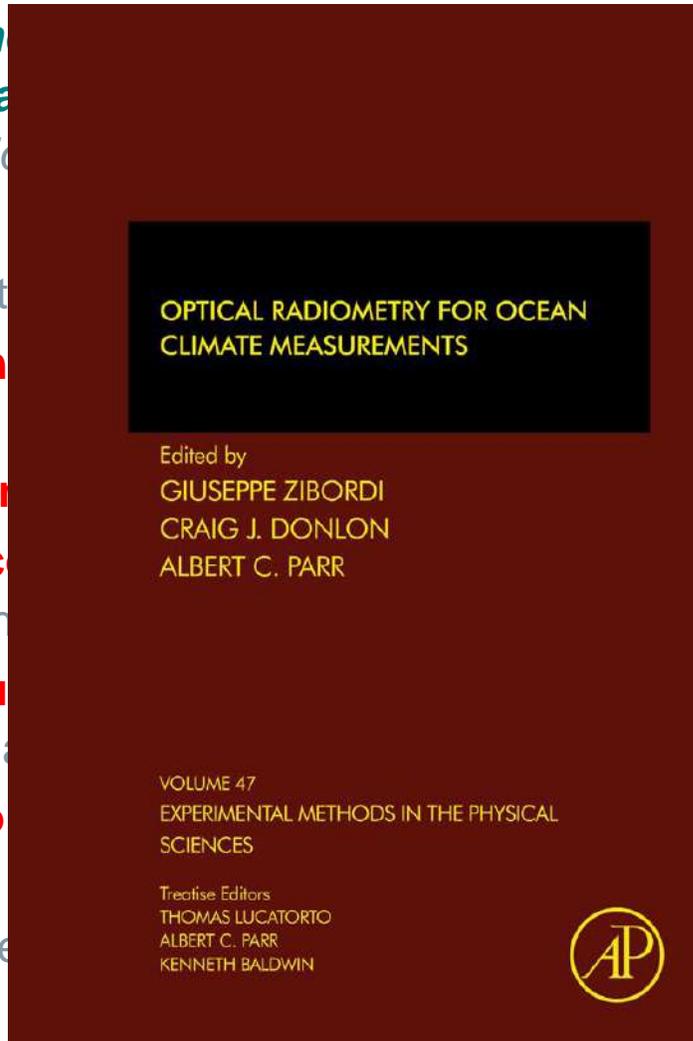
The defining mandate  
Have **documented**  
conditions.

Are **independent**  
**Include an uncertainty**  
traceable when

Are **collected** under  
processing, and

FRM are as close to

FRM are required to  
validation activities



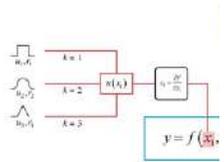
**Return On**  
Investment, in the form of  
validation of the mission.

mission-like  
and maintained,

measurement,  
independent

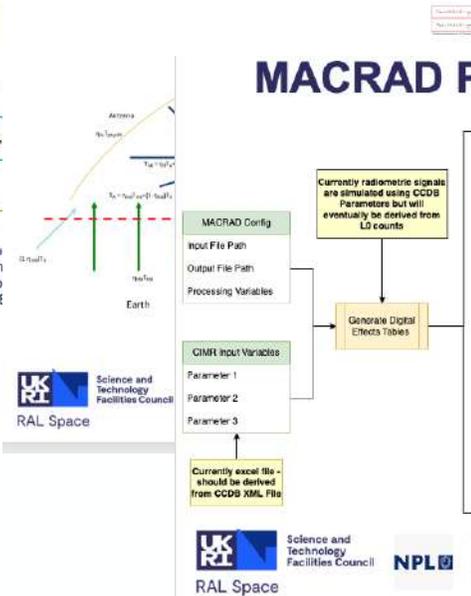
# CIMR Uncertainty Modelling

## Law of Propagation of Uncertainties

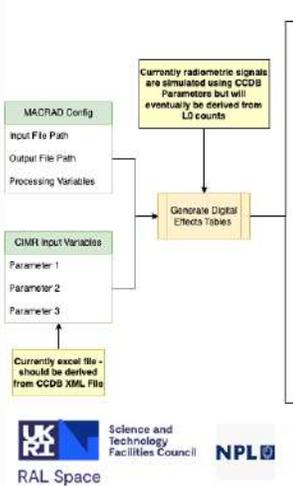


From - Mittaz, J., Merchant, C. J. an Applying principles of metrology to h observations from satellites. Metrolo 1394 doi: <https://doi.org/10.1088/166>

## CIMR L1 Calibration Model



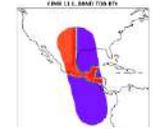
## MACRAD Processing



L1 TOA BTs

Main Room

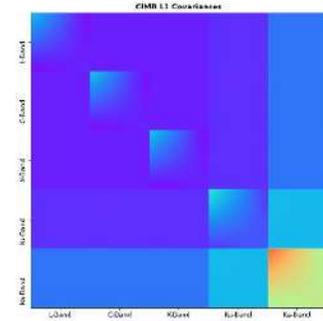
L1 Product



## Outputs from MACRAD L1

Covariance matrices

```
cov_tot = ds.ta.unc["TA"].total_err_cov_matrix()
```



Temperature

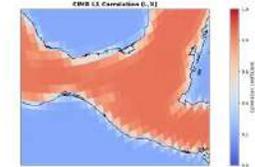
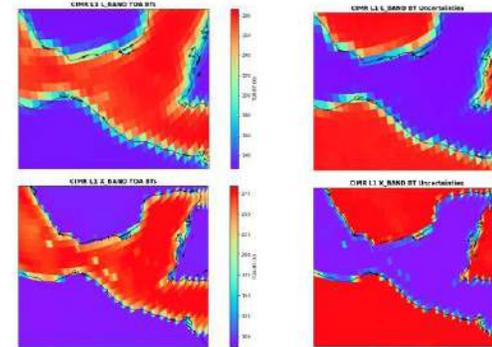
Correlation matrices

```
corr_tot = ds.ta.unc["TA"].total_err_corr_matrix()
```

## Applying to L1 Products

Using output of MACRAD L1 Uncertainty Propagation we can 'map' to per pixel uncertainties

These uncertainties have been included in demo SCEPs products for use by L2 processors.



Correlation coefficients not added to L1 due to different dimensions of band datasets but could be additional dataset

# ESA investments to ensure product quality



## Science Facilities (Airborne Demonstrators – CRISTALair and CIMRair)

Essential for the consolidation of the retrieval algorithms during the implementation Phase, and then for in-flight calibration to complement FRM

## Permanent facilities for calibration

Sizeable investment at the start, but essential for collecting the FRMs that are needed for post-launch validation. This supports the accurate delivery of level 1 and higher-level products, confirming expected performance including processors and any retrieval algorithms

*Fontijn-Tekampel et al, 2015, Goryunov et al, 2020*



# Example: CRISTAL science data products support

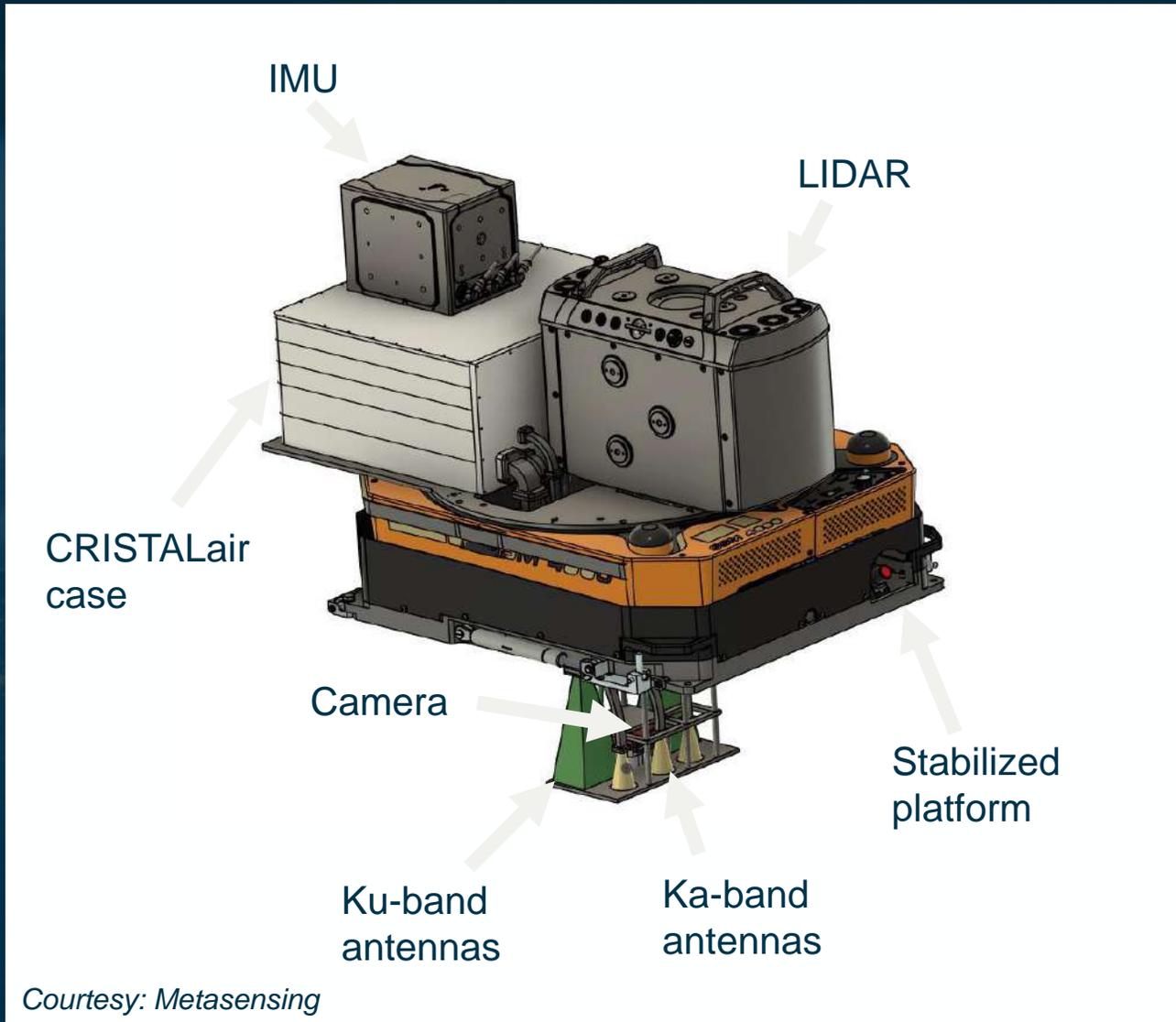




## Interferometric Dual-Frequency Airborne Altimeter Instrument

- Interferometry in both Ku- and Ka-band
- 1 GHz bandwidth (sampling of full bandwidth)
- Range window: 300 m
- Altitude range: 1000 m – 4000 m (AGL)
- Currently optimized for Twin-Otter aircraft
  - We will also get it certified for Basler aircraft
- Included:
  - LIDAR (rented)
  - Colour infrared camera
  - Stabilized platform
  - Inertial Measurement Unit
  - GNSS receiver

Ready early 2025



**Corner Reflectors for CRISTALair**  
(Triangular, Length 0.95 m, RCS: 38.4 dB,  
Elevation: 2 m AGL)

# CRISTALair proposed campaigns summary schedule



Campaign	Objectives	Time / Duration	SSP activities & Mission Obj.s
<b>CRISTALair Functional Flight Campaign in the Arctic (includes a local/ European test ground/flight)</b>	<ul style="list-style-type: none"> <li>- Cal/sync flights</li> <li>- Radiometric / elevation accuracy / slope /point target response and other req verifications</li> <li>- Flights over corner reflectors</li> <li>- Antenna pointing verification</li> <li>- Performance evaluation over altitude</li> <li>- Verification of the CRISTALair Level1 ground processor</li> </ul>	Feb 2025 / 4 days (~20 hours over 4 flights)	SP07, SP08
<b>CRISTALair Functional Campaign add-on in the Arctic (Station Nord)</b>	<ul style="list-style-type: none"> <li>- Collocated snow measurements to validate snow depth</li> <li>- Drone/aircraft snow radar measurements</li> </ul>	Feb 2025	SP03, SP07, SP08
<b>CRISTALair for AWI</b>	Certification of CRISTALair in AWI aircraft	TBD	
<b>CRISTAL first Science Campaign in the Arctic (or Svalbard)</b>	<ul style="list-style-type: none"> <li>- Snow, sea/land ice measurements to develop &amp; consolidate snow depth measurements</li> <li>- Characterize radar return at both frequencies</li> <li>- Validate snow retrievals</li> </ul>	TBD (2025)	SP06, SP07, SP08
<b>The joint Copernicus Expansion Missions CIMR, CRISTAL and ROSE-L sea ice experiment (CEMSIE)</b>	Collocated measurements of CRISTALair, CIMRair, snow radar, radiometer (airborne) with ground measurements	Spring 2026	SP06, SP07, SP08
<b>CRISTAL Science Campaign in Antarctica</b>	Additional measurements for developing retrieval methods based on Antarctica snow conditions which differ considerably from Arctic snow	Dec 2026	SP01, SP02, SP06 SP08



## First Arctic Campaign

- Objective 1: develop and consolidate snow depth measurement retrievals
- Objective 2: verify the across-track collocation of the radar return at both frequencies
- Expected outcome: Collect sufficient airborne Ka/Ku/La + snow radar and in situ data to validate the snow retrievals
- Study how snow depth measurements vary with the spatial scale observed and snow conditions
- Place TBD <math><81.5^\circ</math> (Svalbard)? Time possibly 2025, airborne+drones+in situ

## CEMSIE



- CIMR, CRISTAL and ROSE-L Sea Ice Experiment, proposed by John Yackel (Univ. Calgary) and Rasmus Tonboe (DTU)
- To reduce uncertainties and improve retrievals for Sea Ice concentration/thickness, Snow Depth
- Cambridge Bay (First-Year Ice), Spring 2026
- Extensive set of in-situ instrumentation
- Excellent opportunity for NASA/JPL participation

# CIMRair - High Level Requirements

- Airborne Radiometer with 5 frequency bands (L-, C-, X-, K-, Ka-band)
- Acquire measurements with two channels in vertical linear (V) and horizontal linear (H) polarisation
- Measuring the full stokes vector for each frequency band
- Side-looking configuration with one fixed beam per band with an OZA  $\sim 55$  deg
- Maximum operational altitude  $> 3000$  m above sea level
- Reference altitude for instrument performance is 1000 m above ground
- Fixed footprint measurement from all aspect angles by using circular flight pattern
- The development activity includes
  - Certification of the instrument for the baseline aircraft
  - One initial Functional Flight Campaign in the arctic environment to demonstrate the function and performance of the instrument



HUTRAD 2.0 installed on Norlandair Twin-Otter

Greenland

# Example Flight plan for CIMR Air



PROGRAMME OF THE EUROPEAN UNION



Credit: European Union, Copernicus Sentinel-2 Imagery - Processed by @DEFIS\_EU.

Slide 14



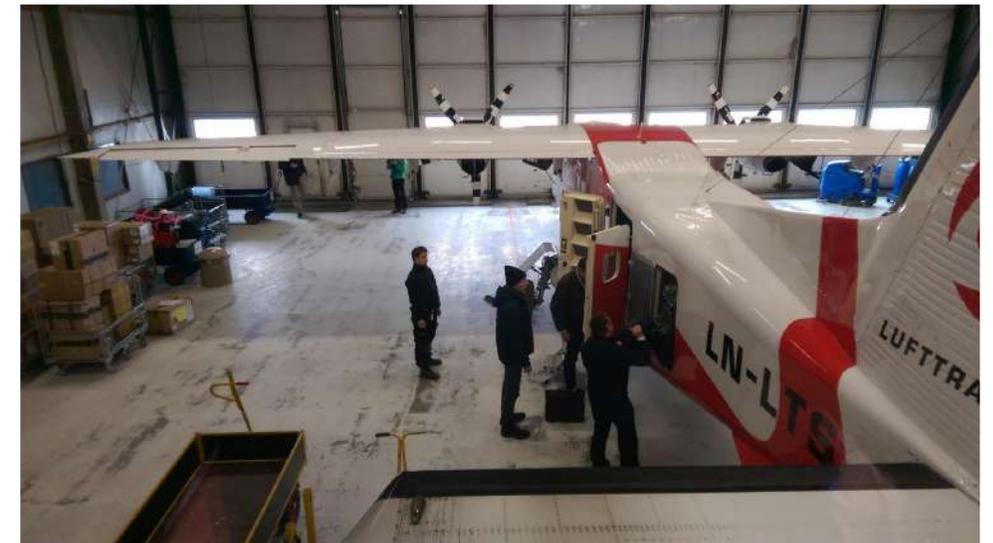
→ THE EUROPEAN SPACE AGENCY

# Aircraft Selection

- The Norlandair Twin-Otter has been confirmed as the baseline aircraft
- The custom door cover with antenna feed through and radomes will be designed and flight certified for this specific aircraft
- The compatibility with the DO228 as secondary aircraft will be assessed and should maintained during the design
- However, this compatibility shall not compromise the instrument performance

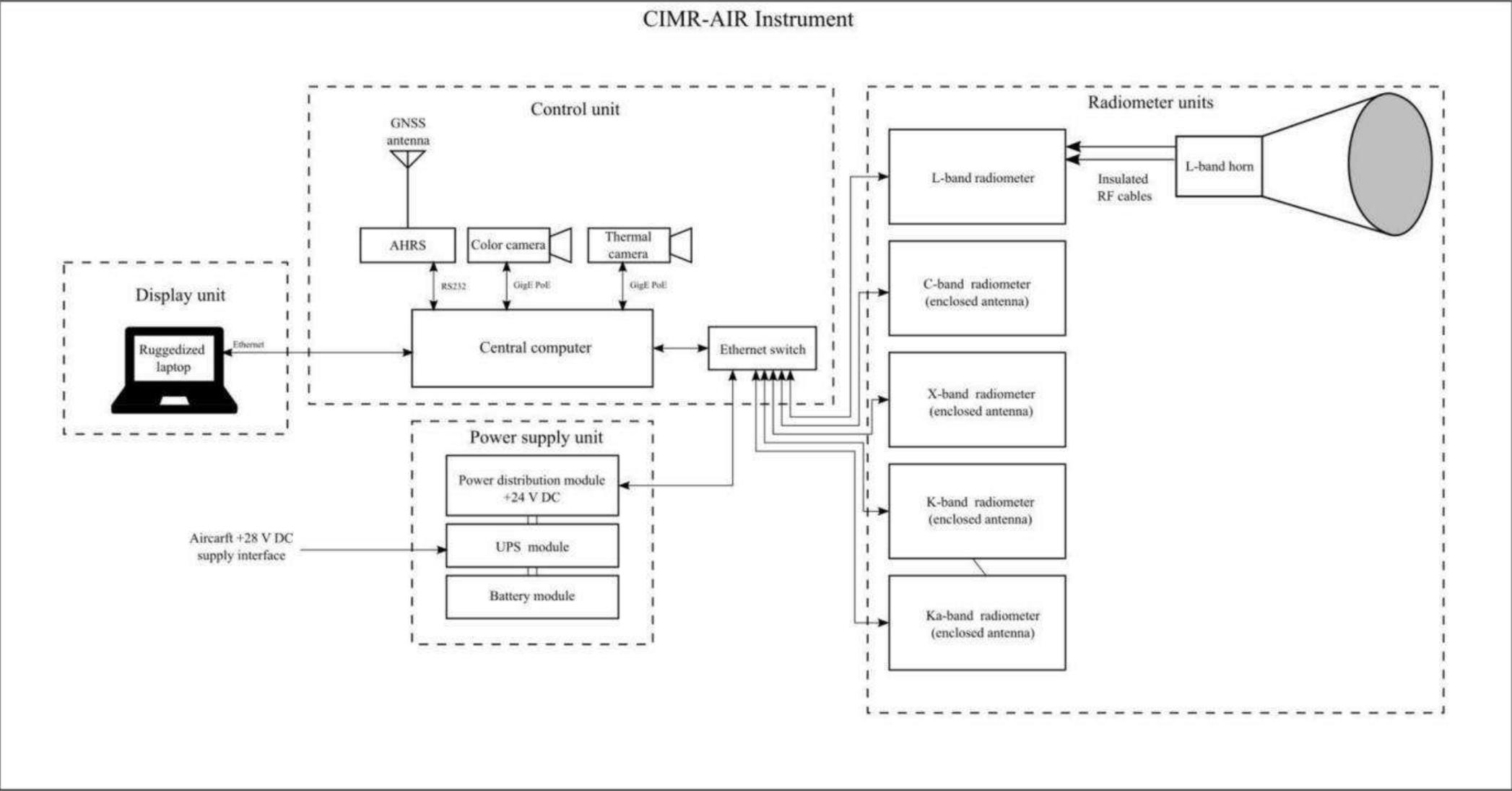


*Confirmed Baseline: Norlandair Twin-Otter*



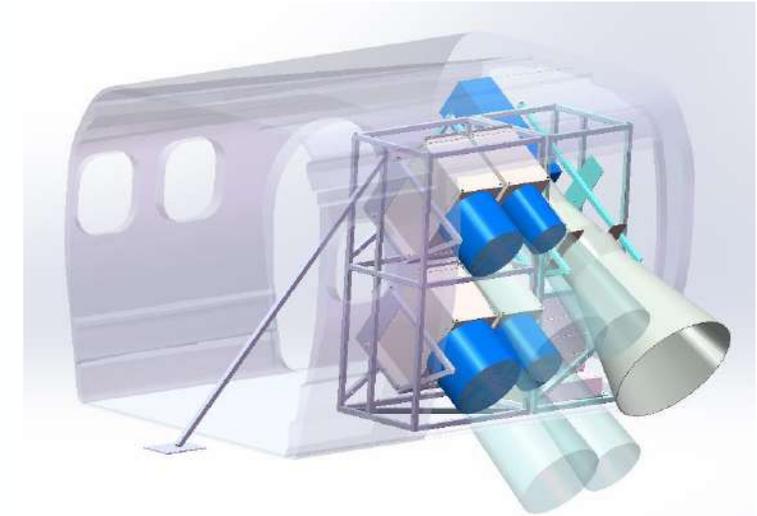
*Lufthansa Do-228 in Svalbard*

# CIMR-AIR Instrument Overview

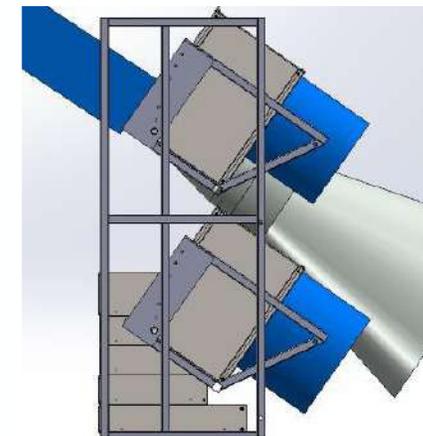


# Instrument configuration

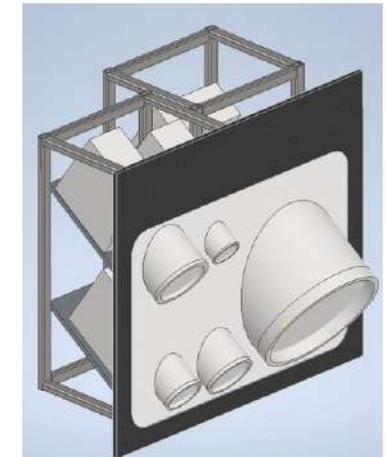
- The radiometer will be mounted behind the cargo door opening
- The door will be closed with a cover including radomes
- The L-band antenna may cover directly the horn opening
- The odd-nadir angle can be adjusted in steps of 5 degree
- This enables antenna angle adjustment for circular flights for multi aspect angle measurements
- The pivot point as close to the radome as possible
- Horn antennas are considered as antenna baseline



Visualisation of instrument inside the aircraft



Radiometer carrier



Door cover radome

- Selected CIRM-AIR cameras
  - Baumer VCXG-15C.I.XT (colour)
  - Infratec HDx 675 (thermal)
- The field of view can be adapted by changing the (C-Mount) optics
- Recorded frame rate specified < 10 fps

Parameter	Value
Camera type	<b>Baumer VCXG-15C.I.XT (optical)</b>
Image size	1440 x 1080
8 mm focal length - field of view	33° x 25°
Projected pixel size	1.7 m
4 mm focal length - field of view	63.8° x 50.1°
Projected pixel size	3.4 m
Dimension	40 x 40 x 50.8 mm
Mass	137 g



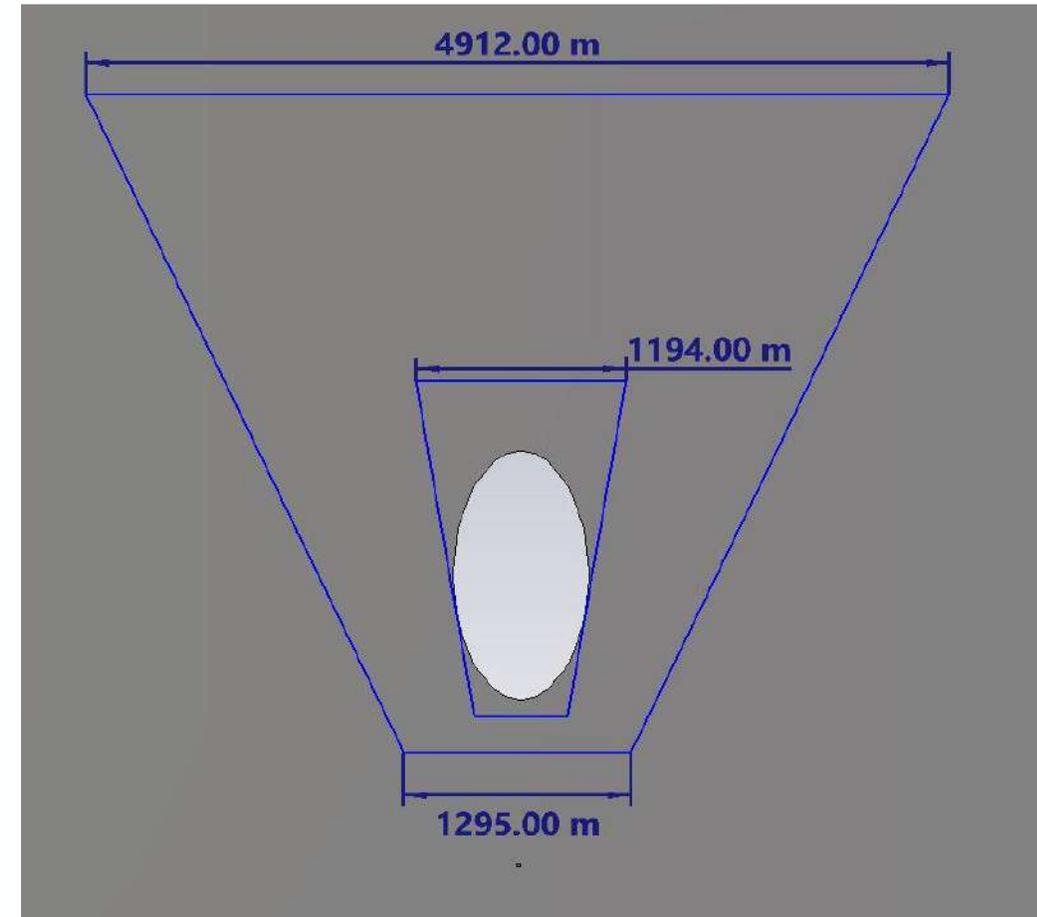
Baumer VCXG-15C.I.XT



Infratec HDx 675

Parameter	Value
Camera type	<b>Infratec HDx 675 (thermal)</b>
Spectral range	7.5 ... 14 μm
Thermal resolution	40 mK
Image size	640 x 480
20 mm focal length - field of view	30.0° x 23.1°
Projected pixel size	4.9 m
10 mm focal length - field of view	57.1° x 44.4°
Projected pixel size	7.4 m
Dimension	90 x 94 x 190 mm
Mass	1150 g

- Comparison of cameras field of view with L-band antenna footprint (~24 deg)
- The image should not only cover the -3dB contour but rather the main beam (~ factor 2.5)
- This ensures that all significant contributors are covered
- This leads to reduced resolution and less detailed images



Thermal camera - field of view projections for 10mm (outer) and 20mm (inner) focal lengths.

# Instrument Performance Figures

- Radiometer Channels are largely aligned with CIMR**

	L-band	C-band	X-band	K-band	Ka-band
Centre Frequency [GHz]	1.4135	6.925	10.65	18.7	36.5
Bandwidth [MHz]	50	400	100	200	300
Band [MHz]	1.4-1.45	6.675-7.075	10.6-10.7	18.6-18.8	36.35-36.65

- Footprint size at reference altitude**

Reference Altitude [m]	1000	1000	1000	1000	1000
Incidence angle [deg]	55	55	55	55	55
Footprint_size Requirement [m]	< 1000	< 500	< 500	< 200	< 200
Preliminary Footprint size [m]	1170	439	445	213	147

- Total standard uncertainty budget**

Total standard uncertainty requirement [K]	0.5	0.5	0.5	0.6	0.8
NEDT [K]	0.04	0.04	0.08	0.11	0.09
Stability requirement [K]	0.2	0.15	0.1	0.2	0.2
Remaining Error budget for calibration errors [K]	0.46	0.48	0.48	0.56	0.77



# 30 Years of Progress in Radar Altimetry Symposium

2-7 September 2024 | Montpellier, France

## The ESA Permanent Facility for Altimetry Calibration in Crete

*Stelios Mertikas<sup>1</sup>, Craig Donlon<sup>2</sup>, Dimitrios Piretzidis<sup>3</sup>, Costas Kokolakis<sup>3</sup>, Fabrice Collard<sup>8</sup>, Robert Cullen<sup>2</sup>, Pierre Femenias<sup>4</sup>, Marco Fornari<sup>2</sup>, Jerome Bouffard<sup>4</sup>, Alessandro Di Bella<sup>4</sup>, Francois Boy<sup>5</sup>, Xenofon Frantzis<sup>1</sup>, Achilles Tripolitsiotis<sup>3</sup>, Mingsen Lin<sup>6</sup>, Lei Yang<sup>7</sup>.*

*1: Technical University of Crete; 2: ESA/ESTEC, The Netherlands; 3: Space Geomatica, Greece; 4: ESA/ESRIN, Italy; 5: CNES, France; 6: NSOAS, China; 7: FIO, China; 8: OceanDataLab, France.*

## Calibrate radar satellite altimeters:

- ESA Permanent Facility for Altimetry Calibration in Crete, Greece;
- Transponders, Corner Reflectors, Sea-Surface, and Sea-State Optical Techniques.

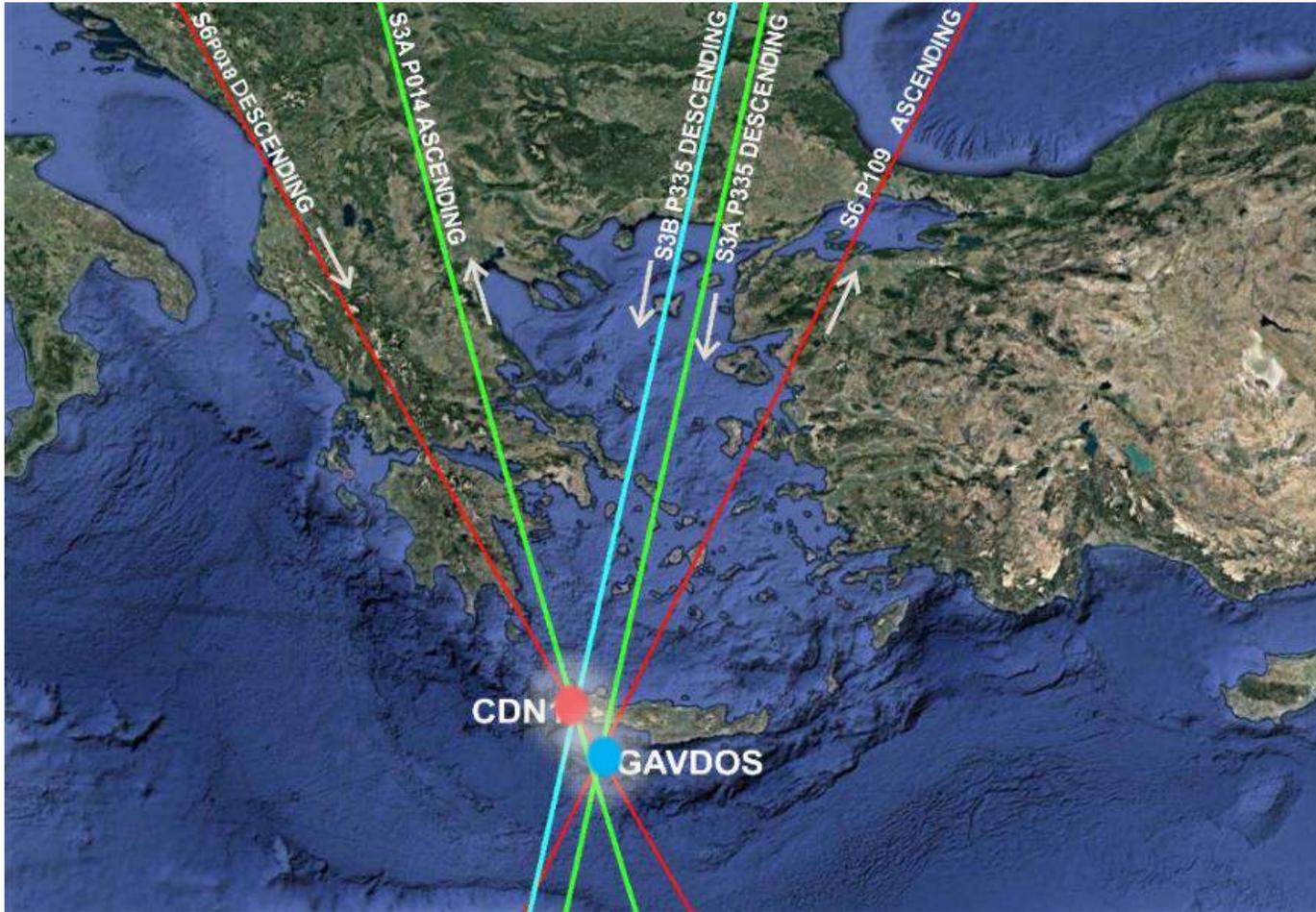
## Results of Calibration to FRM Standards:

- To absolute reference signals,
- Traceable to SI-standards,
- Different & redundant techniques (sea & land),
- Various processes, diverse instrumentation, settings, locations, etc.

## Report FRM Uncertainty for Satellite Cal/Val Results

## Analyse Performance.

## Transponders at ESA PFAC, Crete



- Multiple Cross-over (S3A, S3B, JA3, S6, CryoSat-2, SWOT),
- Low clutter,
- Cross-calibration,
- Crystal clear signal of satellites



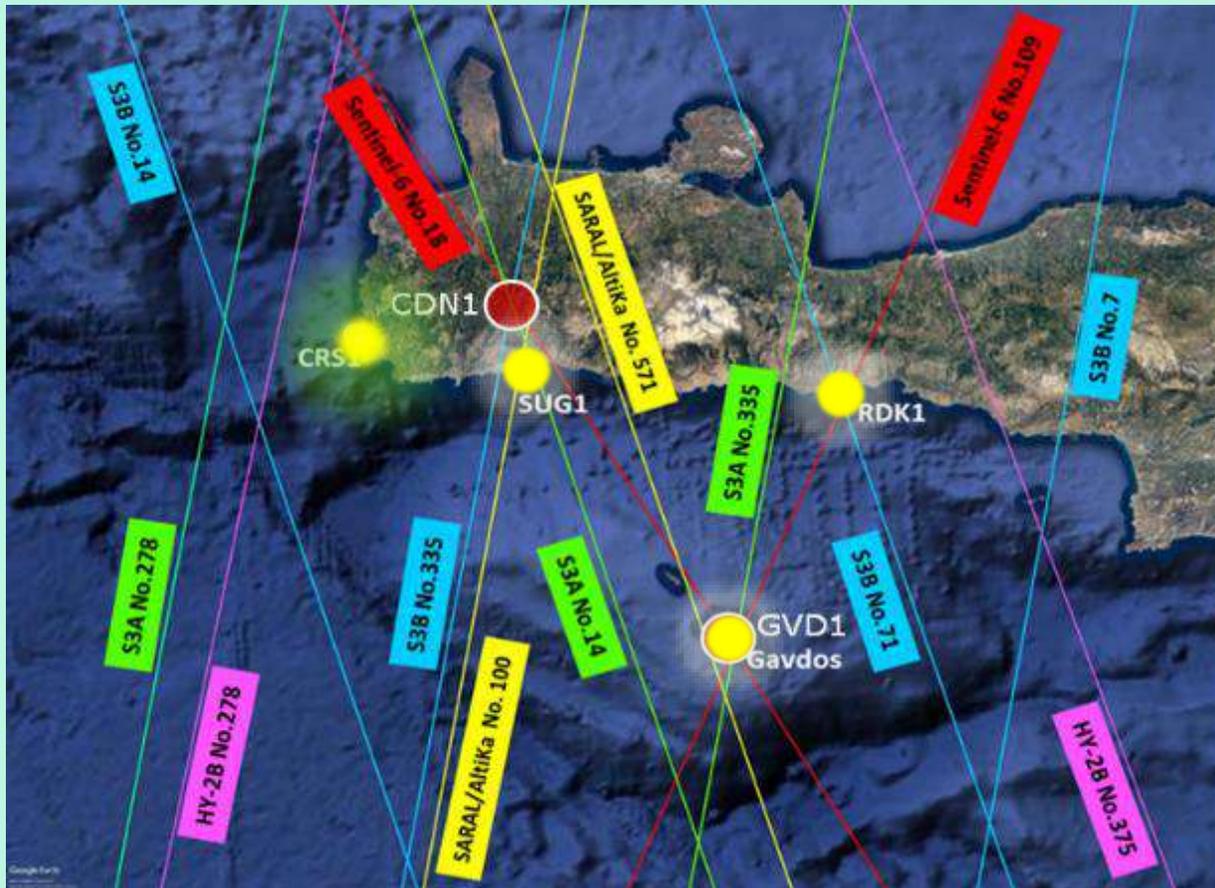
### Gavdos (GVD1 Transponder)

S3A, Sentinel-6 (A109 & D18), CryoSat-2  
Sea-Surface Cal/Val



24

## Sea-surface infrastructure, Crete



CRS1 Cal/Val site (West Crete)



SUG1 Cal/Val site (West Crete)

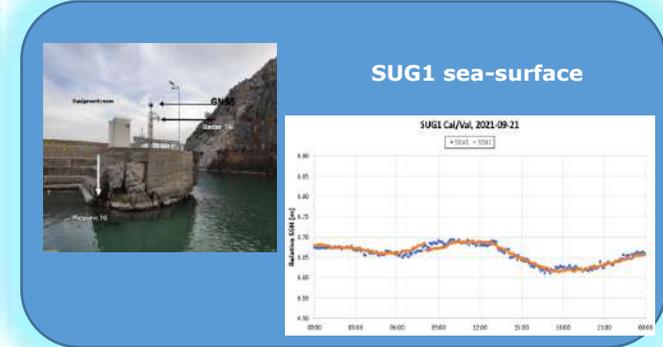
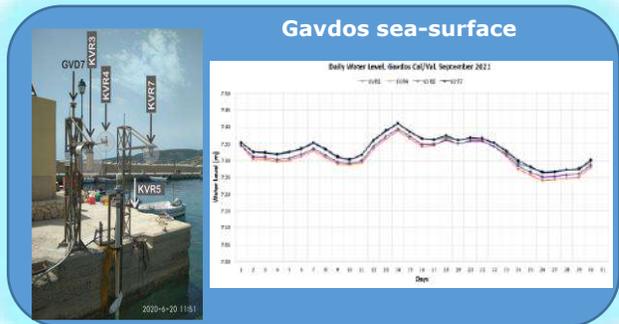
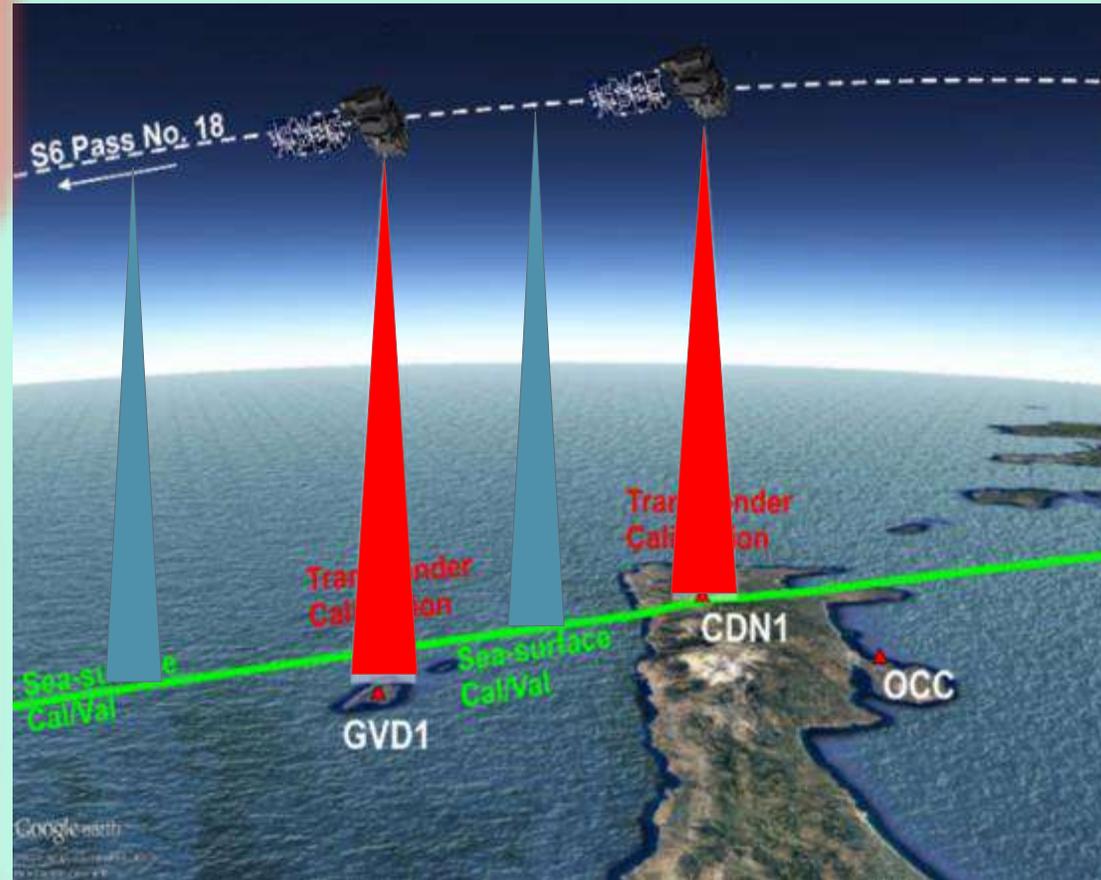
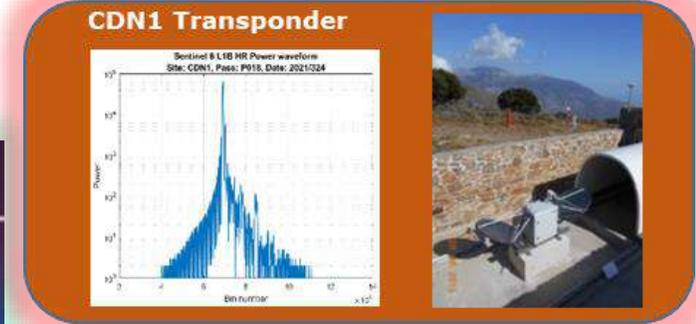
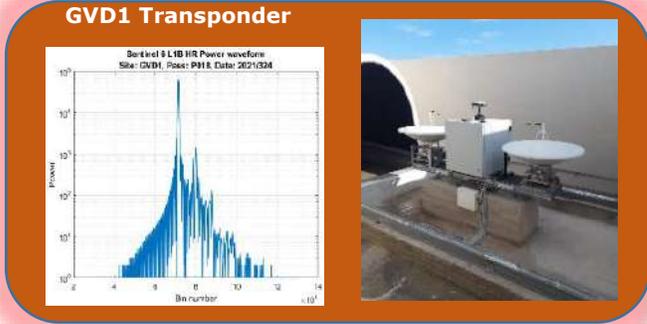


Gavdos Cal/Val site

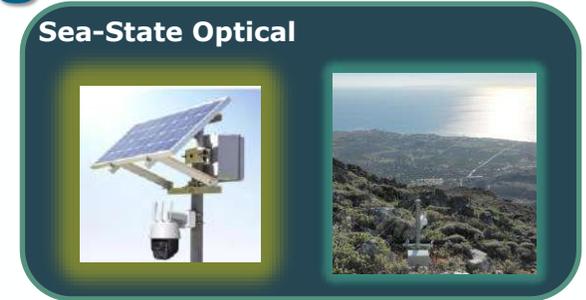
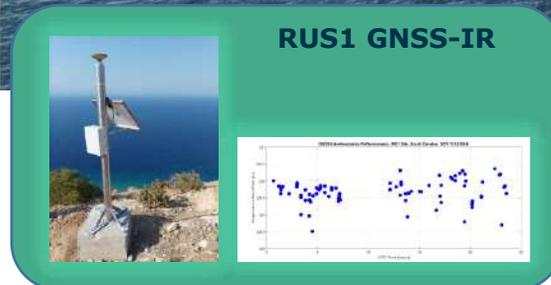
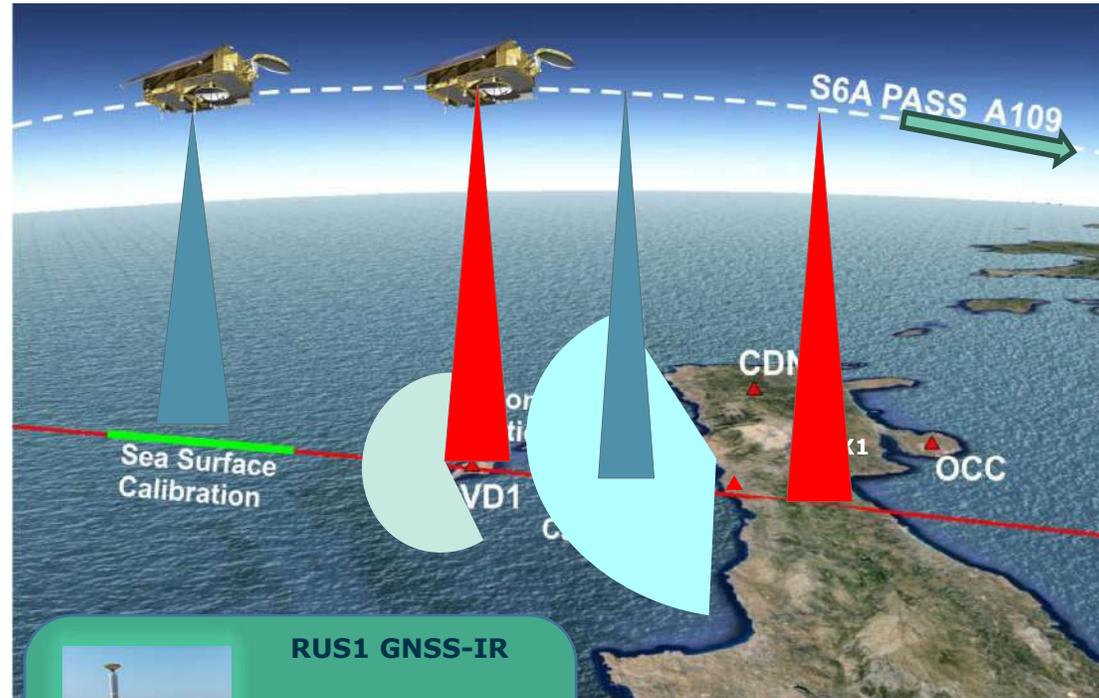
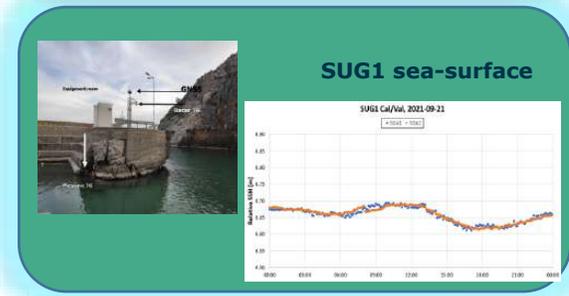
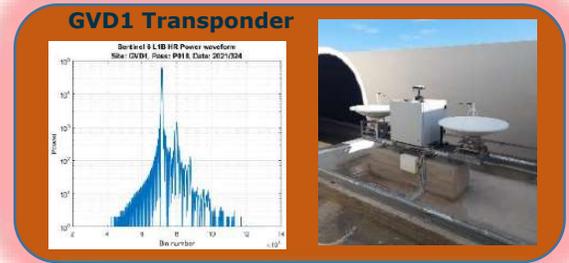
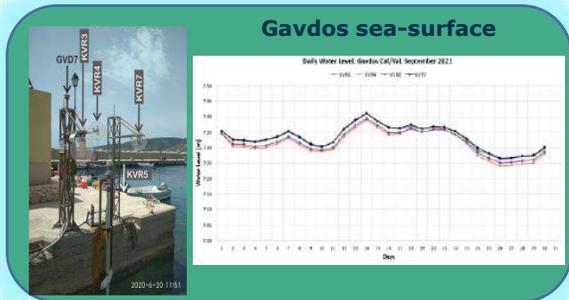


RDK1 Cal/Val site (South Crete)

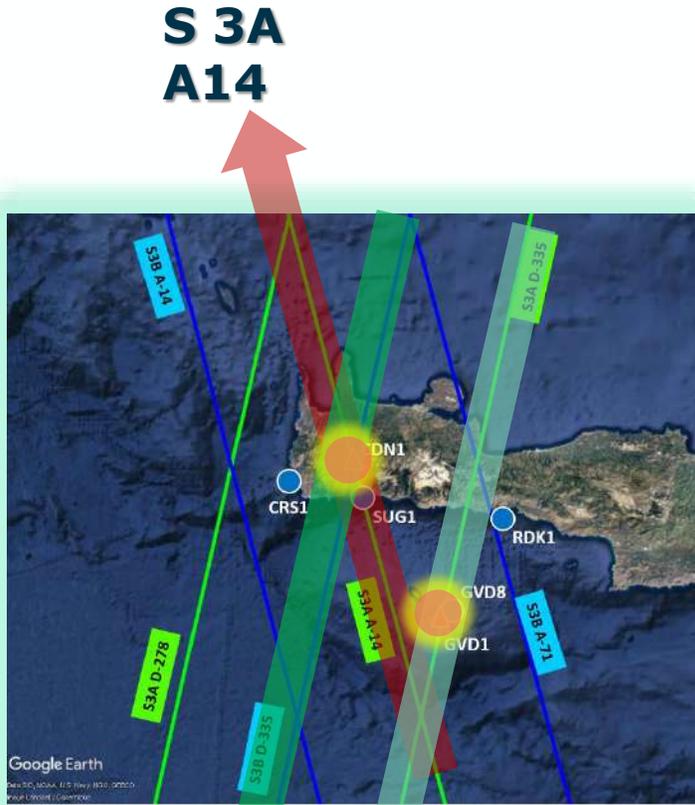
## “Simultaneous” Cal/Val: Descend



## “Simultaneous” Cal/Val: Ascending

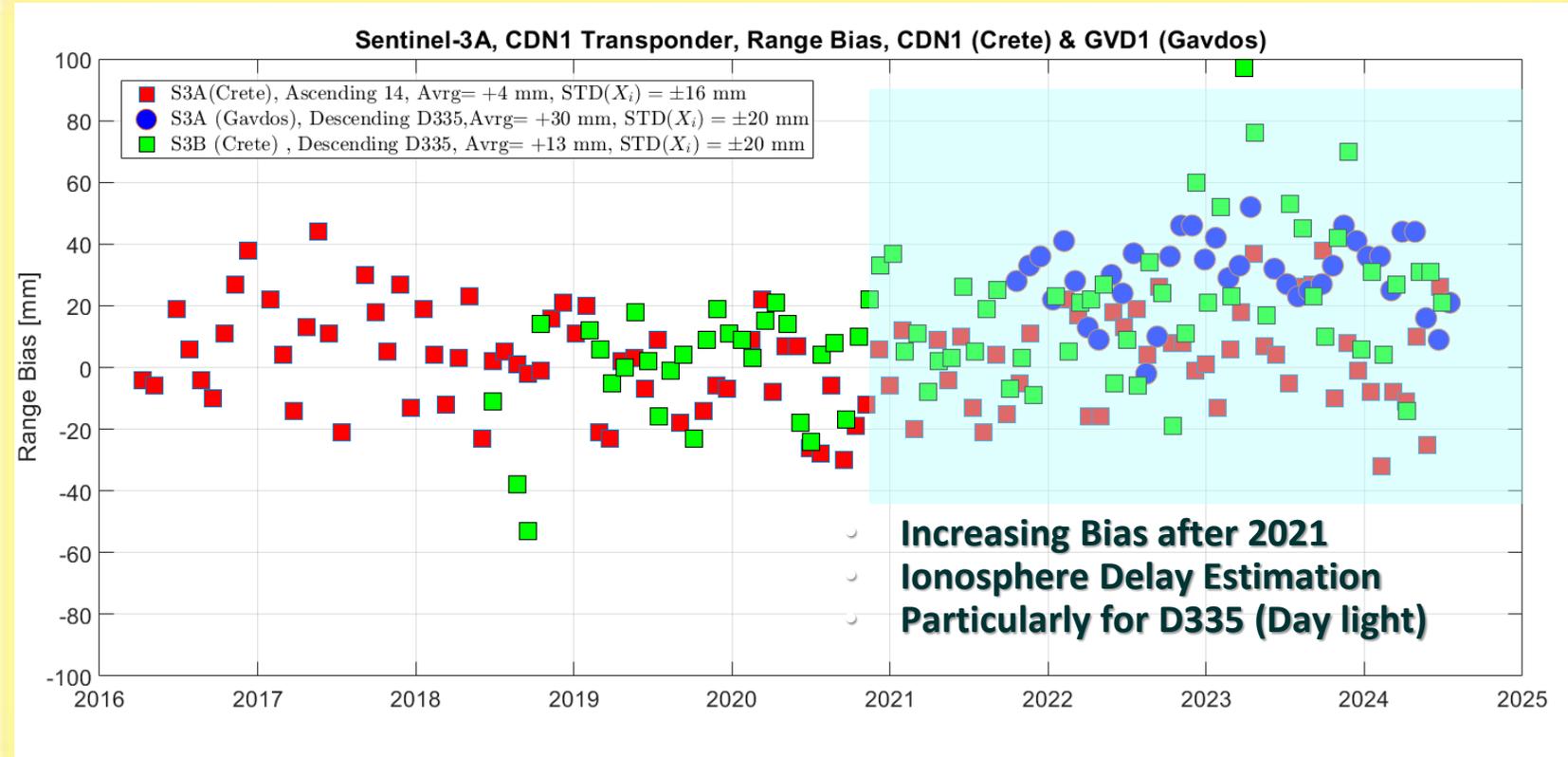


# Sentinel-3A & -3B Transponder Range Bias [Delay-Doppler]



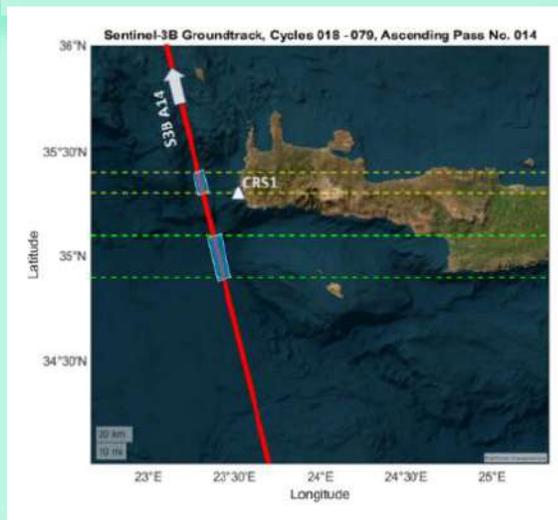
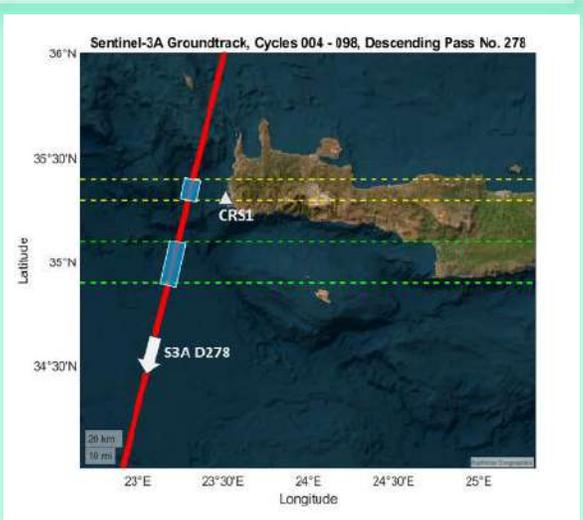
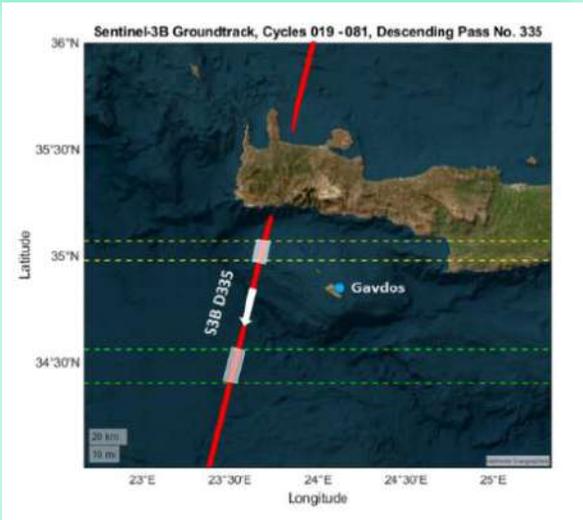
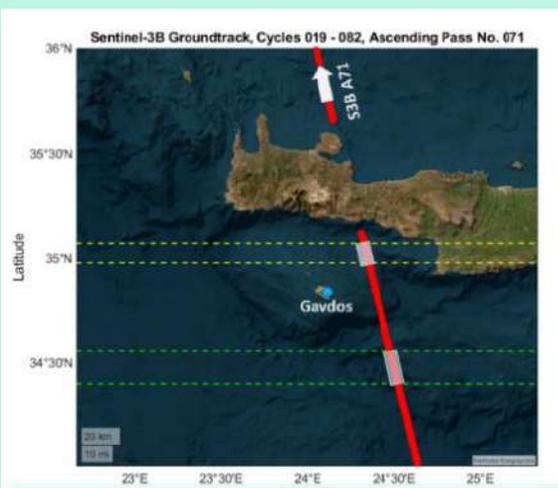
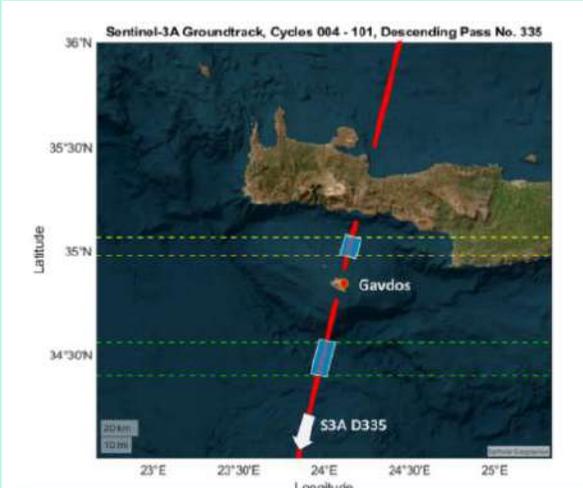
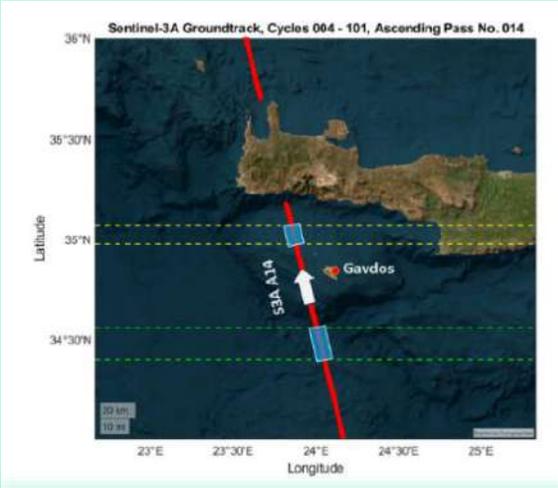
S-3B  
D335

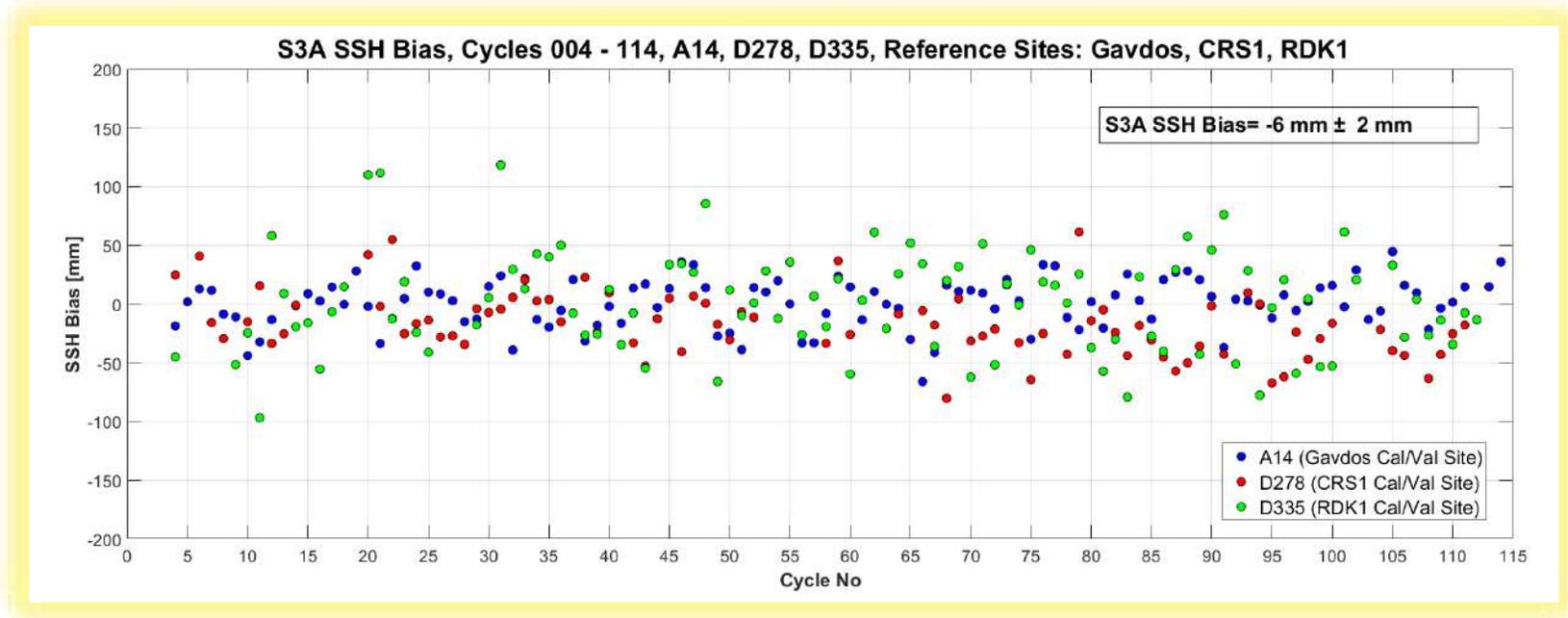
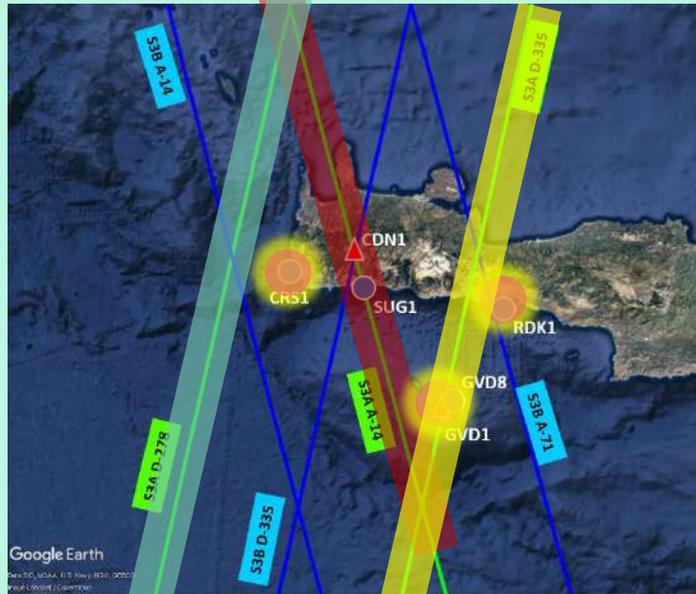
S-3A  
D335



- S3A Range Bias (Crete) = +4 mm ± 16 mm, Ascend A14; [U(FRM)= ± 30mm]
- S3A Range Bias (Gavdos) = +30 mm ± 12 mm, Descending D335, (Day light pass)
- S3B Range Bias (Crete) = +20 mm ± 16mm, Descending D335, (Day light pass)

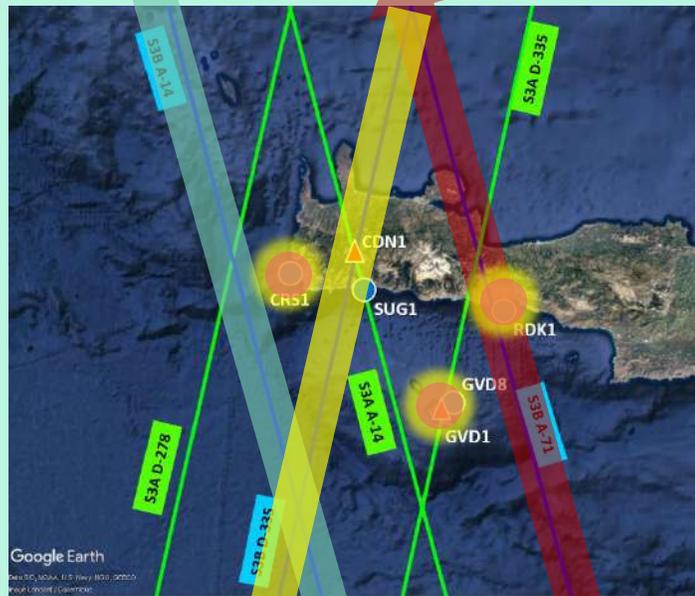
# Sentinel-3: Sea-Surface Cal/Val Regions



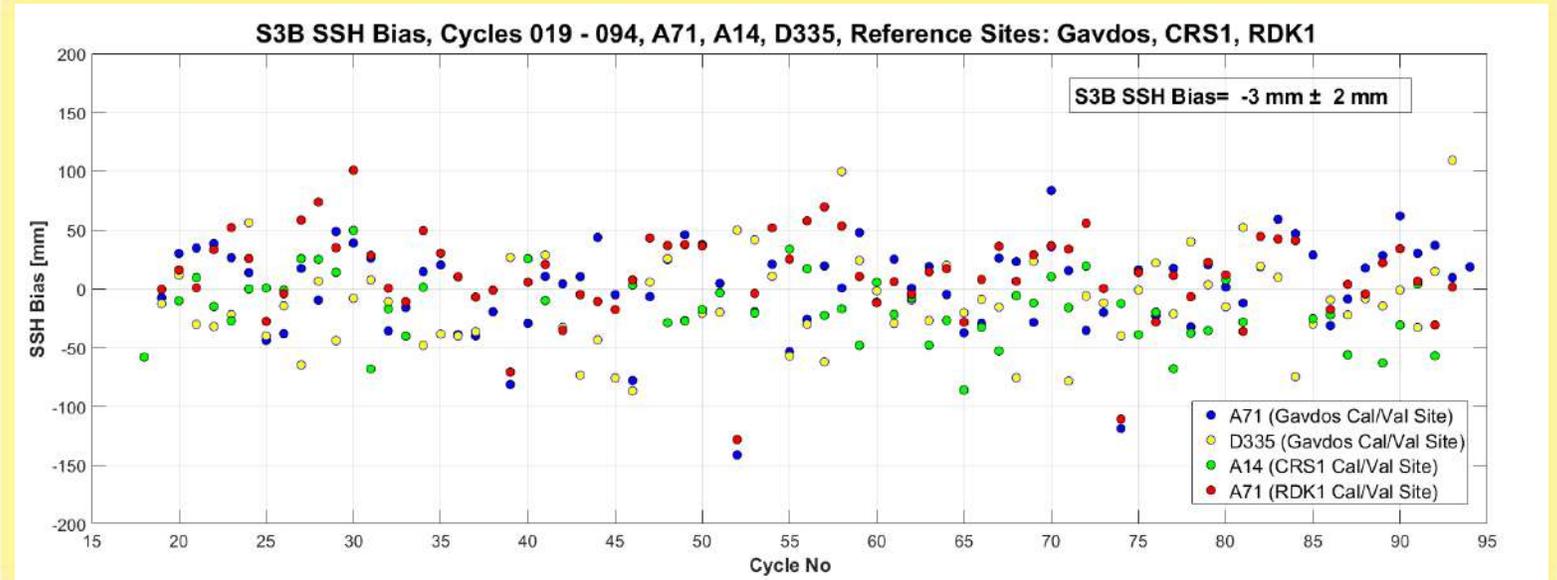


○ **S3A SSH Bias (Crete) = -6 mm ± 2 mm, [U(FRM)= ± 50mm]**

**S3-B A14**      **S3-B A71**

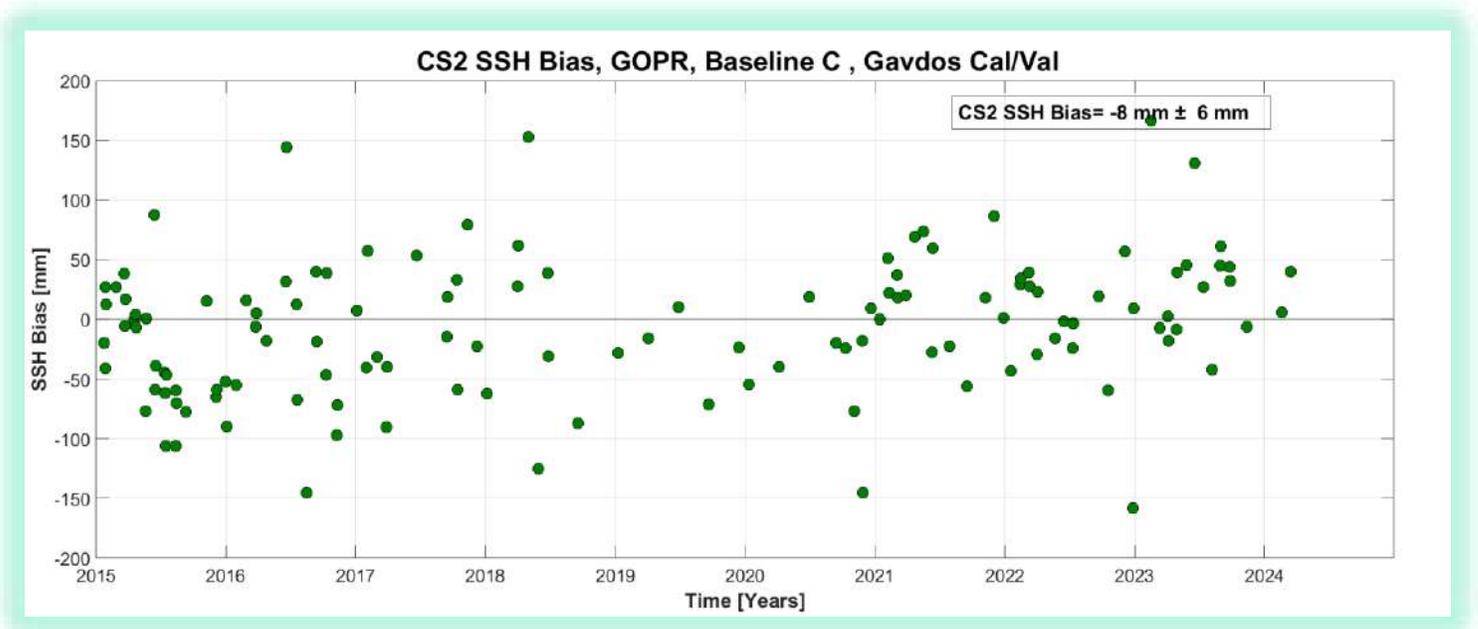
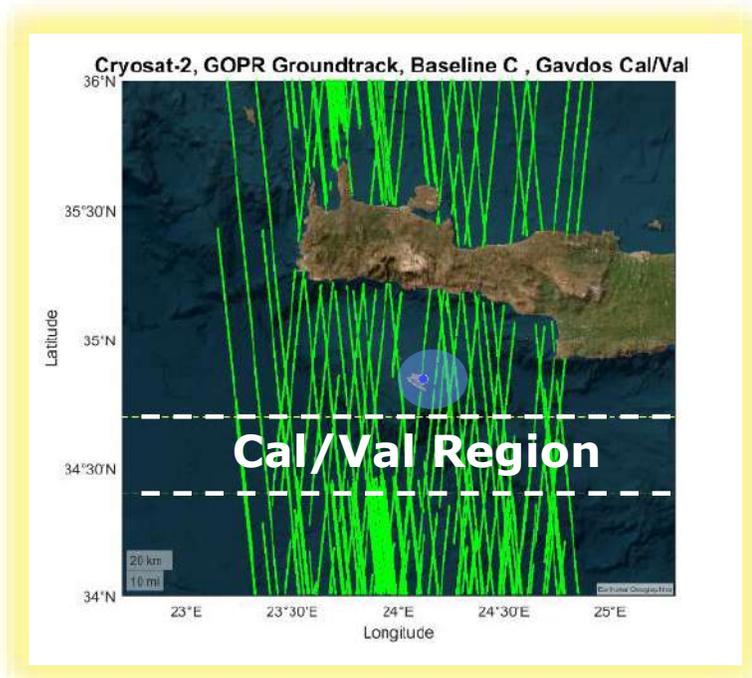


**S3-B  
D335**



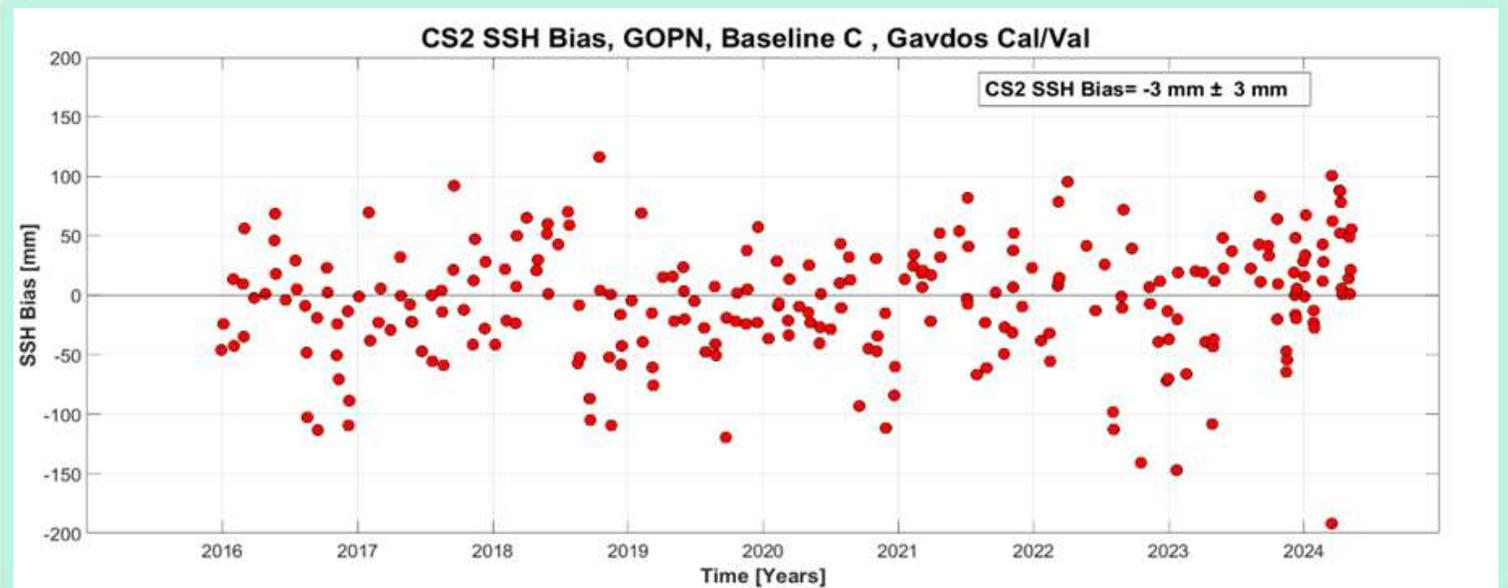
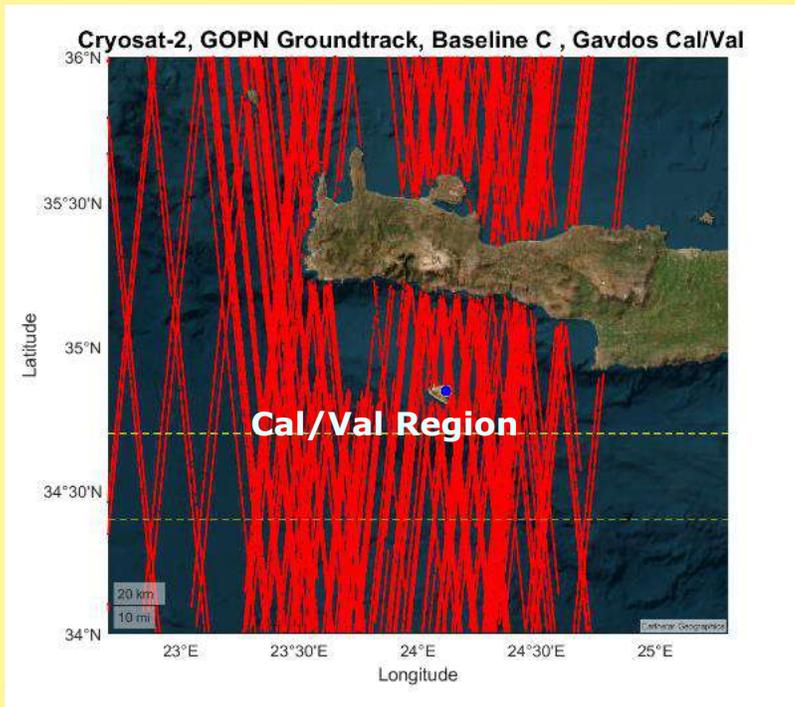
⌘ **S3A SSH Bias (Crete) = - 3 mm ± 2 mm, [U(FRM)= ± 50mm]**

## Geophysical Ocean Products-SAR, Baseline-C, 23-Jan-2015 till 6-May-2024 (N=132) Gavdos Cal/Val Reference site

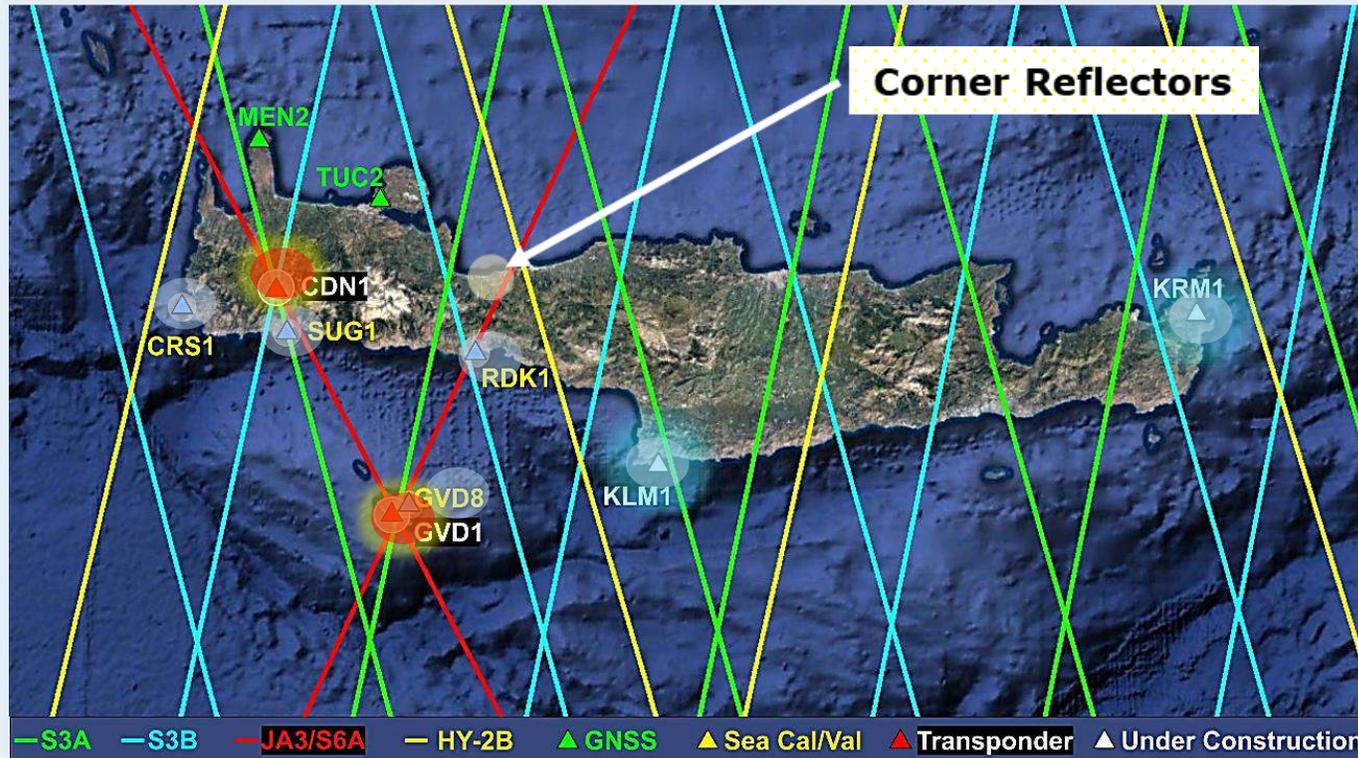


**SSH Bias = -8 mm ± 6 mm, [ U(FRM)= ± 50mm]**

**Geophysical Ocean Products: SARIn, Baseline-C,  
28-Dec-2015 till 8-May-2024 (N=247),  
Gavdos Cal/Val Reference site.**



**SSH Bias = -3 mm ± 3 mm, [ U(FRM)= ± 50mm ]**



- Ground infrastructure covering 260 km (E-W),
- Diverse Instrumentation, Techniques, Locations,
- FRM strategy fully followed,
- LRM, SAR, FF-SAR, SWH, Sigma0,
- Gavdos Transponder tied to absolute time,
- Ascend & Descend orbits (Directional Errors),
- Different sats & Results are cross-examined,
- Data & Results screened for quality;
- Confidence on results built up;
- Patterns & structures can be understood;
- Uncertainty Budget in FRM Standards.

# September 2025: Altimetry Cal/Val Review meeting



**International Review Workshop  
on  
Satellite Altimetry Cal/Val & Metrology  
2025**

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Center of Mediterranean Architecture | Chania, Crete, Greece

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Thank you Any Questions?

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