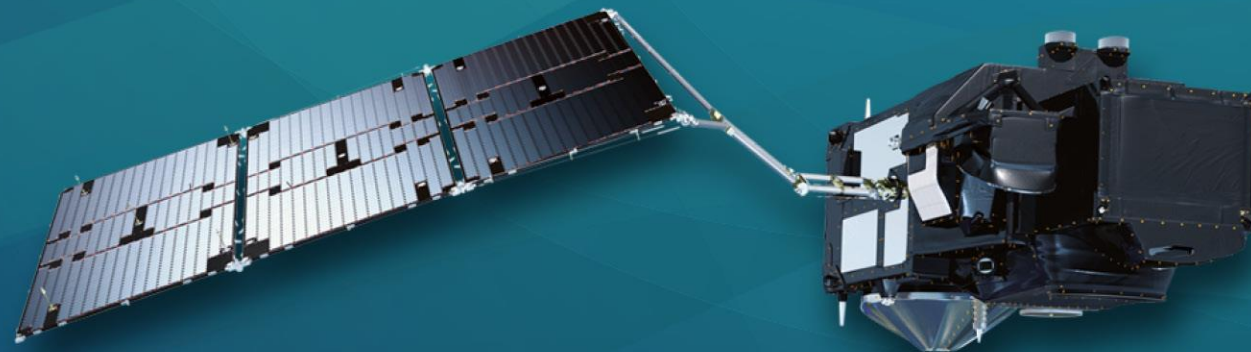




PROGRAMME OF THE  
EUROPEAN UNION



co-funded with



# 9<sup>th</sup> Sentinel-3 Validation Team meeting 2026

30 March–01 April 2026 | ESA–ESRIN | Frascati (Rome), Italy

## FRMOCnet: Empowering Ocean Colour Data Collection

*Presenter: Riho Vendt, University of Tartu  
FRM4SOC Team*

- *University of Tartu* Riho Vendt, Krista Alikas, Ilmar Ansko, Kim Duong, Joel Kuusk, Martin Ligi, Viktor Vabson,
- *ACRI-ST* Christophe Lerebourg, Alexis Deru, Gabriele Bai, Marine Bretagnon
- *Brockmann Consult GmbH* Carsten Brockmann, Uwe Lange, Sabine Embacher, Benjamin Lutz
- *Consiglio Nazionale delle Ricerche (CNR)* Vittorio Brando
- *EOScience* Giuseppe Zibordi
- *National Physical Laboratory (NPL)* Agnieszka Bialek, Ashley Ramsay
- *Plymouth Marine Laboratory (PML)* Gavin Tilstone, Thomas Jordan
- *Royal Belgian Institute for Natural Sciences (RBINS)* Kevin Ruddick, Heloïse Lavigne
- *Istituto Nazionale di Oceanografia e di Geofisica Sperimentale (OGS)* Giorgio Dall'Olmo
- *NASA* Dirk Aurin
- *EUMETSAT* Juan I. Gossn, Ewa Kwiatkowska



UNIVERSITY OF TARTU  
Tartu Observatory



BROCKMANN  
CONSULT GMBH



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*“Earth Observation data without proper calibration and uncertainty assessment has little value for most applications, because if the data cannot be trusted, no reliable information can be derived from them.”*

**FRM – A suite of independent, fully characterised, and traceable (to a community agreed reference, ideally SI) measurements of a satellite relevant measurand, tailored specifically to address the calibration/validation needs of a class of satellite borne sensors, and following the guidelines outlined by the GEO/CEOS Quality Assurance framework for Earth Observation (QA4EO)**



$$u_c^2(y) = \sum_{i=1}^N \left( \frac{\partial f}{\partial x_i} \right)^2 u^2(x_i) + 2 \sum_{i=1}^{N-1} \sum_{j=i+1}^N \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j} u(x_i, x_j)$$



Goryl, P.; Fox, N.; Donlon, C.; Castracane, P. Fiducial Reference Measurements (FRMs): What Are They? Remote Sens. 2023, 15, 5017.

# FRM4SOC – Fiducial Reference Measurements for Satellite Ocean Colour

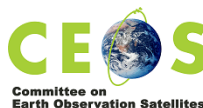


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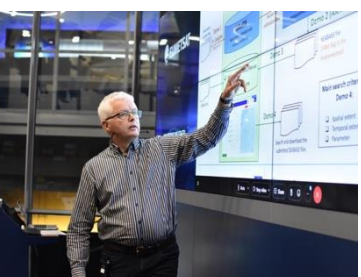


EUMETSAT

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$$u_c^2(y) = \sum_{i=1}^N \left( \frac{\partial f}{\partial x_i} \right)^2 u^2(x_i) + 2 \sum_{i=1}^{N-1} \sum_{j=i+1}^N \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j} u(x_i, x_j)$$



fiducial reference measurements for satellite ocean colour



## 2016 – 2019 FRM4SOC Phase 1



- Funded and coordinated by ESA
- Foundations to achieve FRM quality in the Ocean Colour (OC) domain
- <https://frm4soc.org>



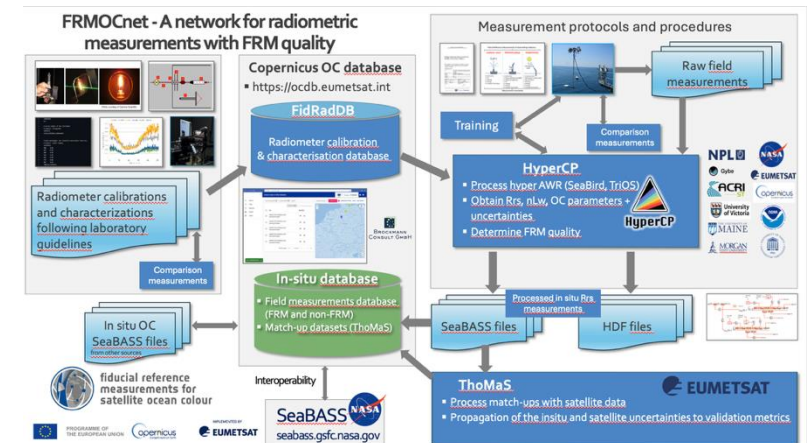
## 2021 – 2026 FRM4SOC Phase 2

- *Funded by the EU Copernicus Program and coordinated by EUMETSAT*
- *Promote the adoption of FRM principles across the OC community*
- *Develop foundations for operational implementation of the FRM principles by the OC community (in situ hyperspectral radiometry)*
- *Verify and demonstrate the operations of the FRM in the community framework*

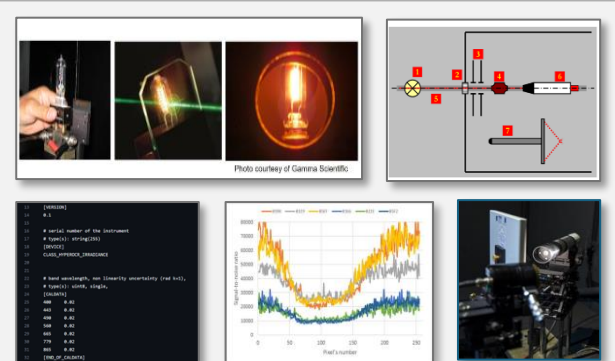
<https://frm4soc2.eumetsat.int/>

## FRMOCnet

- Joint outcome of the FRM4SOC-2 project tasks.
- Network of FRM quality instruments and measurements.
- Implements the FRM principles in the Ocean Colour domain and empowers collection of quality field data.
- Joins and supports the OC community via training, workshops, instruments, and calibration.



# FRMOCnet - A network for radiometric measurements with FRM quality



Radiometer calibrations and characterisations following laboratory guidelines

Comparison measurements

## Copernicus OC database

- <https://ocdb.eumetsat.int>

**FidRadDB**

Radiometer calibration & characterisation database

**In-situ database**

- Field measurements database (FRM and non-FRM)
- Match-up datasets (ThoMaS)

## Measurement protocols and procedures

Fiducial Reference Measurements for Downwelling Irradiance

Measurement uncertainty

Raw field measurements

Training

Comparison measurements

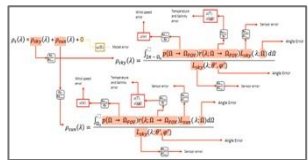
**HyperCP**

- Process hyper AWR (SeaBird, TriOS)
- Obtain  $R_{rs}$ ,  $nL_w$ , OC parameters + uncertainties
- Determine FRM quality

Processed in situ  $R_{rs}$  measurements

SeaBASS files

HDF files



In situ OC SeaBASS files from other sources

fiducial reference measurements for satellite ocean colour

Interoperability

**SeaBASS**

[seabass.gsfc.nasa.gov](http://seabass.gsfc.nasa.gov)

**ThoMaS**

- Process match-ups with satellite data
- Propagation of the insitu and satellite uncertainties to validation metrics



1 NASA  
Goddard Space  
Flight Center



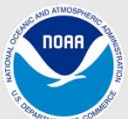
2 Morgan State  
University



5 University of  
Victoria

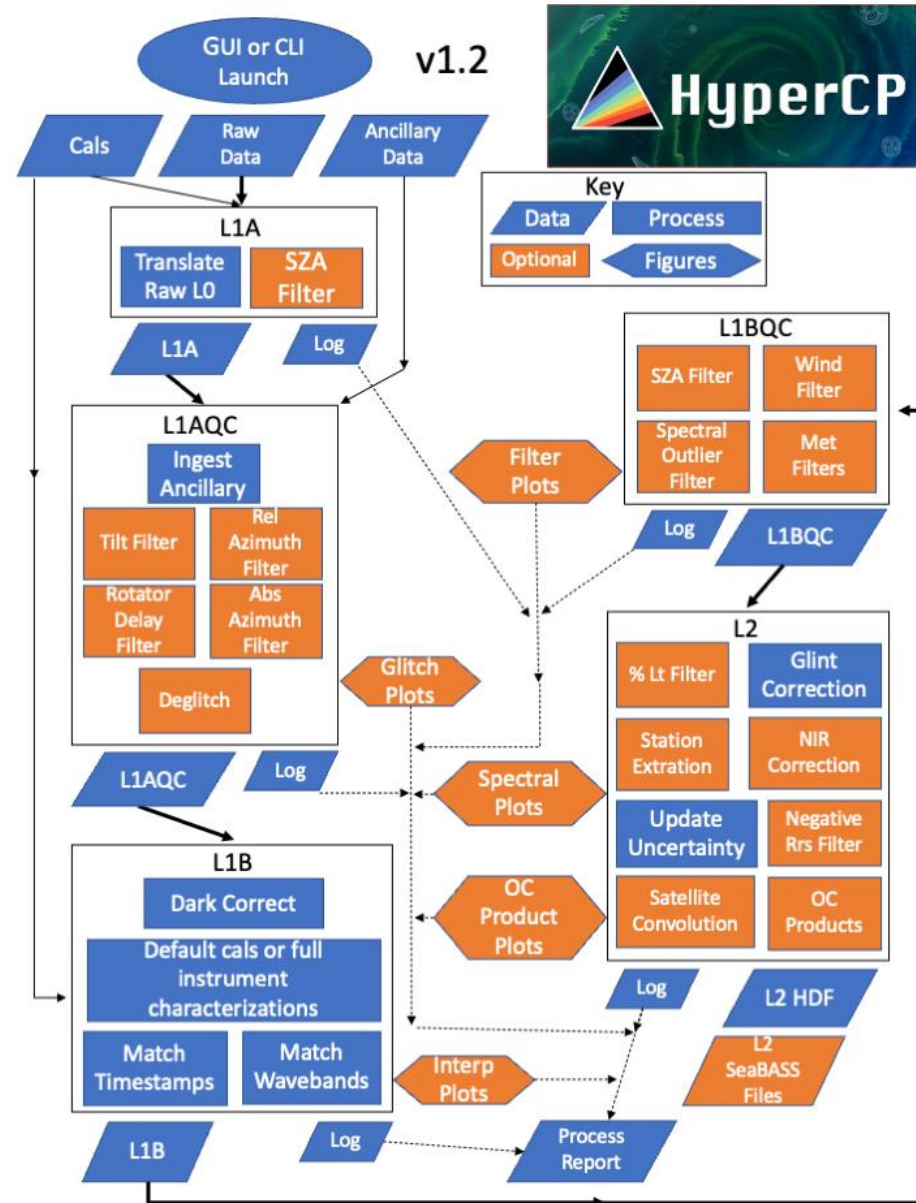
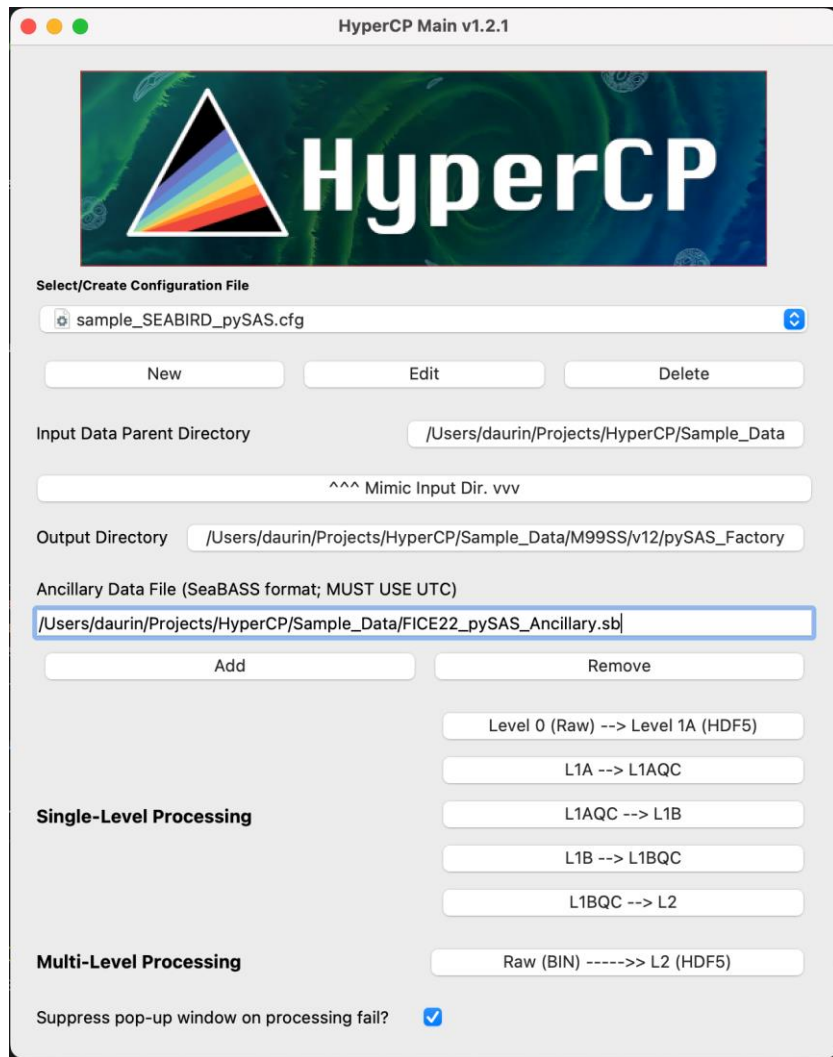


7 National  
Physical  
Laboratory  
(UK)



10 NOAA NMFS

<https://github.com/nasa/HyperCP>



3 EUMETSAT



4 Copernicus  
Programme of  
European  
Commission



6 ACRI-ST



8 University of  
Maine



8 University of Tartu



9 Gybe Inc.

Funding from NASA PACE Mission and Copernicus FRM4SOC-2 Initiative

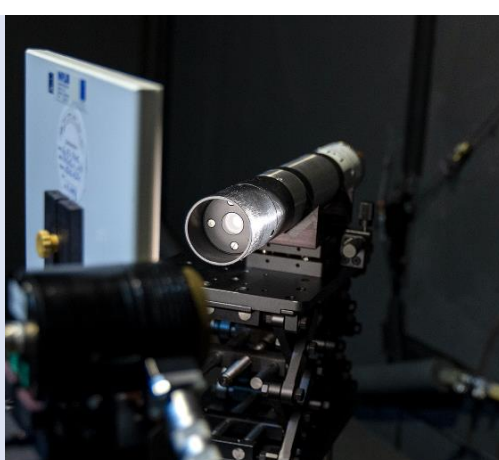


## FRM4SOC-2 Project Workshop

04.12.2022

**5 – 7 December 2022**  
**EUMETSAT,**  
**Darmstadt, Germany**

At this workshop, we present the most important outcomes from the FRM4SOC phase project and seek for agreement in the community through discussions.



## FRM4SOC Phase 2 laboratory comparison

14.03.2022

The absolute radiometric calibration comparisons will be implemented through a round-robin comparison of each participant's irradiance and radiance calibration capability using ocean colour transfer radiometers.

## Field InterComparison Exercise (FICE)

11-20 July 2022,

at **Acqua Alta Oceanographic Tower (AAOT), Venice, Italy.**

Comparison of  $L_{\lambda}$ ,  $L_{\lambda}^w$ ,  $E_d$ ,  $R_{rs}$ ,  $L_{wn}$

Critical review, testing, and feedback on

- Measurement protocols/procedures
- Community processor
- FRMOCnet
- Application of instrument characterisation

Validation of

- SI traceability;
- Uncertainty budgets;
- Aimed uncertainty levels.

**Participants:** CNR-ISAC, Helmholtz Center Hereon, NASA, NOAA, PML, RBINS, UT

**Instruments:**

Above water (7): TRIOS RAMSES, TriOS RAMSES G2 sun tracker (SoRAD), Seabird HyperOCR HyperSAS with PySAS robot, HYPSTAR, PANTHYR.

In-water (2): Sea-Bird HyperPro II, TriOS RAMSES floating buoy.



**PML** Plymouth Marine Laboratory



## The second FRM4SOC-2 WORKSHOP

on Calibration and Characterisation of Ocean Color Field Radiometers

**Second FRM4SOC Workshop on Calibration and Characterisation of Ocean Colour Field Radiometers**

30.06.2025

[Click here for the details and agenda.](#)

20 – 22 May 2025

@ Tartu Observatory, University of Tartu, Estonia

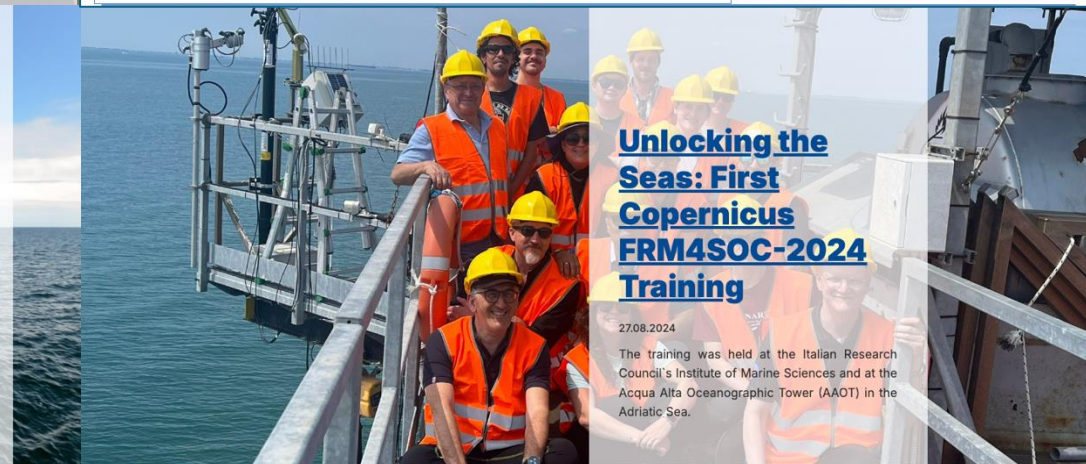


## Short-term use of Ocean Colour radiometric system. Free calibration of your own radiometers.

11.04.2024

The application period has ended.

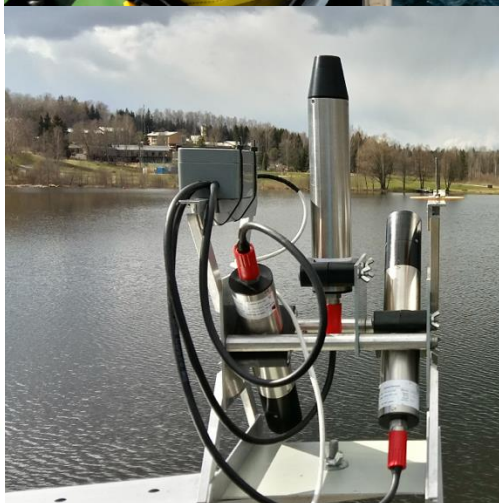
Opportunity to apply for the



## Unlocking the Seas: First Copernicus FRM4SOC-2024 Training

27.08.2024

The training was held at the Italian Research Council's Institute of Marine Sciences and at the Acqua Alta Oceanographic Tower (AAOT) in the Adriatic Sea.



## Short-term (free) rental of an Ocean Colour radiometric system. Free calibration of your own radiometers - SECOND CALL

27.01.2025

SECOND CALL (closed)



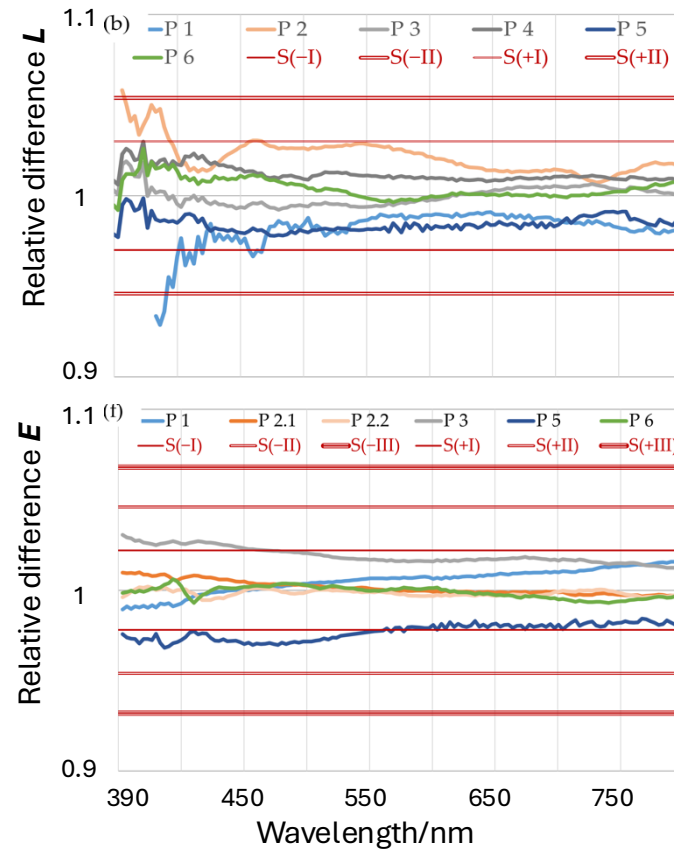
## Advanced training to support the use of fiducial reference measurements for satellite ocean colour validation

07.01.2026

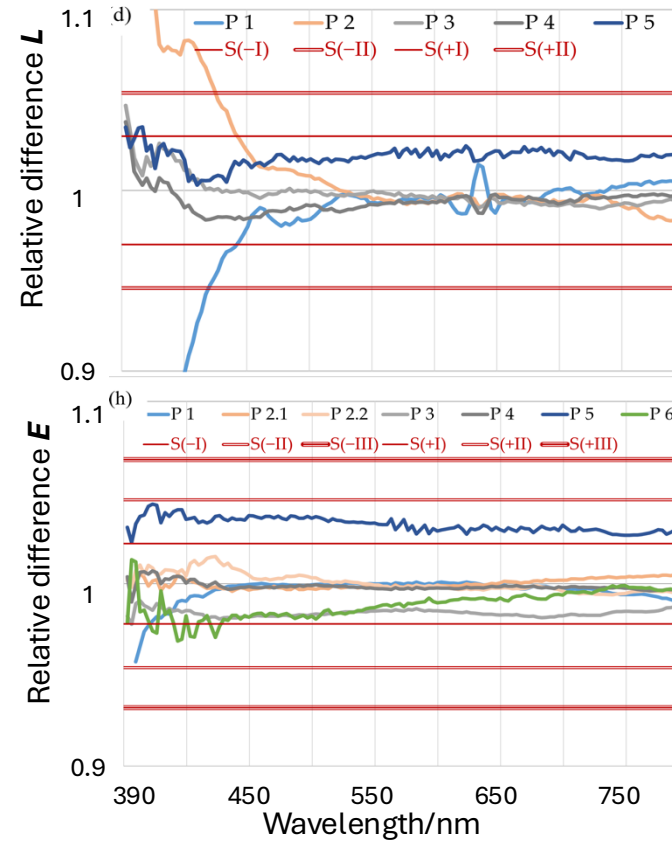
The Second EU Copernicus FRM4SOC Training for in situ Ocean Colour Above-Water Radiometry towards Satellite Validation was held in Venice from 6 to 20 July 2025.

Vabson, et al. 2025, Remote Sens. MDPI, 17, 3692.

### TriOS Ramses



### Seabird HyperOCR



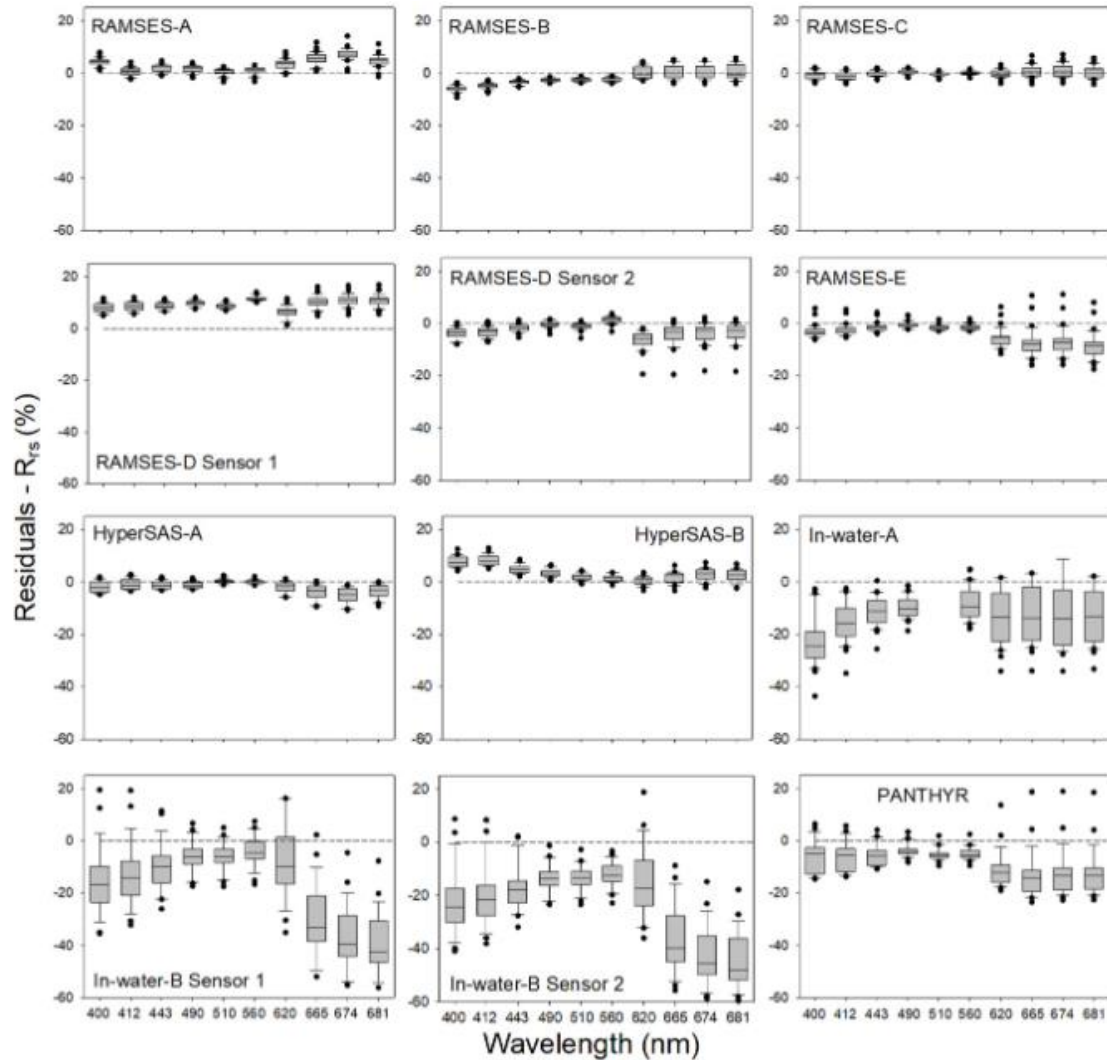
The relative difference from CCV of  $L$  and  $E$  sensors. Agreement among participants within  $\pm 3\%$

# FRM4SOC 1 & 2. Field inter-comparison results.

FRM4SOC 1.

Percent residuals of Rrs for above- and in-water systems.

*Tilstone et al. 2020, Remote Sens. MDPI, 12, 1587.*

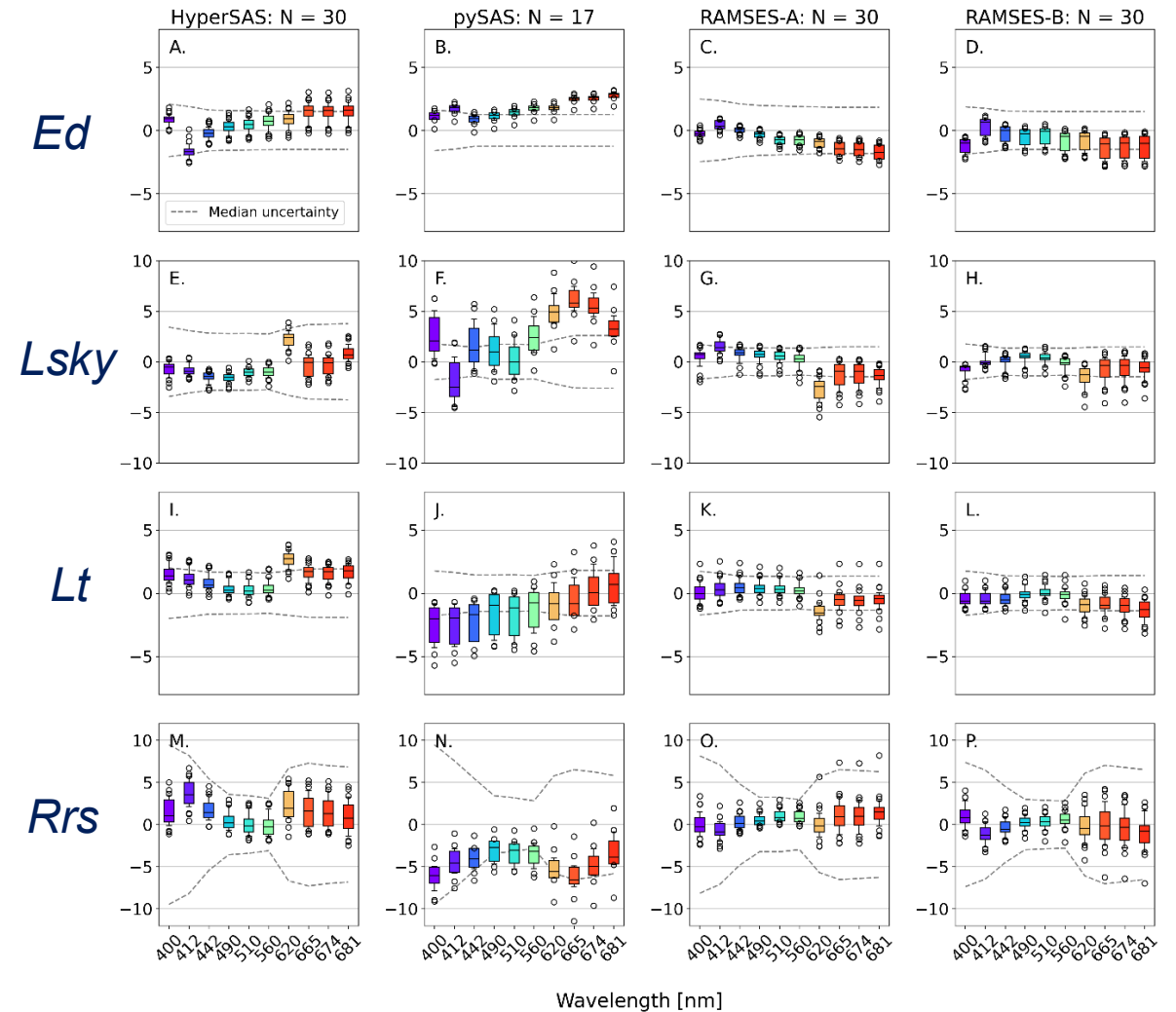


Differences between TriOS RAMSES were <3.5%, <2.5%, <7.5%; for Sea-Bird HyperSAS were 3.5%, 1%, 3% at 443, 560, 665 nm.

FRM4SOC 2.

Percent residuals compared to the mean of all systems.

*Tilstone et al. 2025, Optics Express, 33, 15756-15781.*



Differences in  $Ed(\lambda)$ ,  $Lsky(\lambda)$ ,  $Lt(\lambda)$  &  $Rrs(\lambda)$  between instrument systems was <2.5% using Sensor-specific characteristics.

**Instrument pool** – fully operational, calibrated and characterised system (TriOS Ramses) kindly provided by JRC,

- **(Free) short-term rental for**
  - 2 campaigns in 2024.
  - 2 campaigns in 2025
  - **New call expected in 2026**
- **Project-supported calibrations**
  - 4 sets of radiometers in 2024.
  - 4 sets of radiometers in 2025
  - **New call expected in 2026**



- FRM4SOC Phase-2 – EUMETSAT project no. EUM/CO/21/460002539/JIG
- ESA Estonia research infrastructure funded by the Estonian Research Council grant TARISTU24-TK3.
- Estonian Research Council grant PRG2646 “Methods, Traceability and Validation of the In-Water Ocean Color Measurements”.

Contact: <https://frm4soc2.eumetsat.int/>