



# Using Machine Learning to Identify Air Pollution Plumes from EO Data

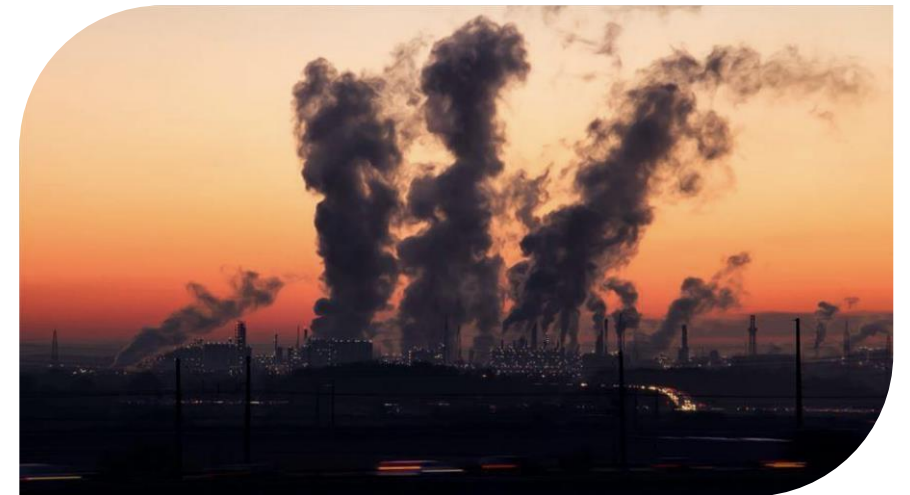
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## Introduction

- Emission inventories can be temporally and geographically crude.
- Satellites can provide information about atmospheric concentrations more quickly than emission inventories are updated
- Can we develop machine learning models to identify pollution plumes, therefore informing us about emissions on a near real time basis?

## Objective

- Develop a database containing plume information for SO<sub>2</sub>, NO<sub>2</sub> and CH<sub>4</sub>



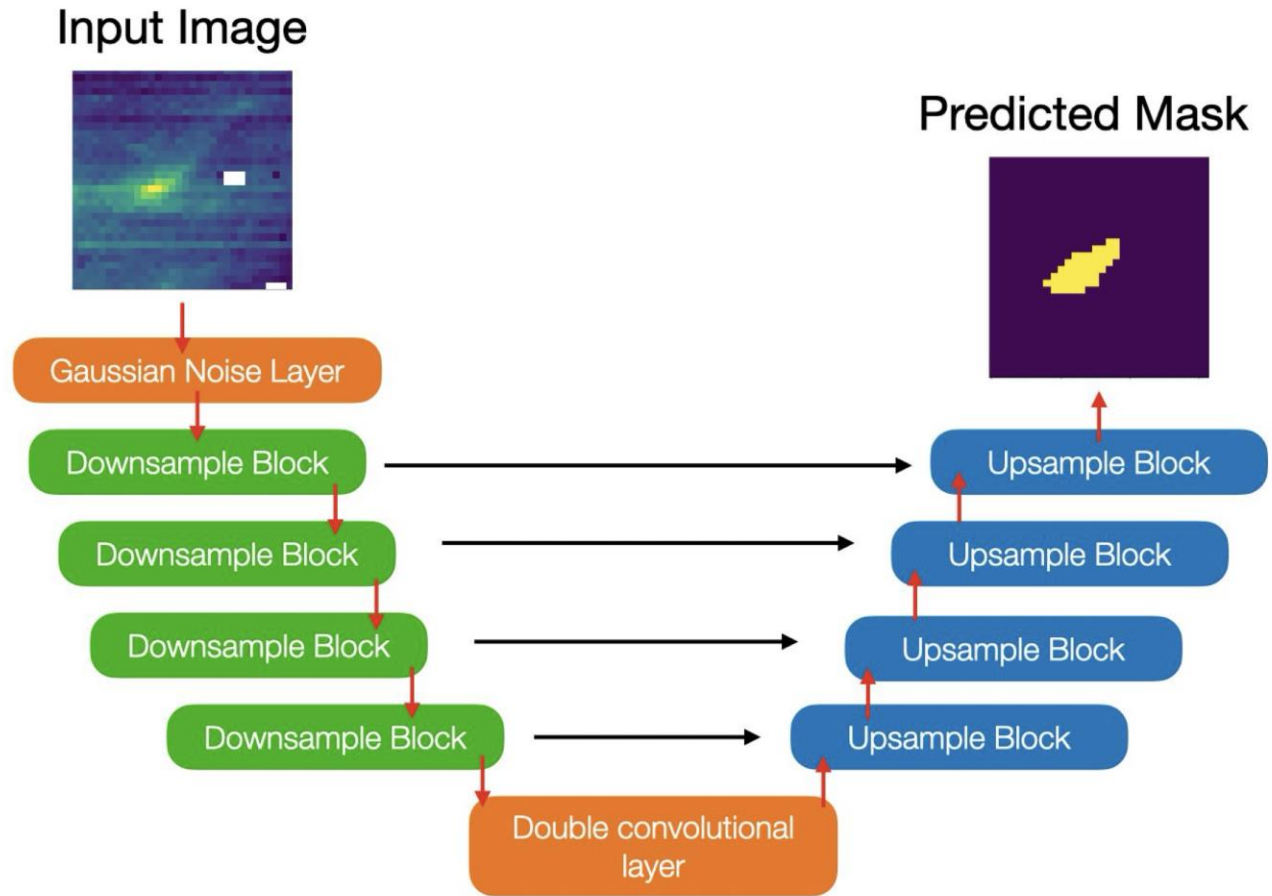
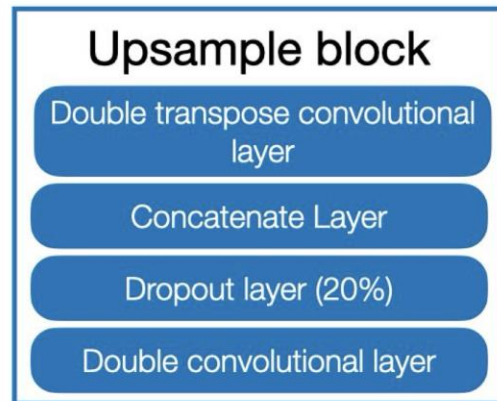
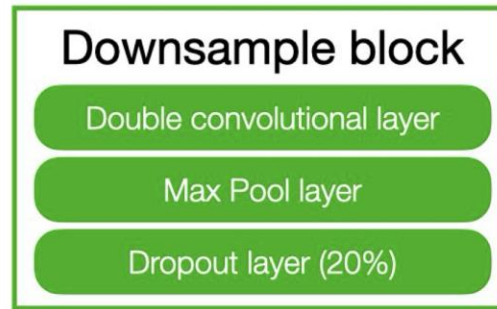
## Data Use

- We use TROPOMI level 2 data to develop three machine learning models (for SO<sub>2</sub>, NO<sub>2</sub> & CH<sub>4</sub>).
- NO<sub>2</sub> & SO<sub>2</sub> products have a spatial resolution of 3.5 x 5.5 km. CH<sub>4</sub> has a resolution of 5.5 x 7.5 km.
- Near global coverage on a daily basis.
- TROPOMI swath is split into 32 x 32-pixel images
- Each image has the standard TROPOMI QA applied and is normalized.



# Developing Plume Detection Models

- All three models are U-Net style with similar architecture
- Allows the model to detect patterns in the image and build a plume mask the same shape as the input image
- The entire TROPOMI swath is rebuilt by merging the predicted masks



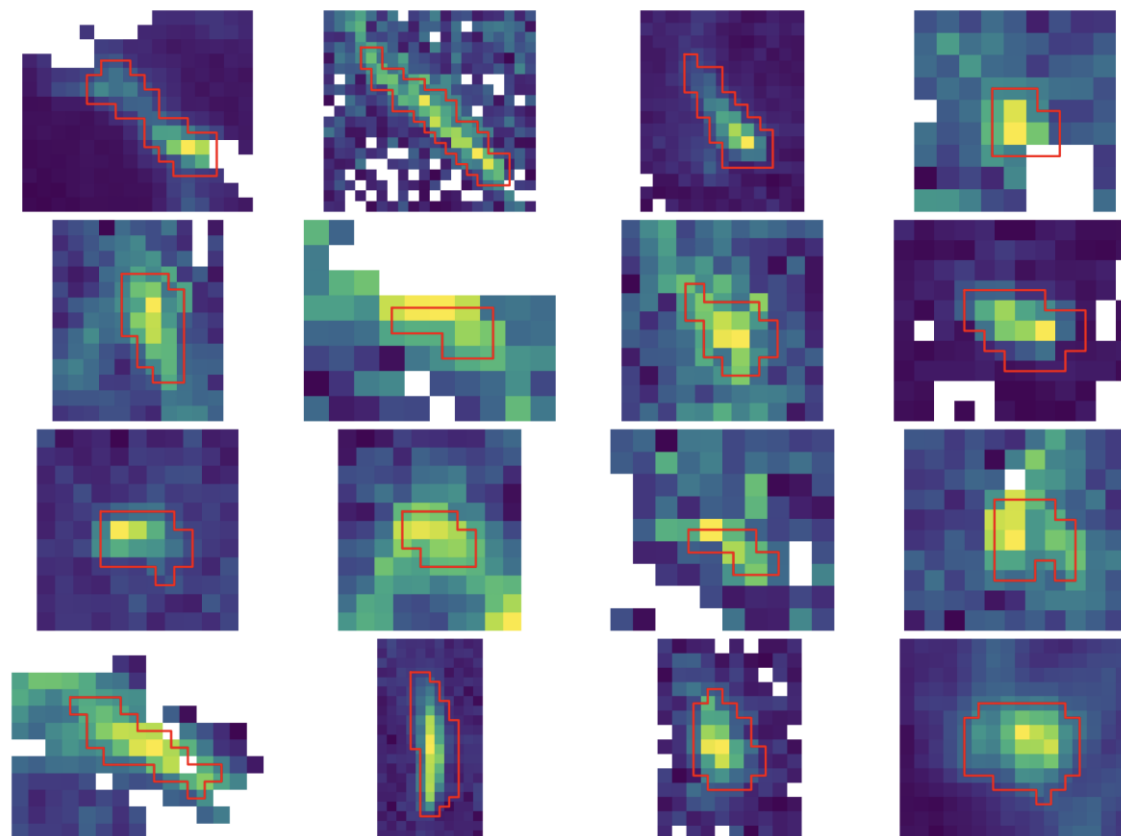
# Model Output

- We store plume location, time, predicted boundary, species concentration and wind data (among other metrics)
- Plumes can be nearly any shape or size (some filters applied)
- Ran the detection model from May 2018 – July 2023

Species	Number of Plumes
SO <sub>2</sub>	67,317
CH <sub>4</sub>	8,057
NO <sub>2</sub>	116,743*

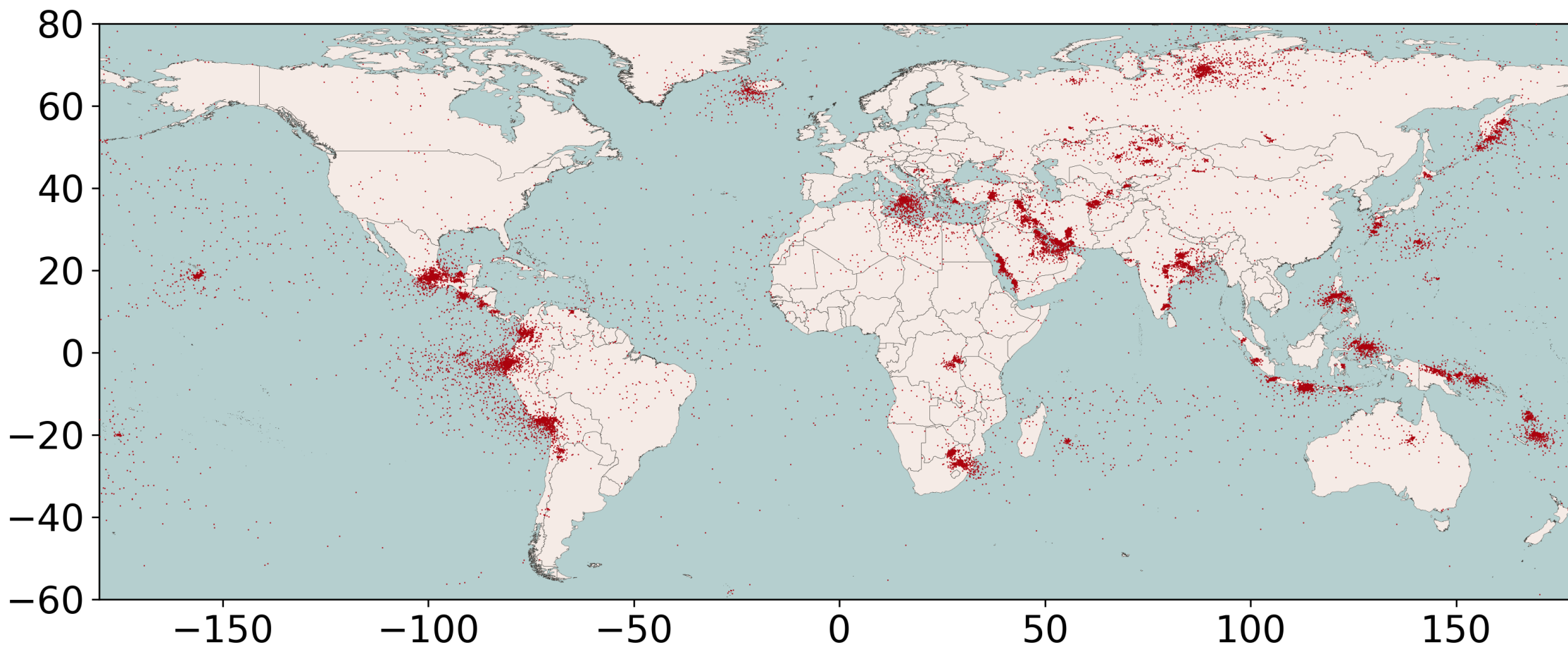
(\*Only 2021)

Example plumes and masks



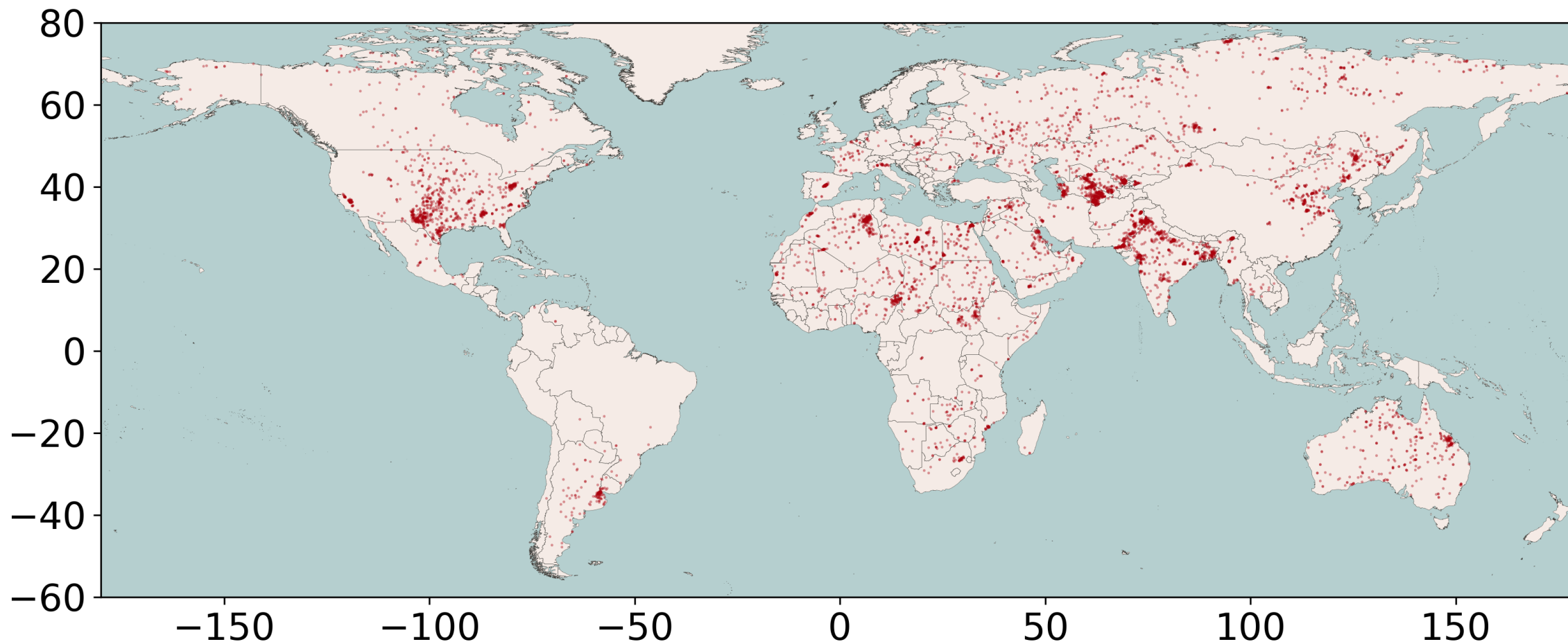
# SO<sub>2</sub> Global Map

Precision: 0.81 Recall: 0.79



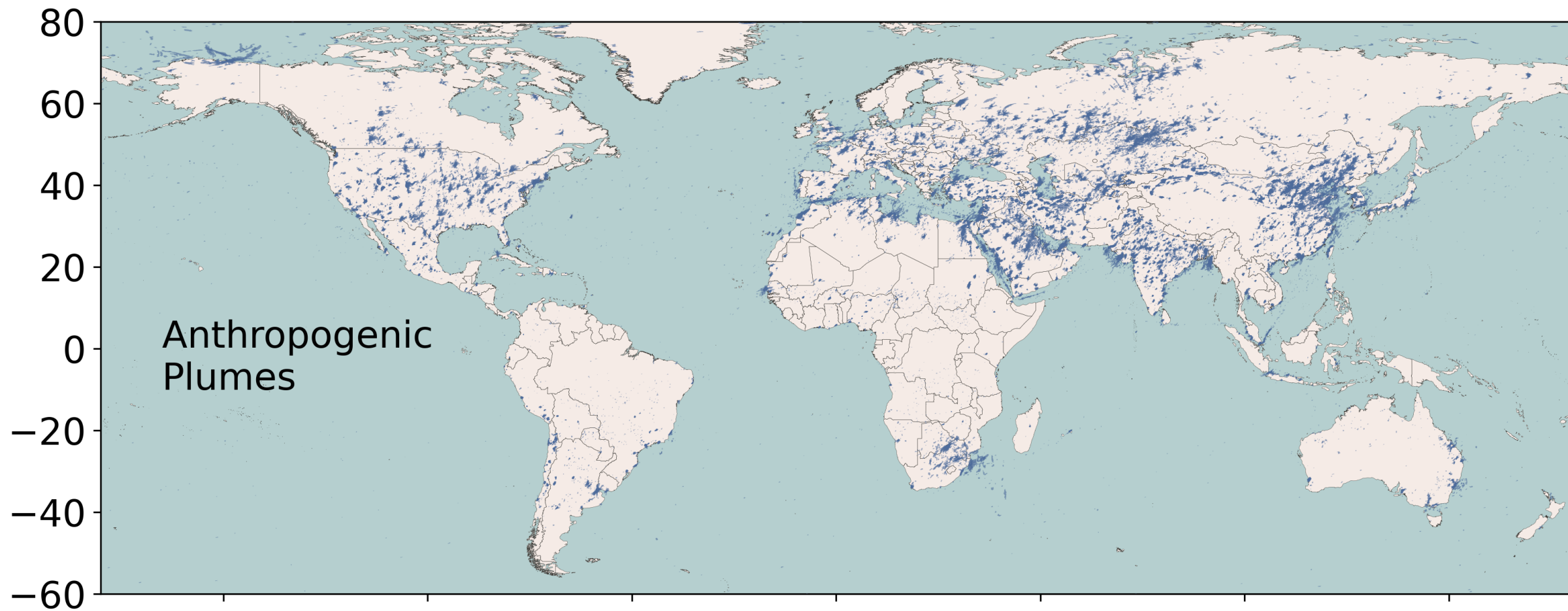
# CH<sub>4</sub> Global Map

Precision: 0.74 Recall: 0.74



# NO<sub>2</sub> Global Map

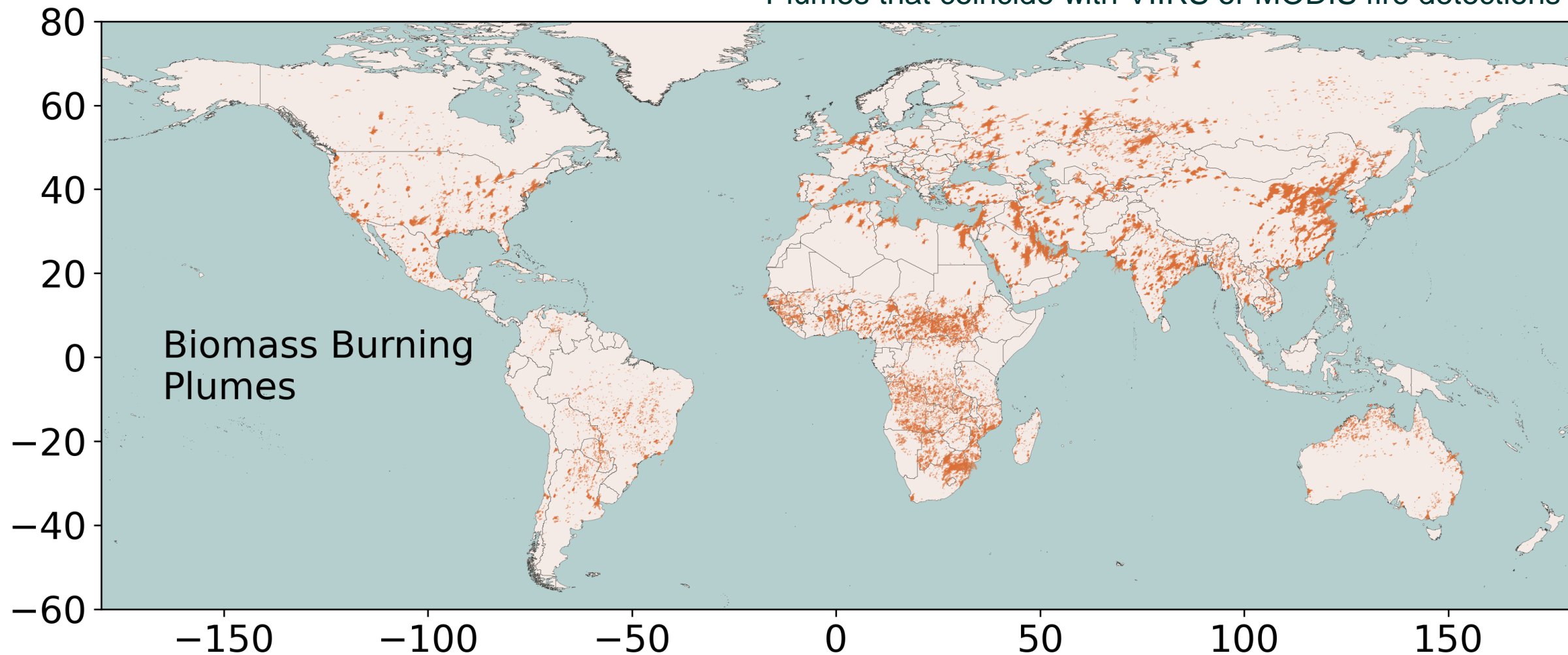
Precision: 0.77 Recall: 0.75





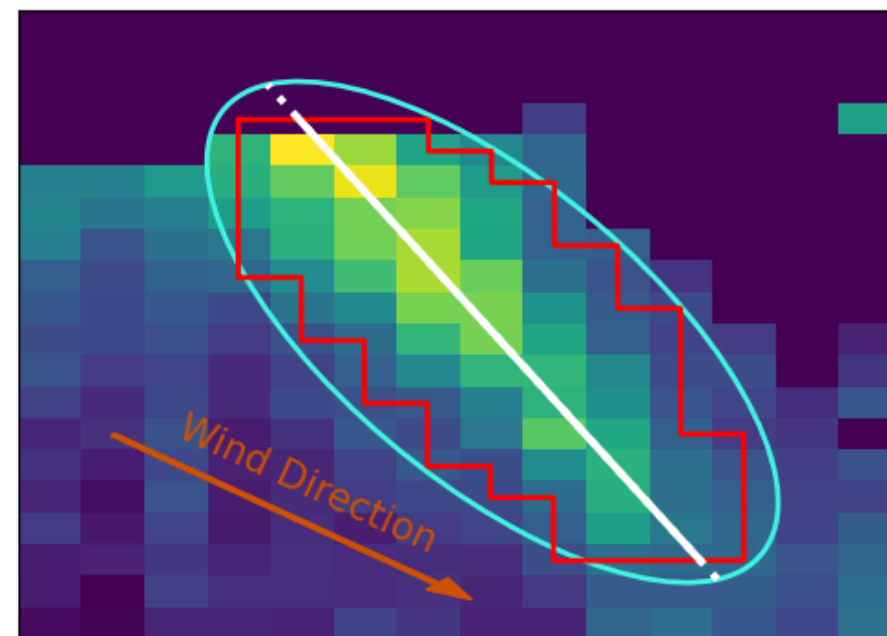
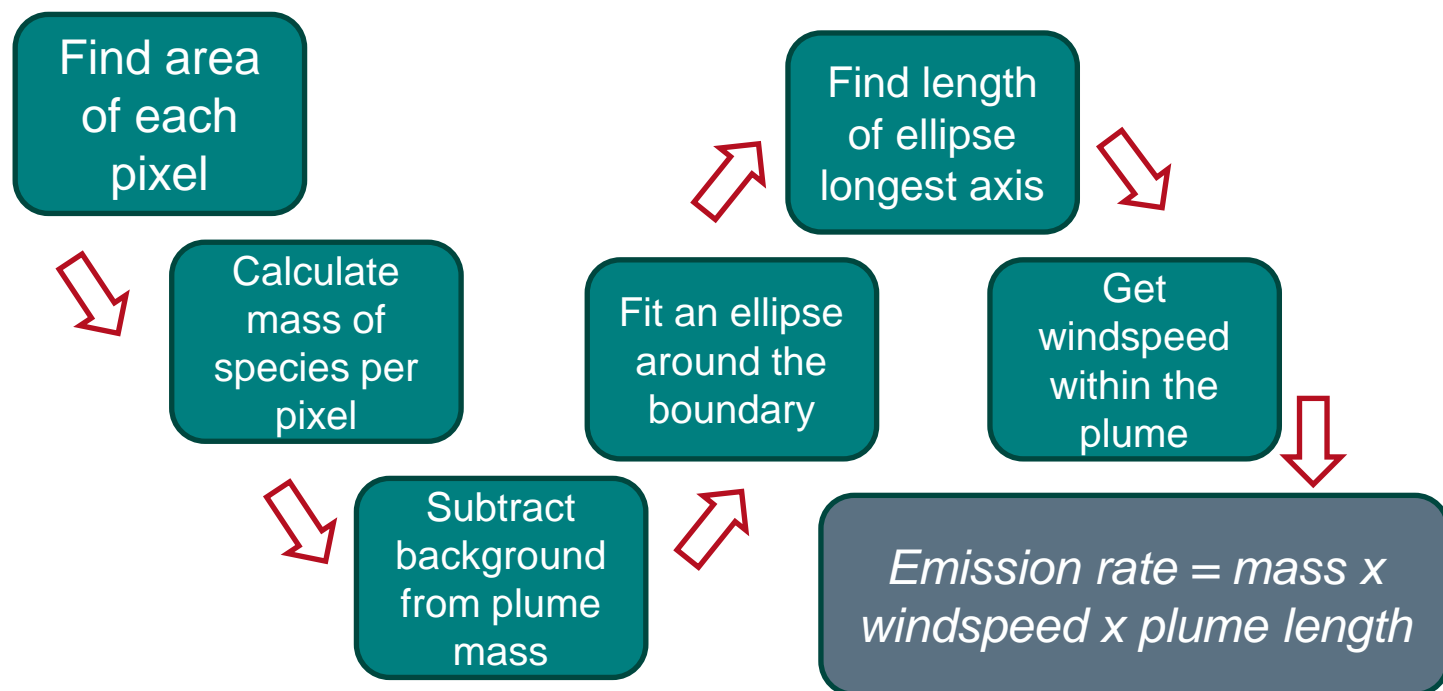
# NO<sub>2</sub> Global Map

Plumes that coincide with VIIRS or MODIS fire detections



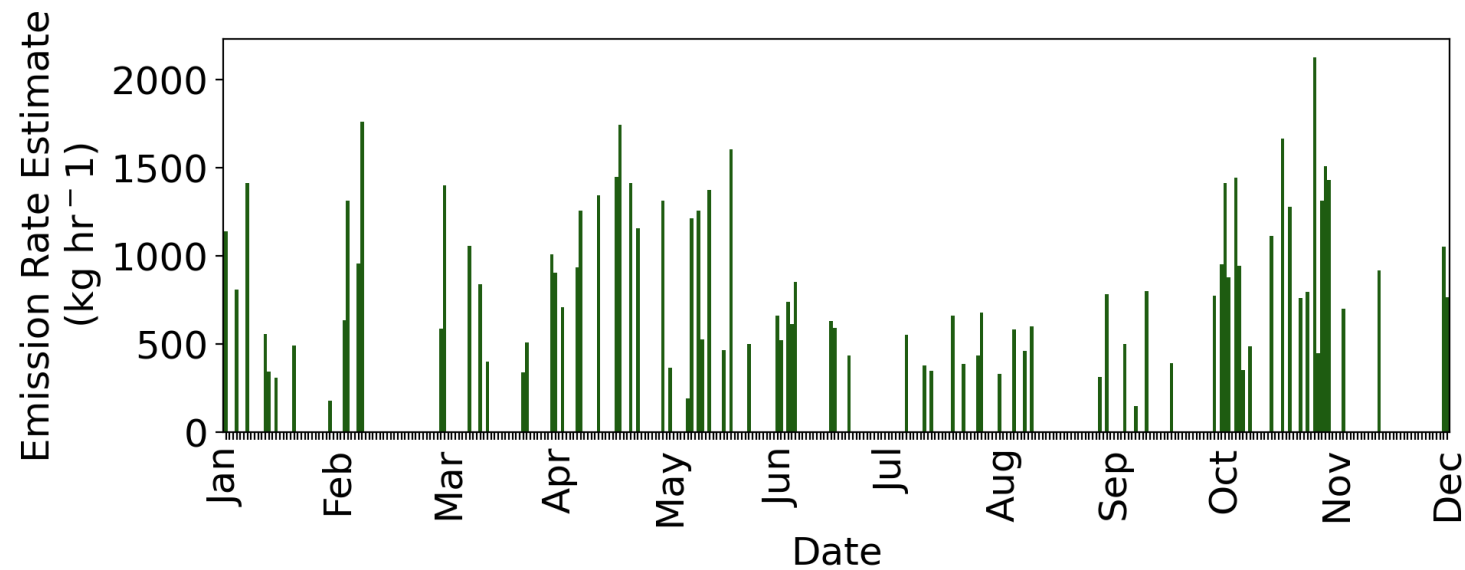
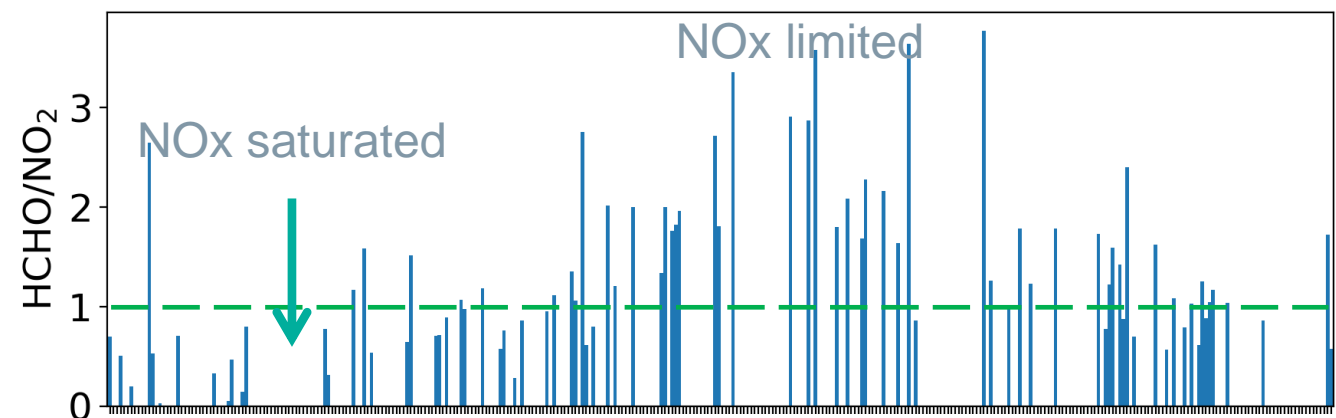
# Estimating Emission Rates

- We can estimate an emission rate associated with each plume based on the predicted boundary and wind data
- Wind data used is 10 m U & V wind fields from ECMWF (included in the TROPOMI files)

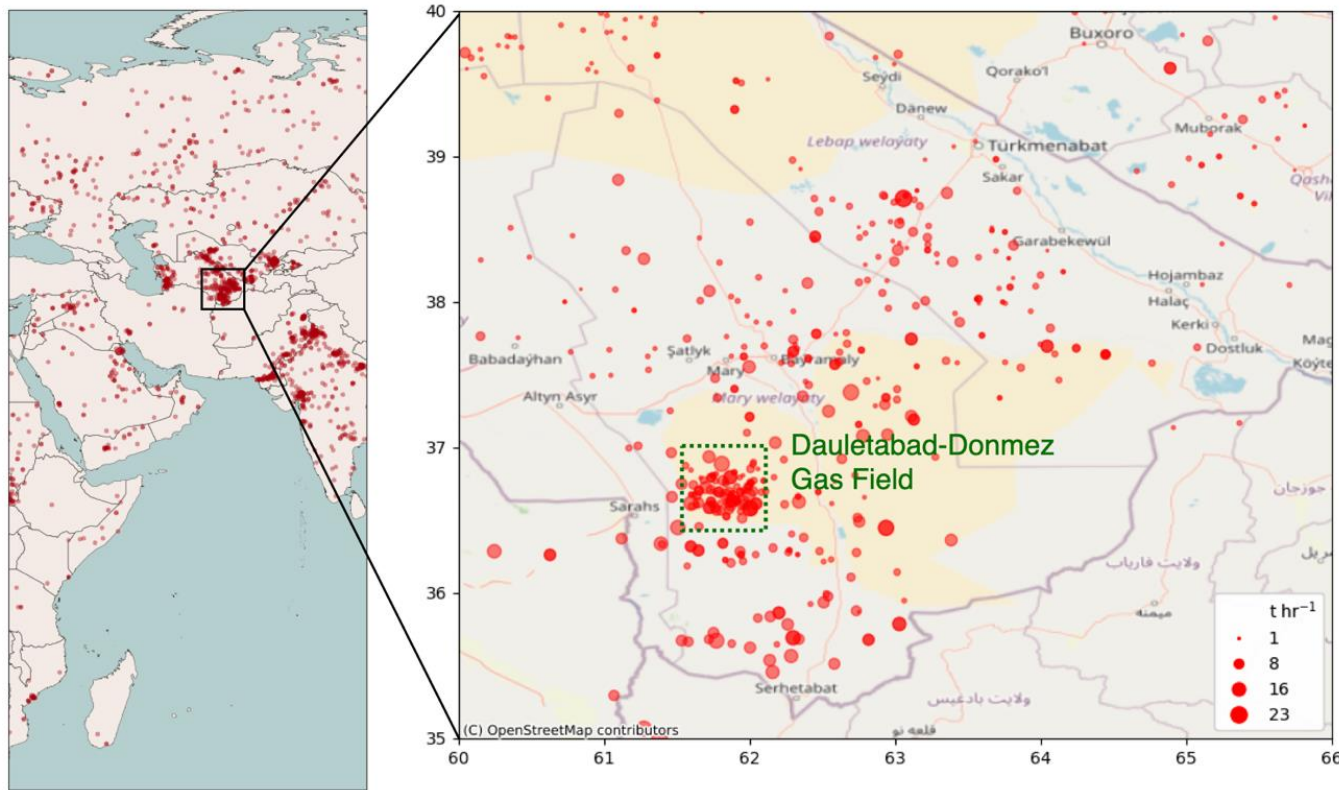


## Case Study – HCHO:NO<sub>2</sub> Ratios

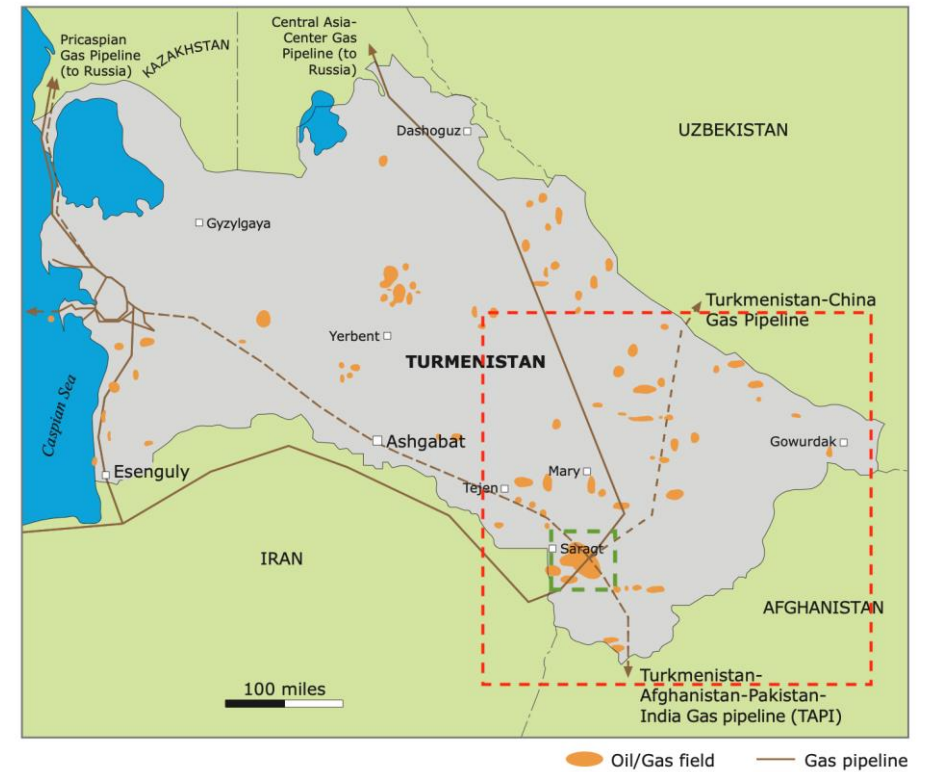
- HCHO:NO<sub>2</sub> ratio can tell us about the photochemical environment
- HCHO values can be extracted from plume locations
- 86 plumes over Alexandria, Egypt – large port
- The larger the emission rates (possibly more shipping emissions?) increases the HCHO:NO<sub>2</sub> ratio



# Case Study – CH<sub>4</sub> from Oil Fields



Turkmenistan Oil and Gas Fields

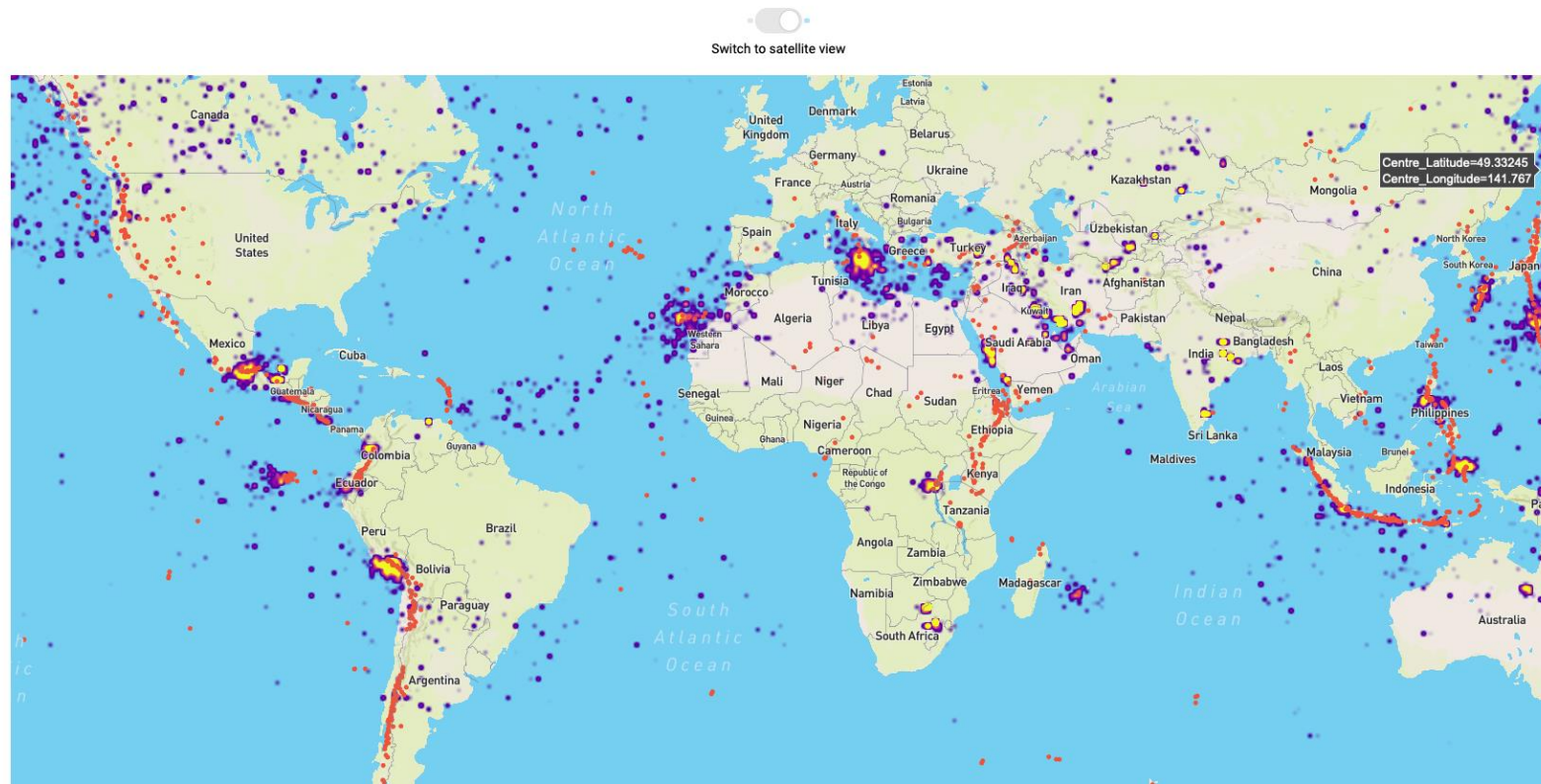


- We can see clusters of methane plumes from a known oil field in Turkmenistan.
- Although there is also noise about, some of it lines up with other smaller oil fields

# Data Availability – eoplumes.com

## Sulphur Dioxide Plume Map

This map shows the initial results for the SO<sub>2</sub> plume found through the model. Volcanoes are shown in red. Improvements to this model are ongoing to refine the plume location and filter erroneous results.

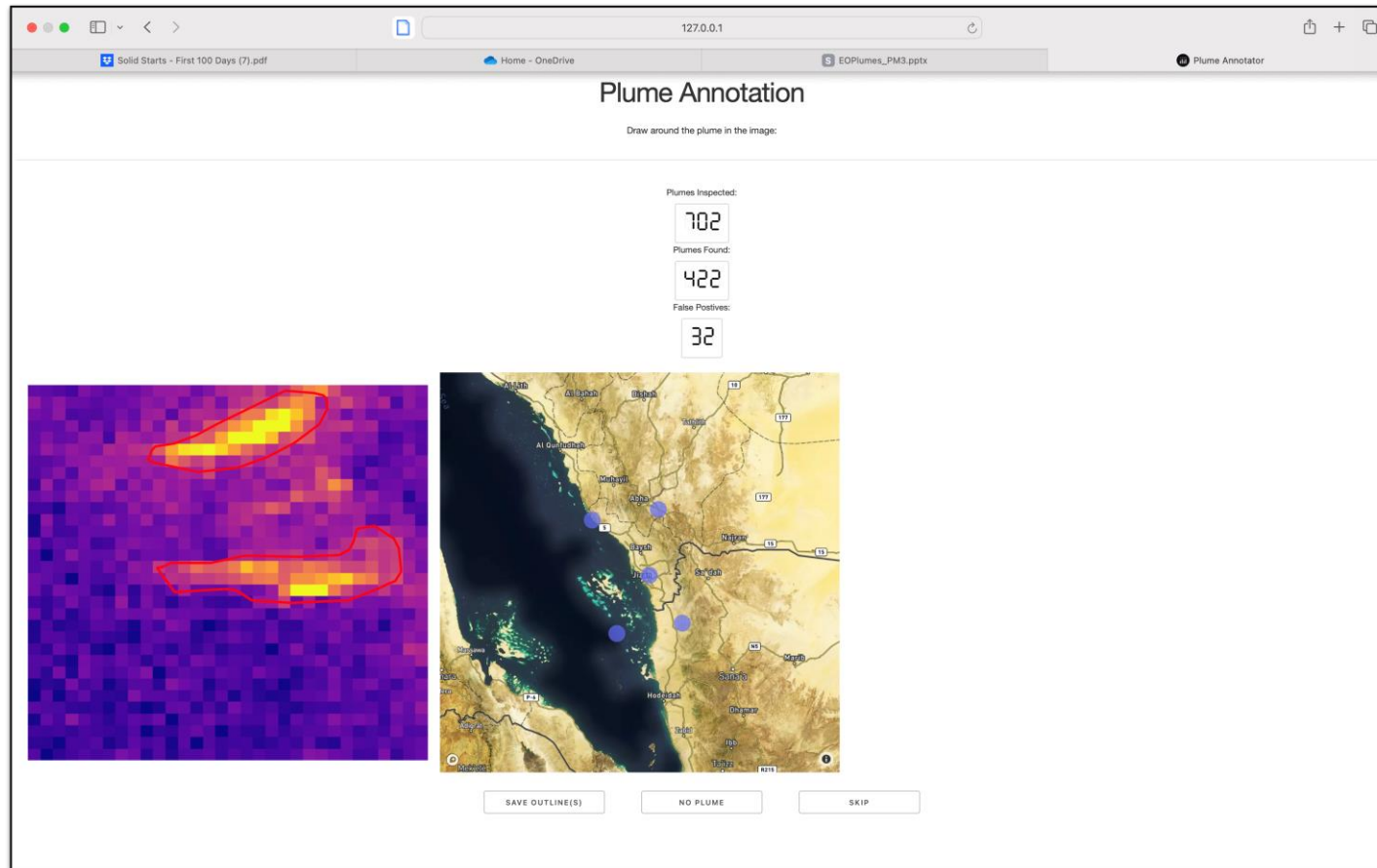


- All this data will be available on our project website
- Site is currently out-of-date
- Latest data will be published later in the year
- Zoomable maps, quick look statistics and downloadable data will be available



# Extra slides

# Plume Labelling

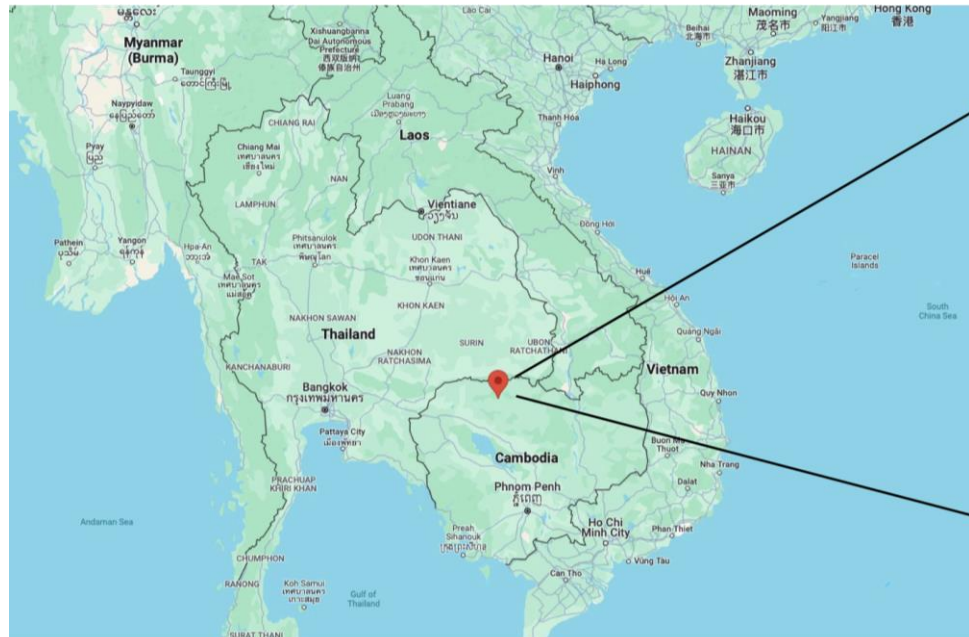


- Created an app to run locally
- Went through images and draw round plume shapes
- Showed location of plume alongside image as a sanity check
- Saved drawn outline as binary mask for model training

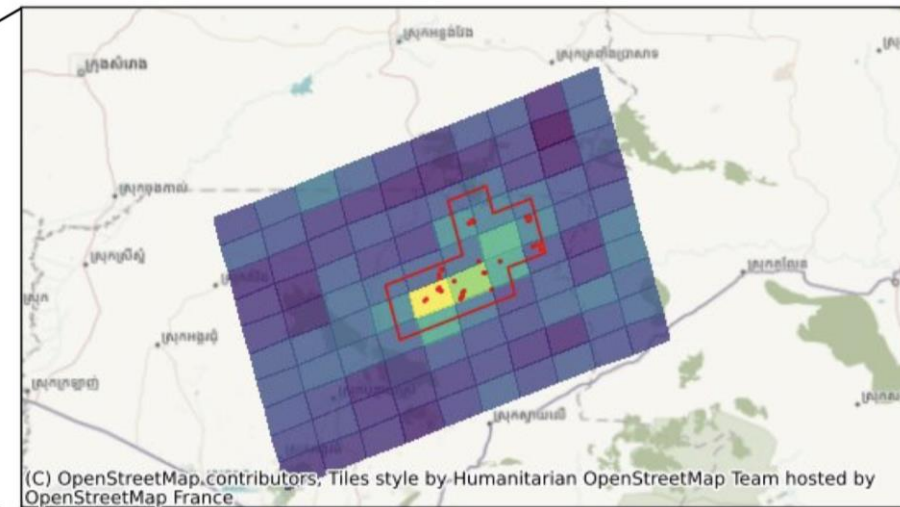


# Separating Biomass Burning

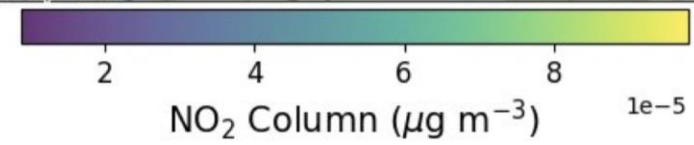
- Where a plume boundary contains a detected fire from VIIRS or MODIS on the same day – classify as BB



Red dots are VIIRS fire detections



(C) OpenStreetMap contributors, Tiles style by Humanitarian OpenStreetMap Team hosted by OpenStreetMap France



## Detection Limits (NO<sub>2</sub>)

- Model works on shapes and gradients and therefore relies on how well a plume stands out from the background, not absolute concentration
- We can compare the median background to the median concentration within the plume to get an idea of normal plume enhancement

Minimum enhancement = 3% enhancement  
 1st percentile enhancement = 16% enhancement

