



ESA-JAXA Pre-Launch EarthCARE Science and Validation Workshop

13 – 17 November 2023 | ESA-ESRIN, Frascati (Rome), Italy

FRM4Radar – Cloud Profiling for Satellite Validation

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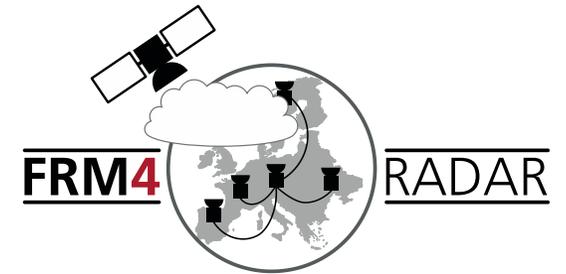
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3) SMHI, Sweden 4) INOE, Romania 5) Finish Meteorological Institute, Finland 6) ESA / ESTEC 7) ESA / ESRIN

Objectives of the FRM4Radar Project



- Create the foundation for Fiducial Reference Measurements (FMR) for the EarthCARE Cloud Profiling Radar (CPR)
- The role of the FMR's is to deliver confidence to user community in the CPR products by means of ground-based observations
 - Quality check of data: C-FMR, C-CD,
 - Quality check of retrieval products: C-CT, C-CLD, C-PRO
- The EarthCARE CPR FMR is a 94-GHz radar network
 - Uses the same wavelength as the EarthCARE CPR
 - Closes geographical gaps of the European ground-based network
- Foster the development of new Cal/Val products
- Long term monitoring of the data – over years



Cloudnet & FRM4Radar Network



- Compliment the existing 94-GHz EU network and fill gaps in under sampled regions (Sweden & Romania)
 - Coverage of different cloud and climate regimes
- Instrumental synergy with ceilometer and microwave radiometer
 - Run 94-GHz version of Cloudnet (no microwave radiometer needed)
 - Improve Cloudnet coverage
 - Validation of CPR retrievals
- Cloudnet: Cloud target classification algorithm (Illingworth, 2007, BAMS, Tukiainen et al., 2020, JOSS)



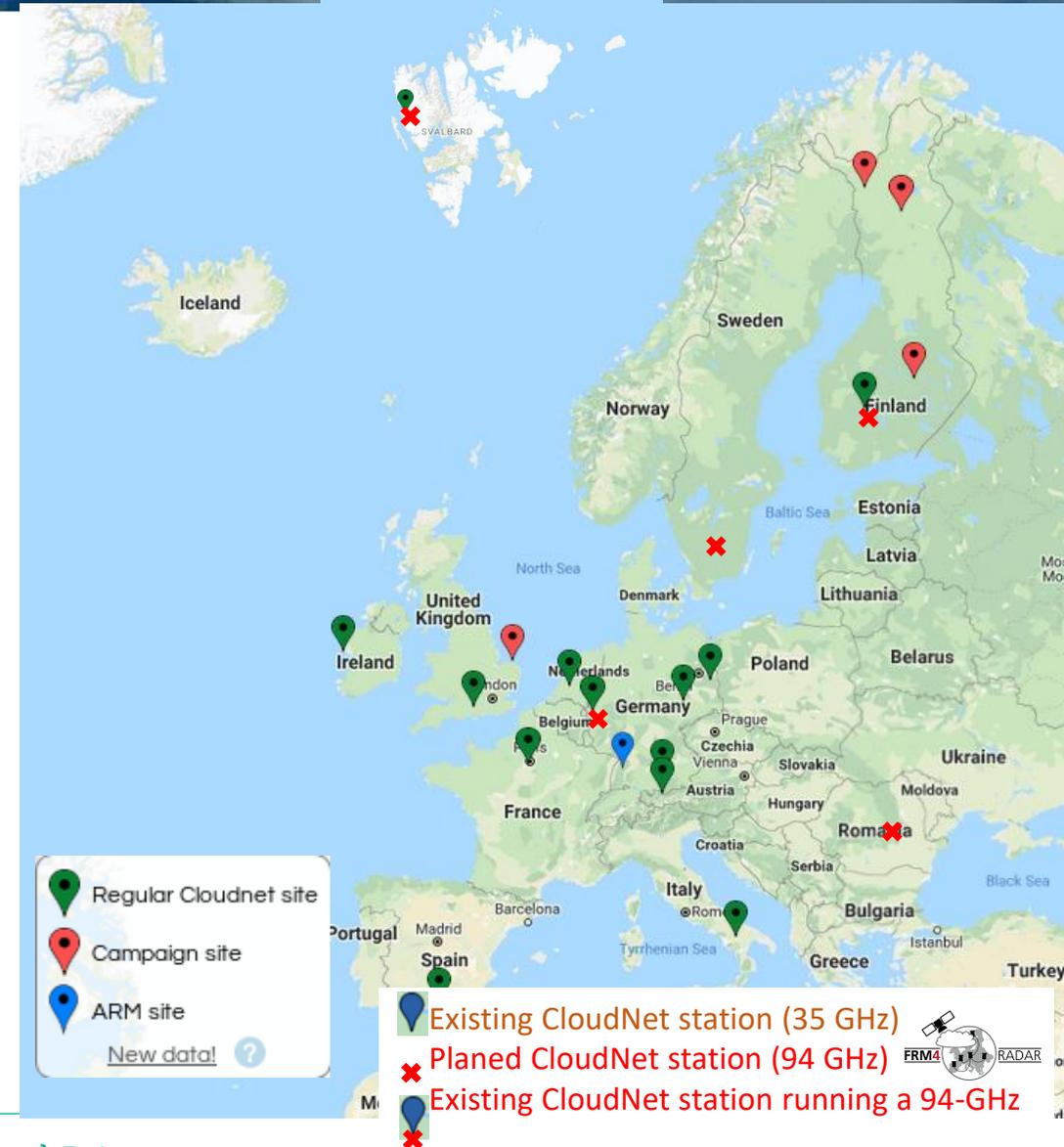
ACTRIS-CloudNet classification



- Cloudnet algorithm
 - Atmospheric target classification algorithm
 - Instrumental synergy
 - ✓ Radar
 - ✓ Microwave radiometer (89 GHz channel radar)
 - ✓ Ceilometer
 - Implementation of the FRM4Radar station into the Cloudnet/ACTRIS network
 - Standardized quality controlled data set

➤ Collaboration with ACTRIS

- Ze-monitoring
- antenna miss-pointing

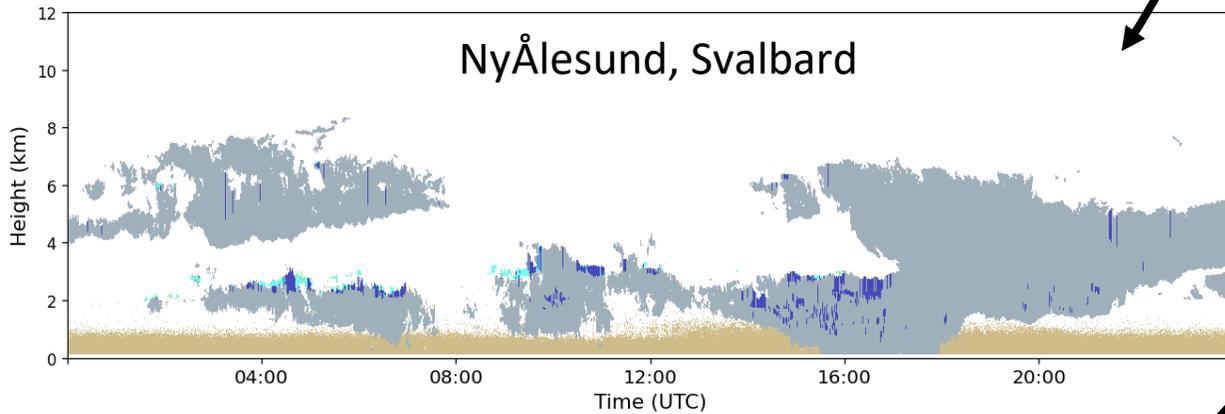


ACTRIS CloudNet classification

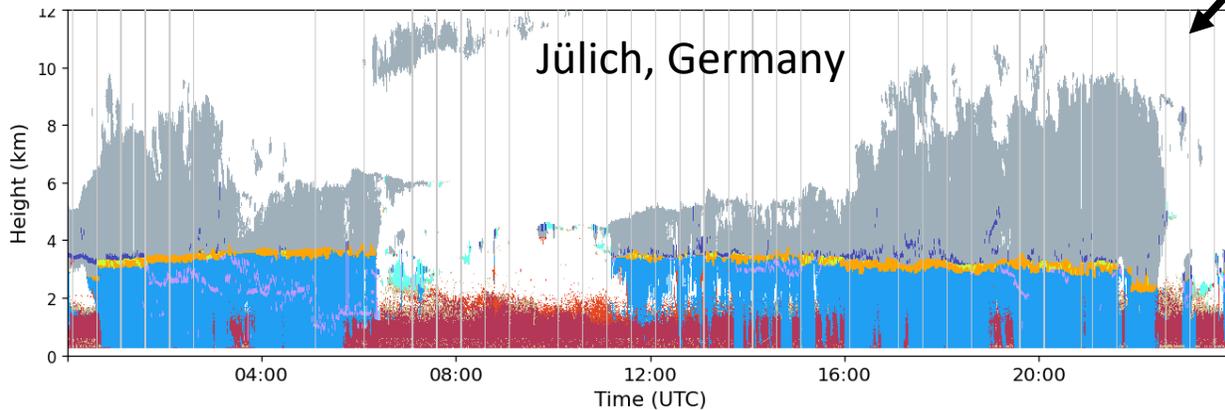


Cloudnet Classification 13th Oct 2023

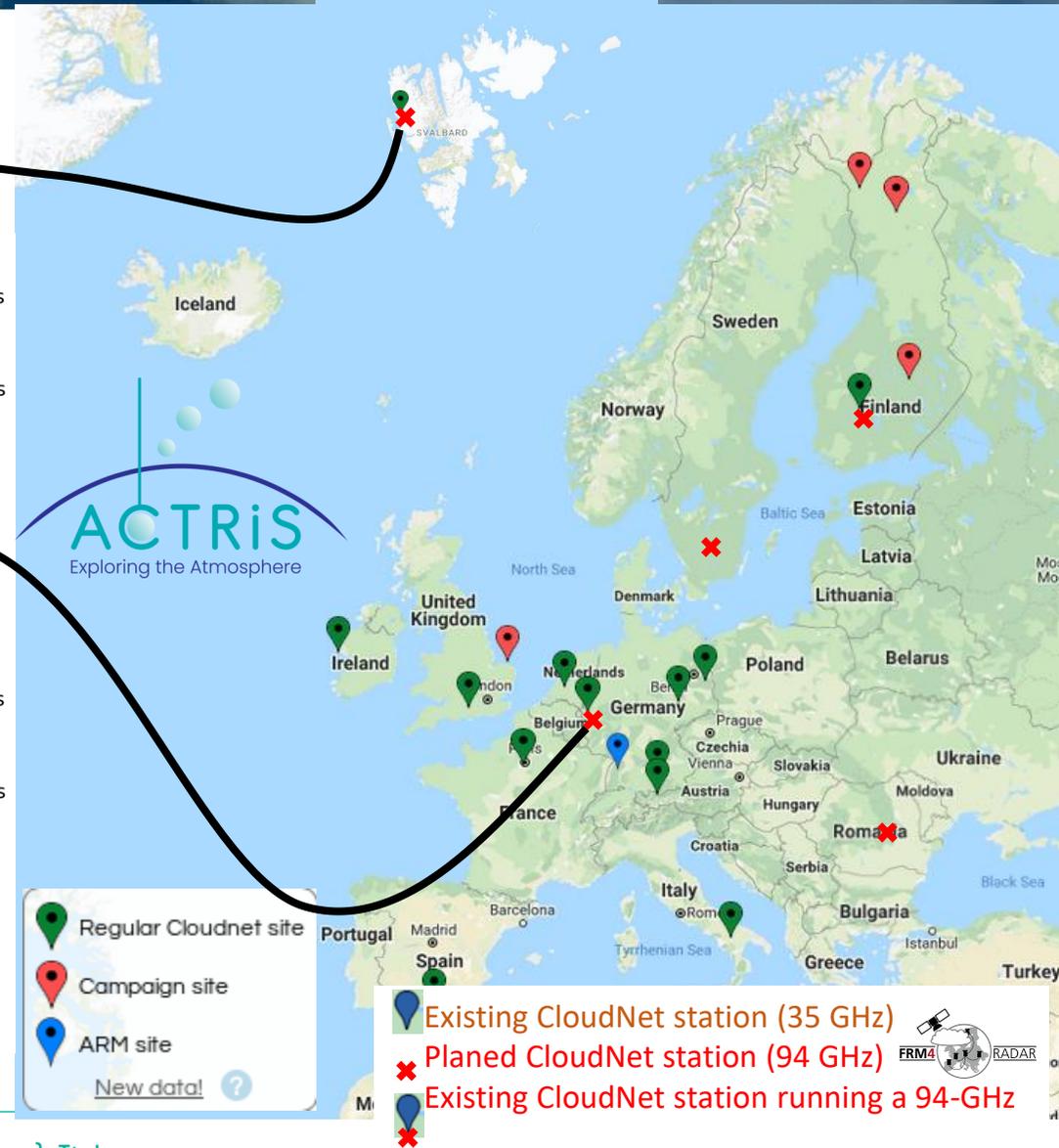
NyÅlesund, Svalbard



Jülich, Germany



see www.cloudnet.fmi.fi for more



Concept: Radar Ze-monitoring



- Total system calibration monitoring
- Based on Disdrometer radar reflectivity comparison method *

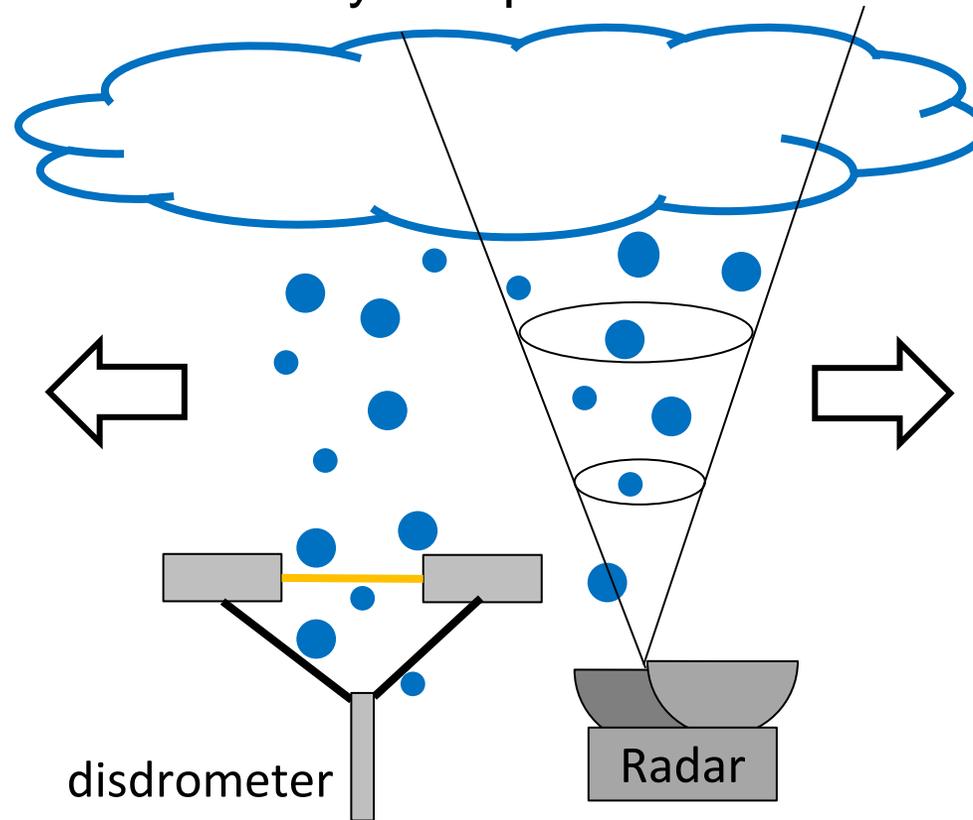
* Kollias et al., 2019, AMT
Myagkov et al., 2020, AMT
Chellini, et al., 2022, JGR Atmos

Disdrometer:

optical particle counter

N(D)

- Forward modeling of Ze based on measured N(D)
- Compare forward simulated Ze_dis to radar Ze



Radar:

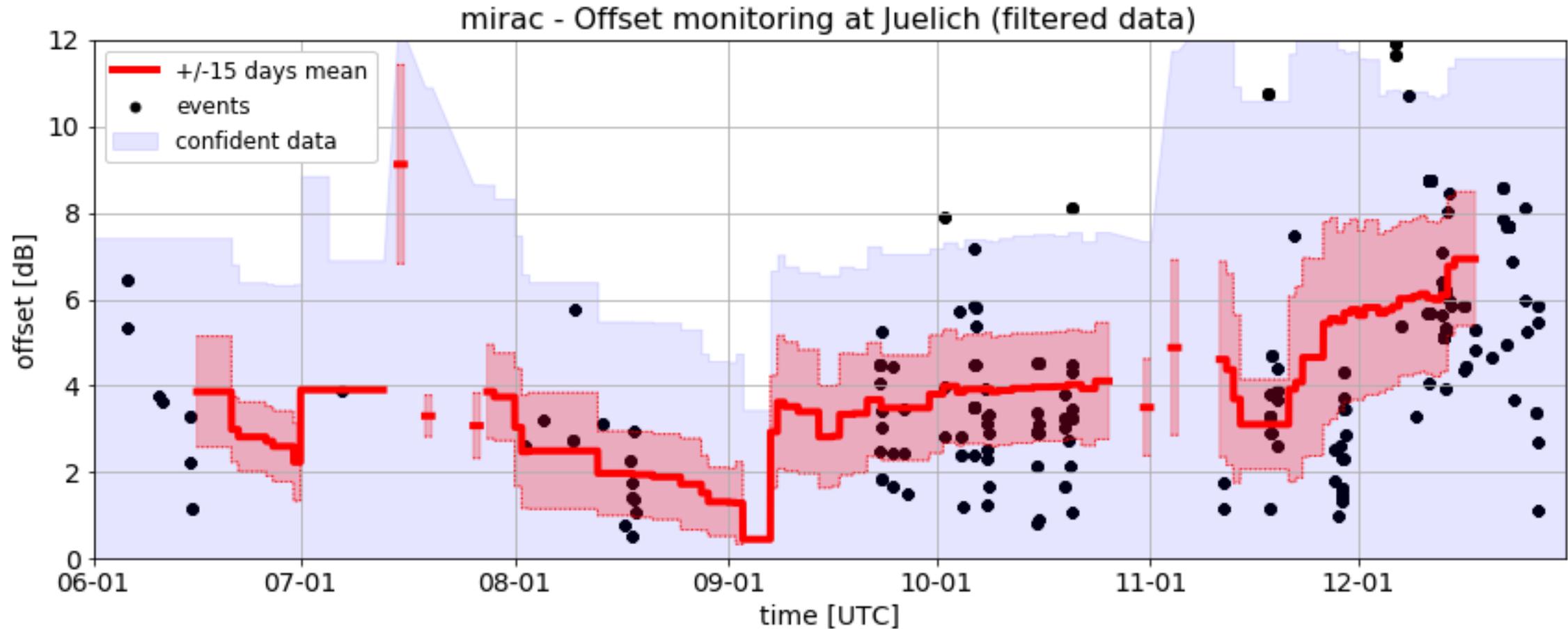
Measures reflectivity (Ze) of all drops in volume

- $Ze \sim N(D) D^6$
- Correction of Ze for attenuation
- Compare Ze to Ze_dis calculated from Disdrometer measurements

➤ **Cooperation with ACTRIS to get a standard method**



Example: Radar Ze-monitoring, JOYCE, 2019



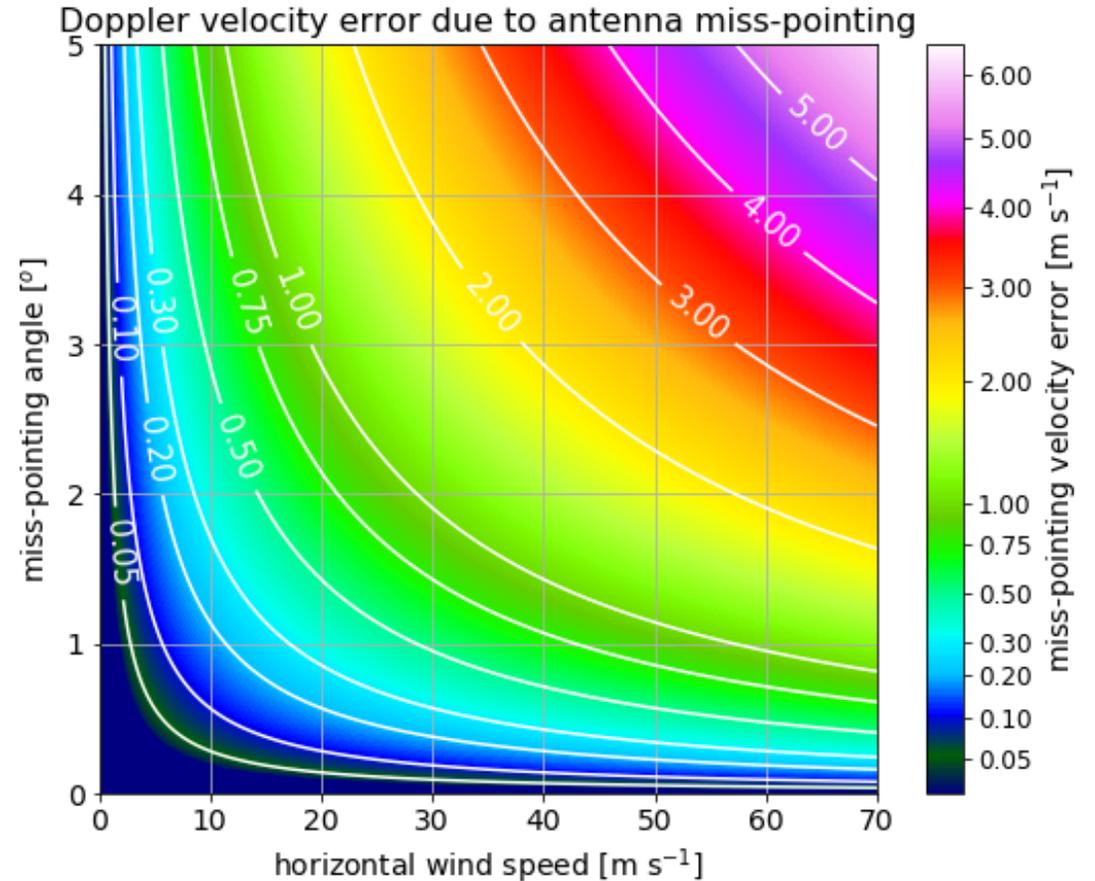
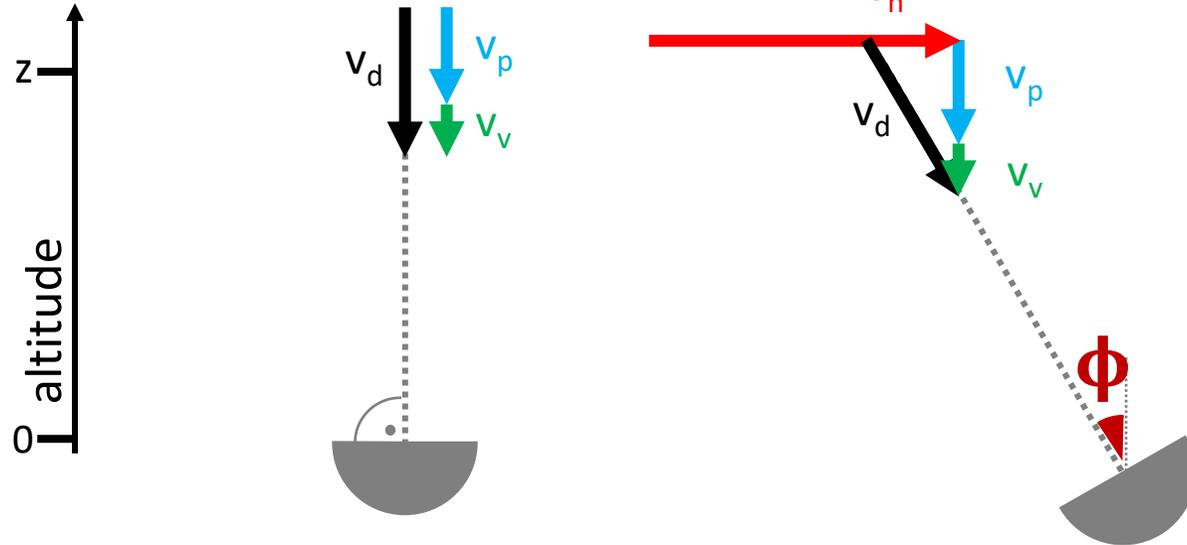
Next project phase: Why the offset differs that much for different sites?



Concept: Antenna pointing correction



zenith pointing antenna miss-pointed antenna



Doppler velocity is velocity component along the line of sight

- $V_d = \text{particle fall velo} + \text{air motion}$
- $V_d = \text{particle velo} + \text{air motion} + \text{hor wind contribution}$

So V_d is a function of V_h , and of the miss-pointing angle ϕ

Horizontal wind information from ECMWF IFS or retrieved from radar PPI scans

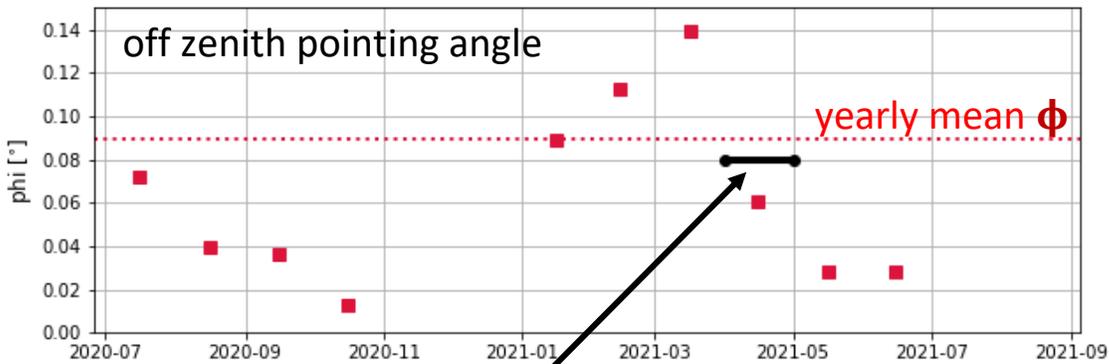
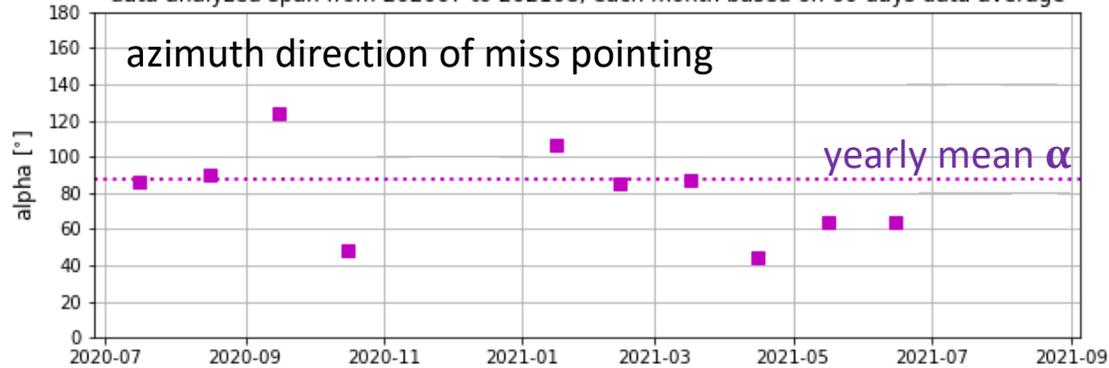


Example: Antenna pointing correction



a) Monitoring of the off zenith pointing

data analyzed span from 202007 to 202108, each month based on 60 days data average



off zenith angle
received from sun scans

work in progress

90 days of Doppler velocity measurements and wind direction data (ECMWF IFS)

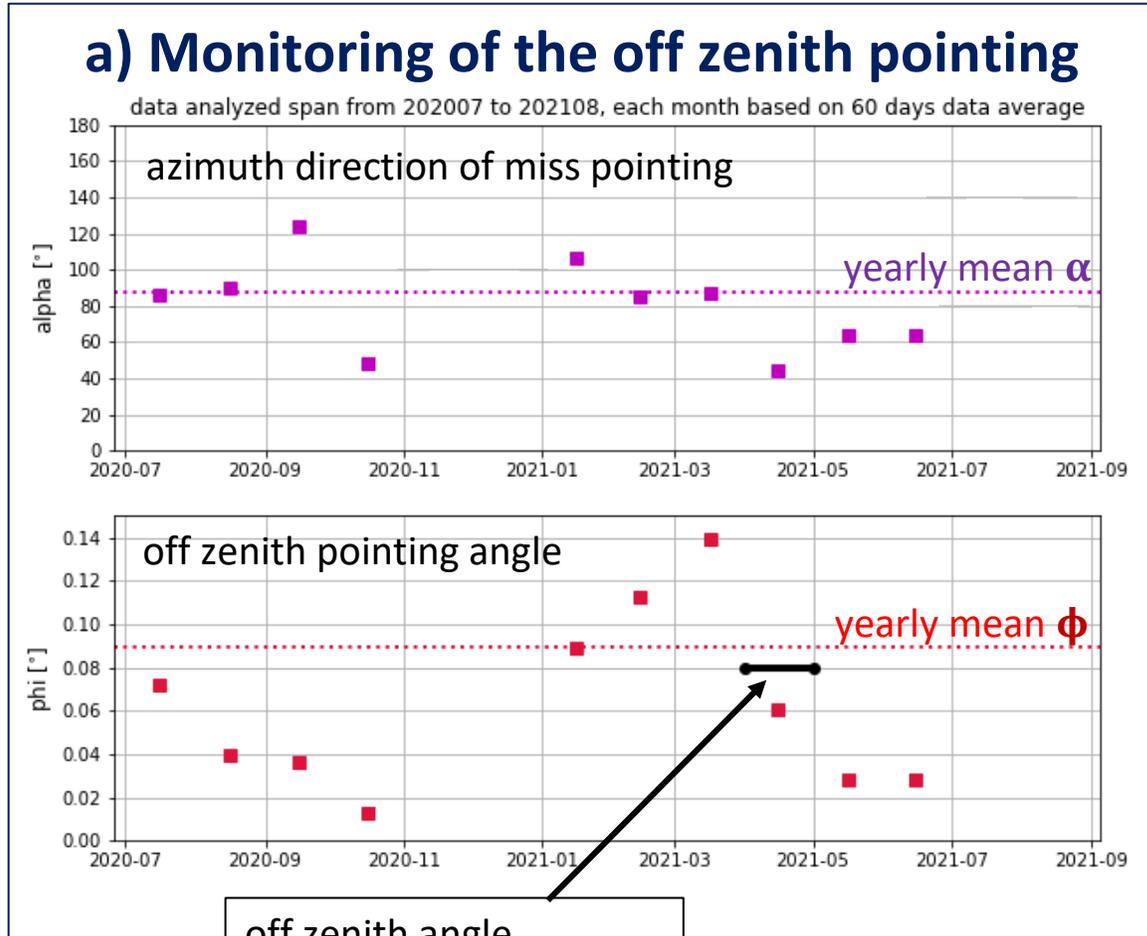
Fit the model against the data set

obtain ϕ : off zenith pointing angle

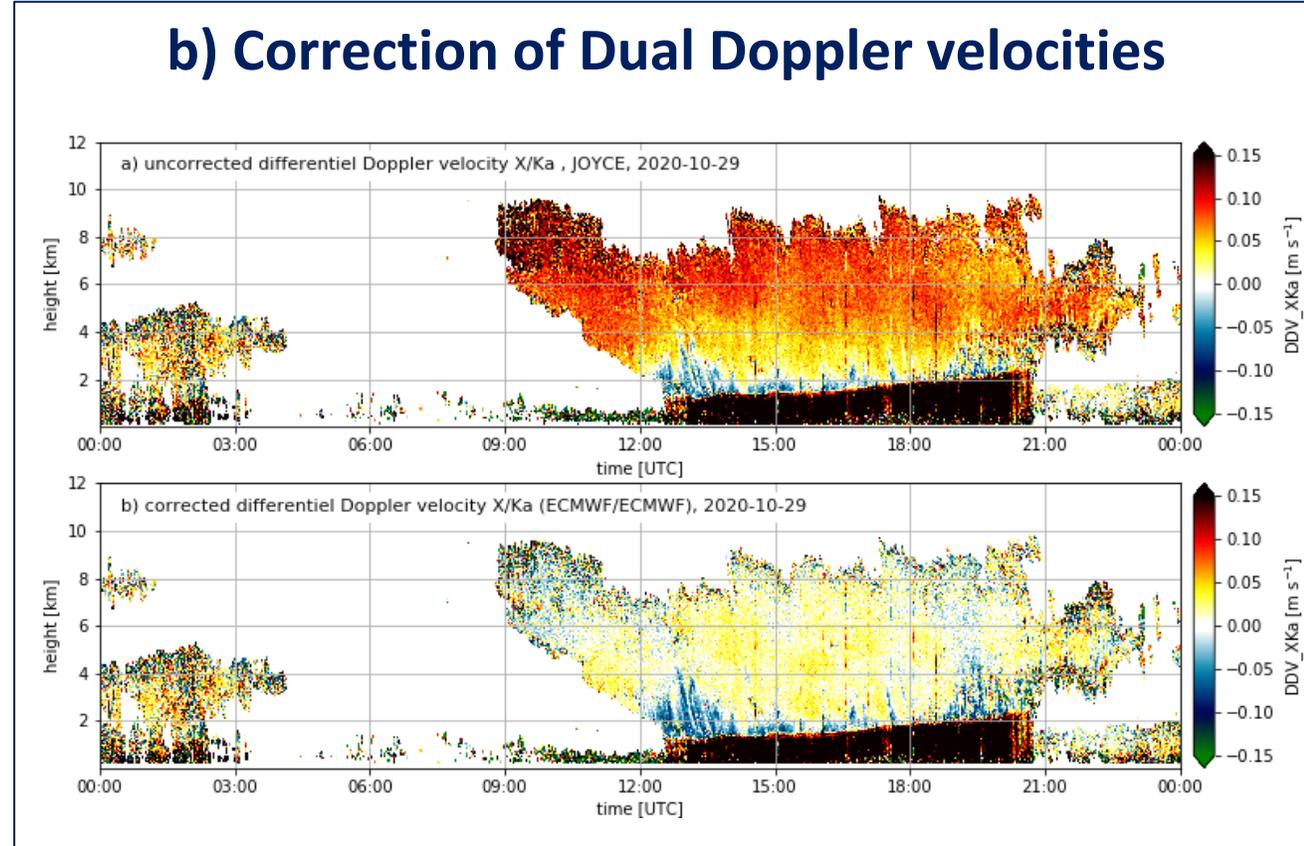
obtain α : azimuth direction of ϕ



Example: Antenna pointing correction



work in progress



Doppler velocity difference X/Ka should be 0 at cloud top
 Off-zenith pointing cause errors up to 0.15 m s^{-1}
 After correction of each radar
 reduction to the X- band Doppler velocity resolution



CPR forward simulation tool



Motivation:

- Create data base for CPR Cal/Val
- Usage of existing long time data sets
- Easy usage -> python code (github)

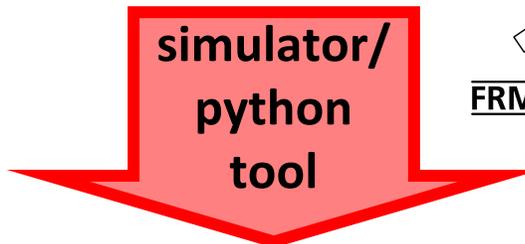
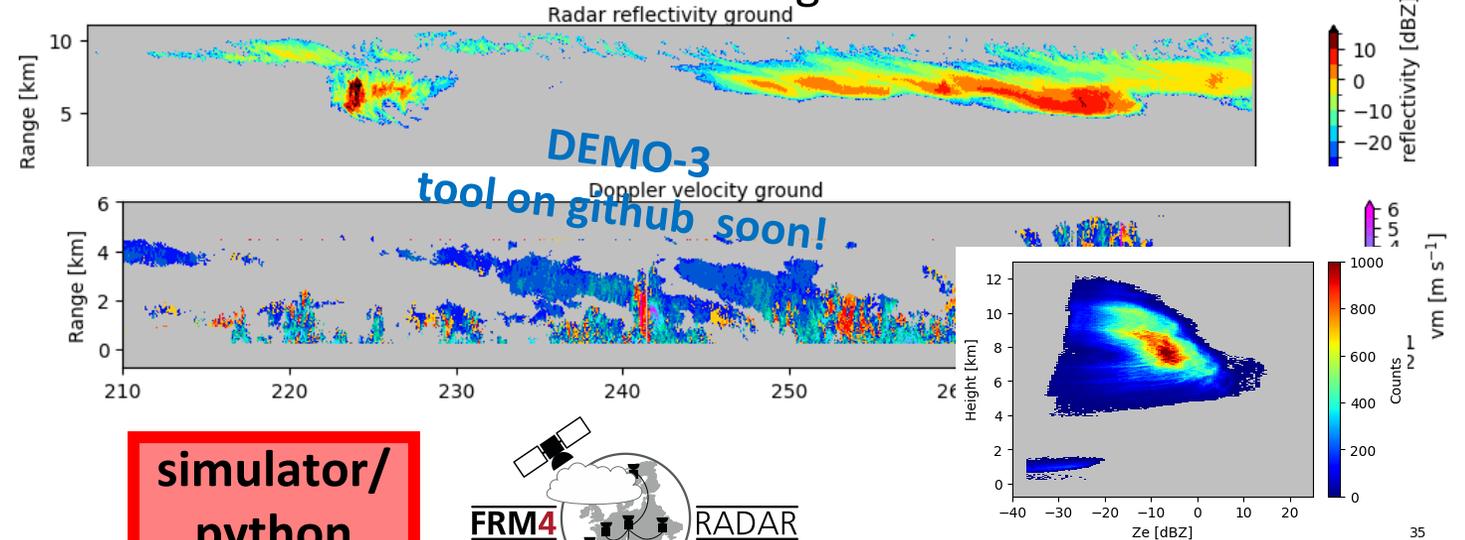
INPUT: Ground based radar data:

- Readers ACTRIS, GEOMS, airplane radar (Polar5, RASTA)
- sites act as 'ground truth' for EarthCARE CPR simulations
- flexible satellite configuration
 - CloudSat
 - EarthCARE

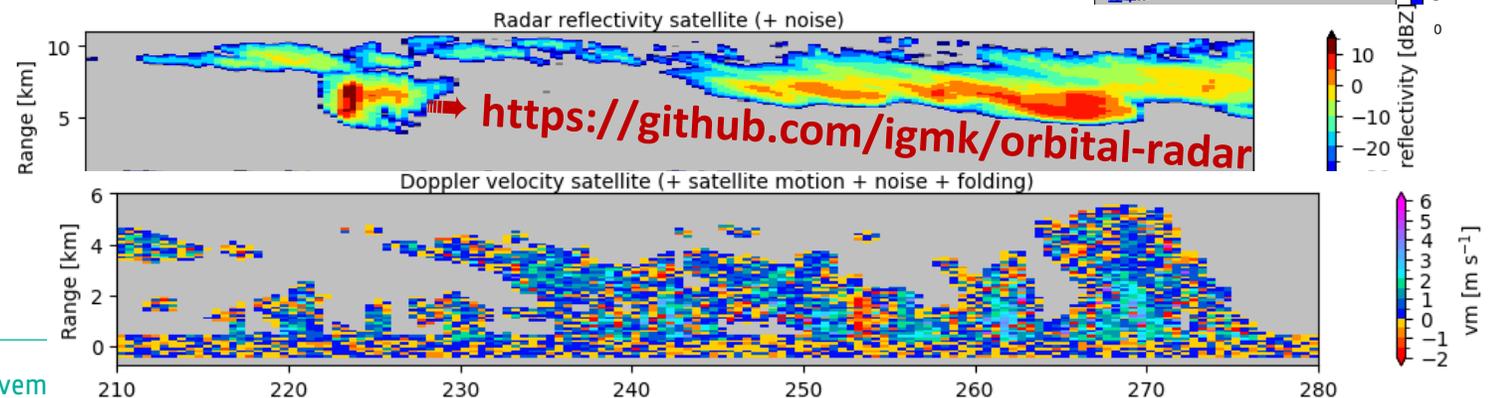
Output: EarthCARE CPR view like data

- Validation of L1 with ground
- Creation of long term data sets

INPUT: ground based radar data



OUTPUT: EarthCARE synthetic CPR



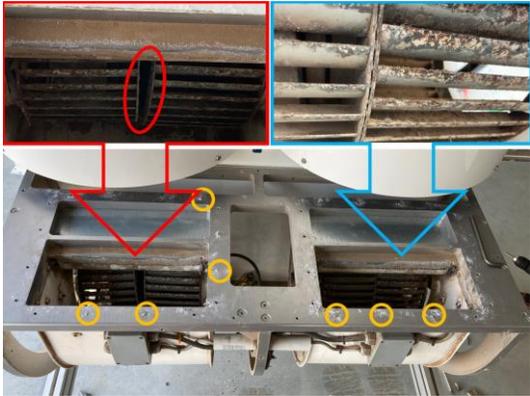
Results



Cloud Radar in Cape Verde – ASKOS campaign 2021-2022

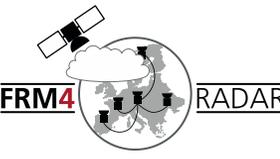


- Lessons learned in radar and disdrometer operation
- Radar data processing (Matlab on github)
 - publication planned
- INOE radar part of ASKOS campaign at Cape Verde
 - Data uploaded to EVDC
- Simulation tool to create synthetic EarthCARE CPR data
 - Release planned soon, latest till March 2024
- FRM4Radar method on its way to be implemented in ACTRIS cloud remote sensing processing
 - Ze-monitoring – ACTRIS started the implementation
 - Antenna pointing monitoring – work in progress



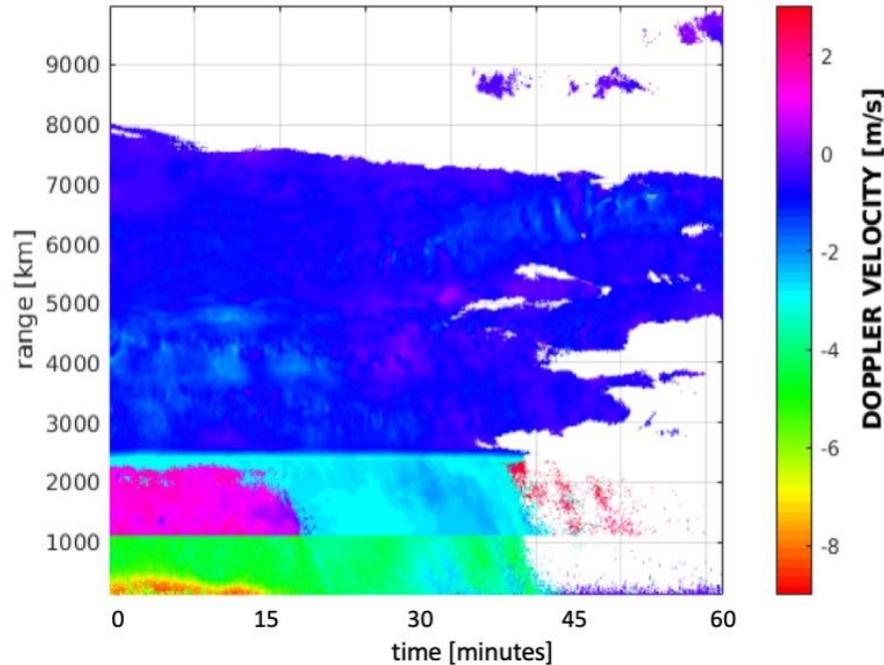


Appendix: 94-GHz cloud radar processing code

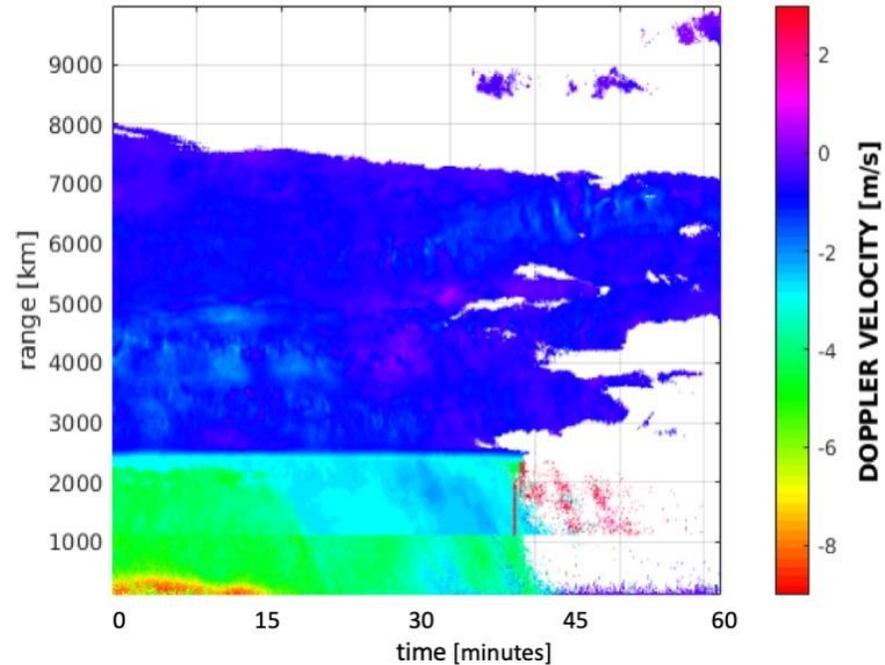


- Post-processing of the 94-GHz radar data
 - Unfolding of the recorded Doppler spectra
 - Moment estimation: Z_e , V_m , S_w and higher moments such as S_K and K
 - Estimation of LDR
 - Data output in GEOMS

a) Example folded Doppler velocity



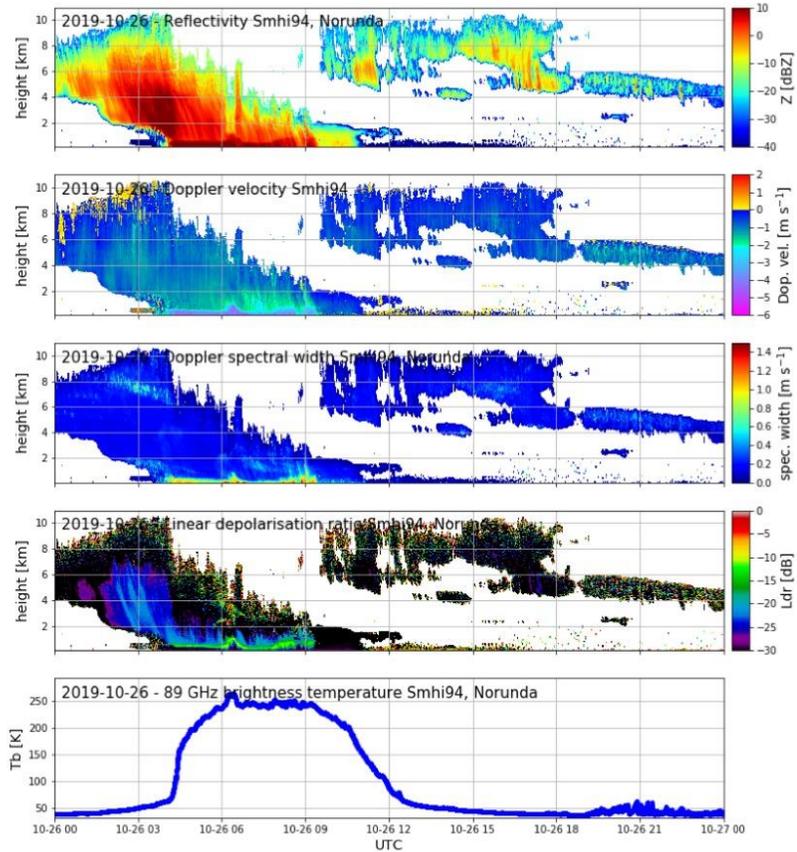
b) Example: unfolded/corrected Doppler velocity



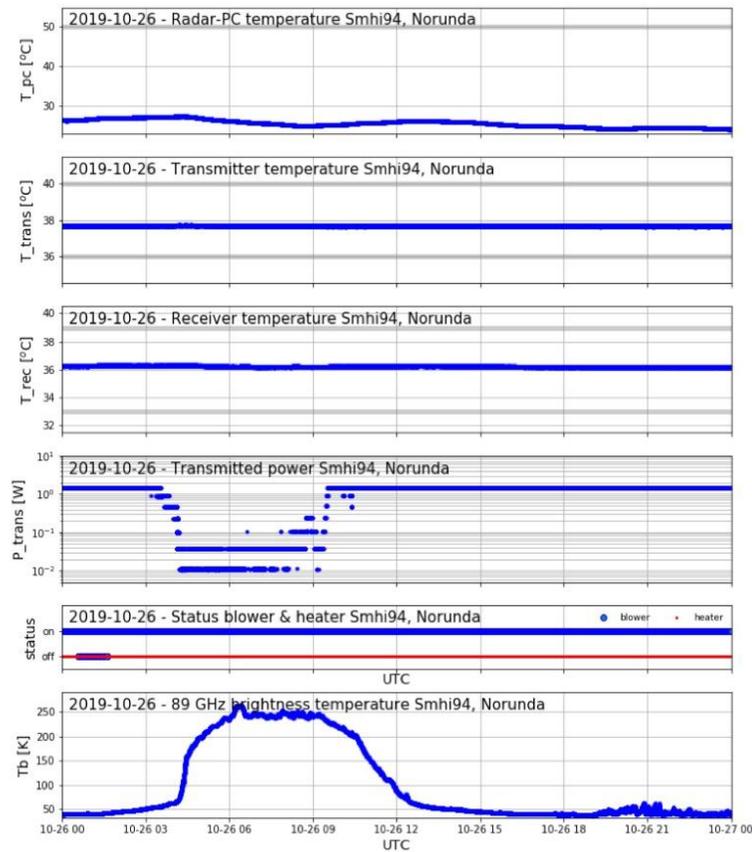
Z_e : Reflectivity
 V_m : Doppler velocity
 S_w : Doppler spectral width
 S_K : Doppler spectrum Skewness
 K : Kurtosis

Radar Quicklook browser / data archive

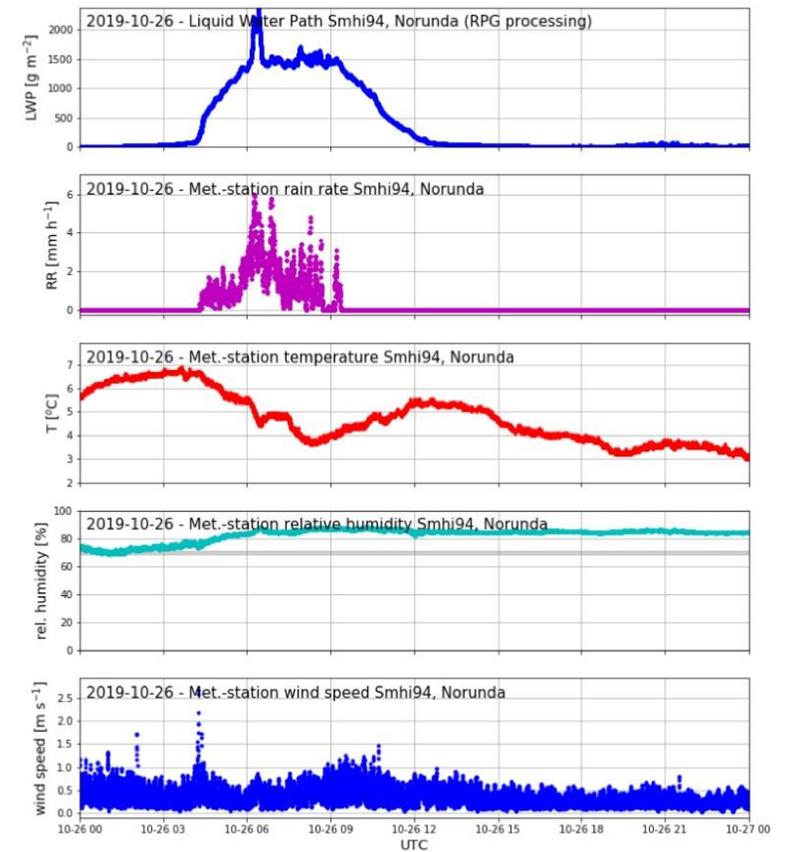
radar overview



radar status



weather station



<https://atmos.meteo.uni-koeln.de/~lpfitzen/dataBrowser/dataBrowser2.html>