

# Direct FE<sup>2</sup> – Concurrent multiscale modelling with commercial finite element codes

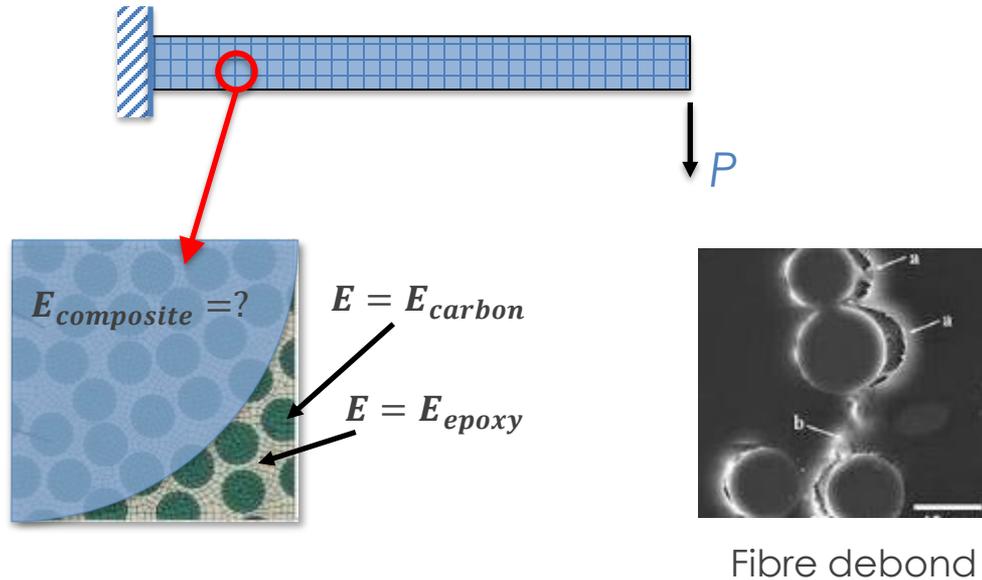
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# Introduction

## What is FE<sup>2</sup> ?

- A two-scale finite element analysis of structures of heterogeneous materials.
- Traditionally implemented when
  - the constitutive property of heterogeneous material is unavailable, or
  - microstructural changes during loading affect constitutive property
- Comprises macroscale FEA of structure with many microscale FEA of unit cells/RVEs to obtain homogenized properties



# Single scale FEA

Static stress analysis

$$\sigma_{ij,j} + b_i = 0$$

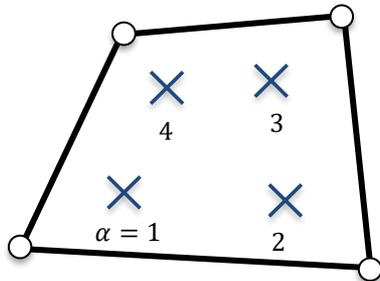
$$\Rightarrow \underbrace{\int_V \delta \varepsilon_{ij} \sigma_{ij} dV}_{\delta W_{int}} = \underbrace{f_I \delta u_I}_{\delta W_{ext}}$$

Numerical integration

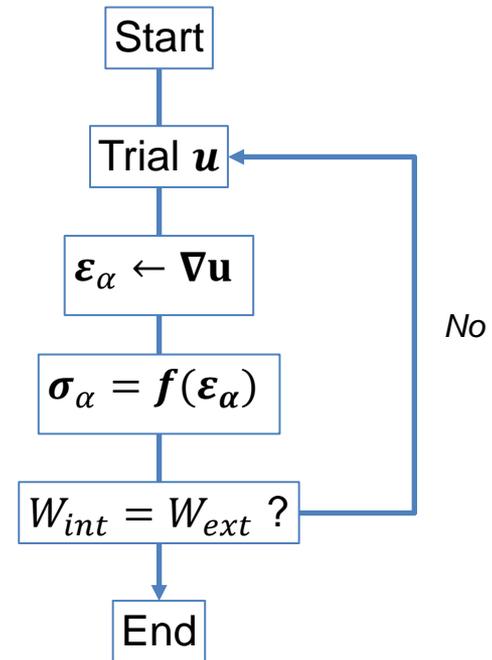
$$\Rightarrow \delta W_{int} = \sum_{\alpha} w_{\alpha} J_{\alpha} (\delta \varepsilon_{ij})_{\alpha} (\sigma_{ij})_{\alpha}$$

Gaussian weight

Jacobian determinant  $|J_{\alpha}|$



4-node quad element with 2x2 gauss points



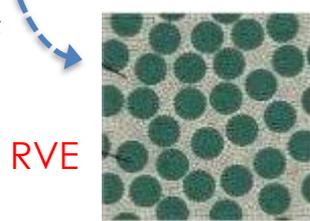
# Multiscale FEA with FE<sup>2</sup>

Static stress analysis

$$\sigma_{ij,j} + b_i = 0$$

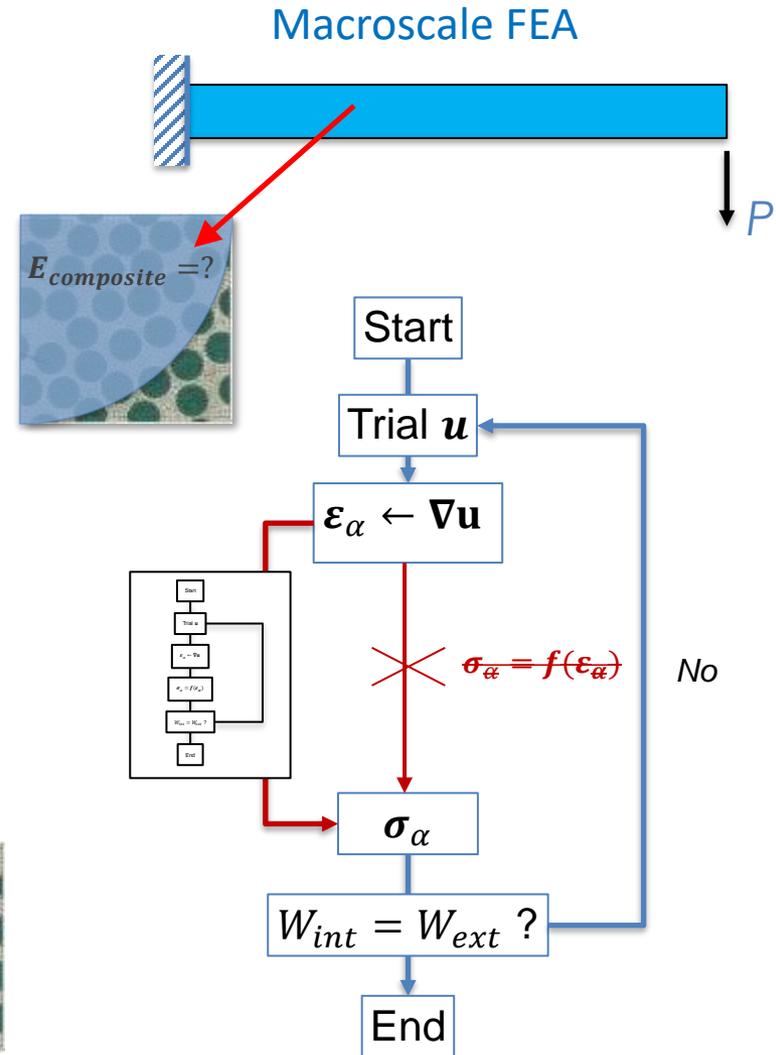
$$\Rightarrow \int_V \underbrace{\delta \varepsilon_{ij} \sigma_{ij}}_{\delta W_{int}} dV = \underbrace{f_I \delta u_I}_{\delta W_{ext}}$$

Numerical integration

$$\Rightarrow \delta W_{int} = \sum_{\alpha} w_{\alpha} J_{\alpha} \underbrace{(\delta \varepsilon_{ij})_{\alpha}}_{\varepsilon_{\alpha}} \underbrace{(\sigma_{ij})_{\alpha}}_{\sigma_{\alpha}}$$


RVE

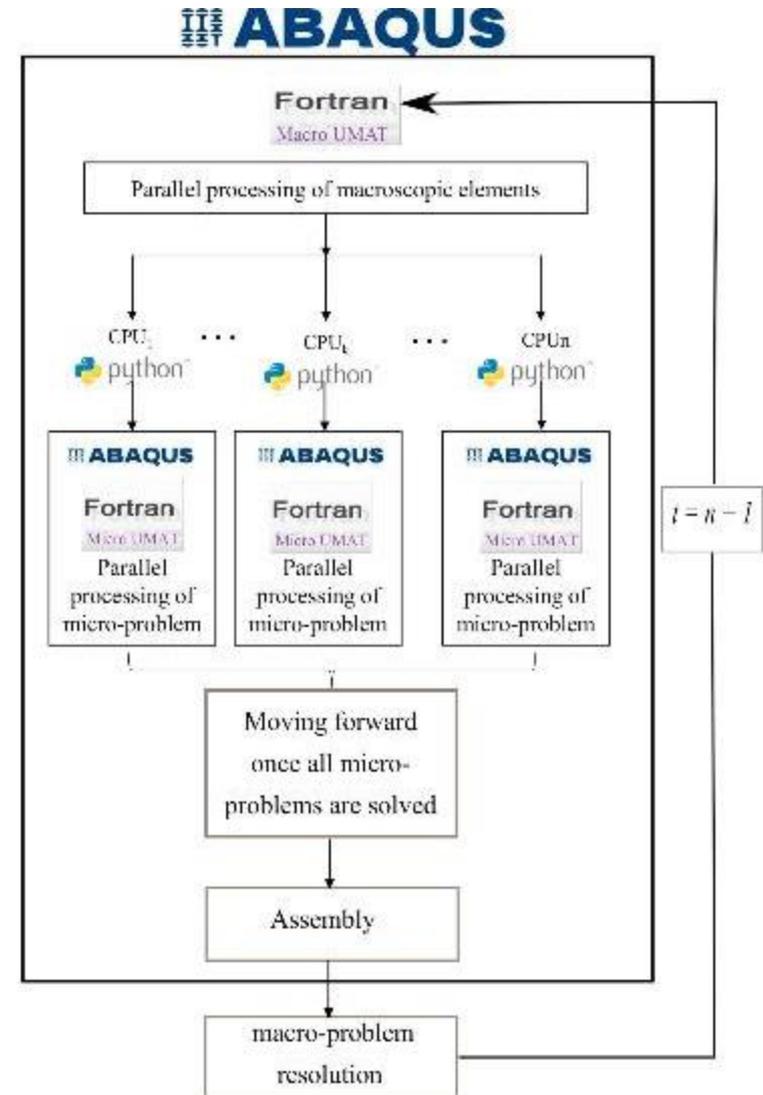
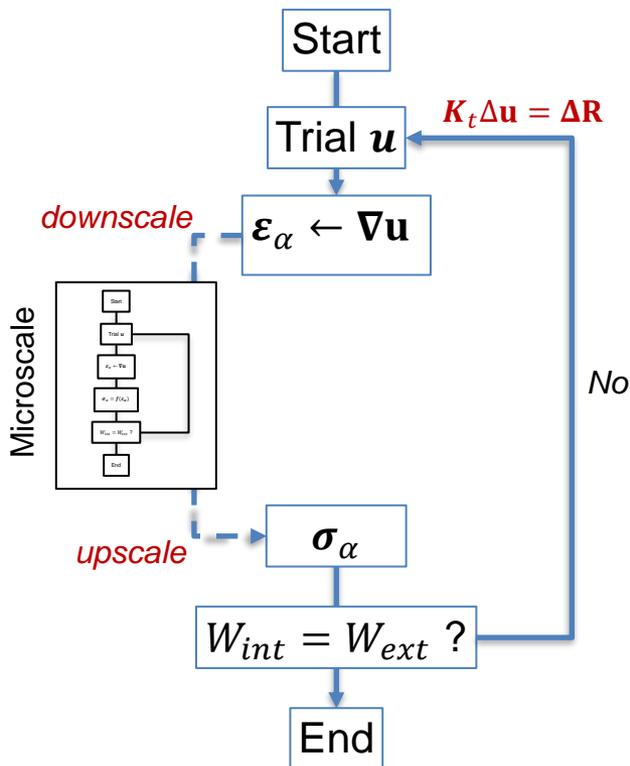
Microscale FEA



# Conventional FE<sup>2</sup>

## Typical implementation

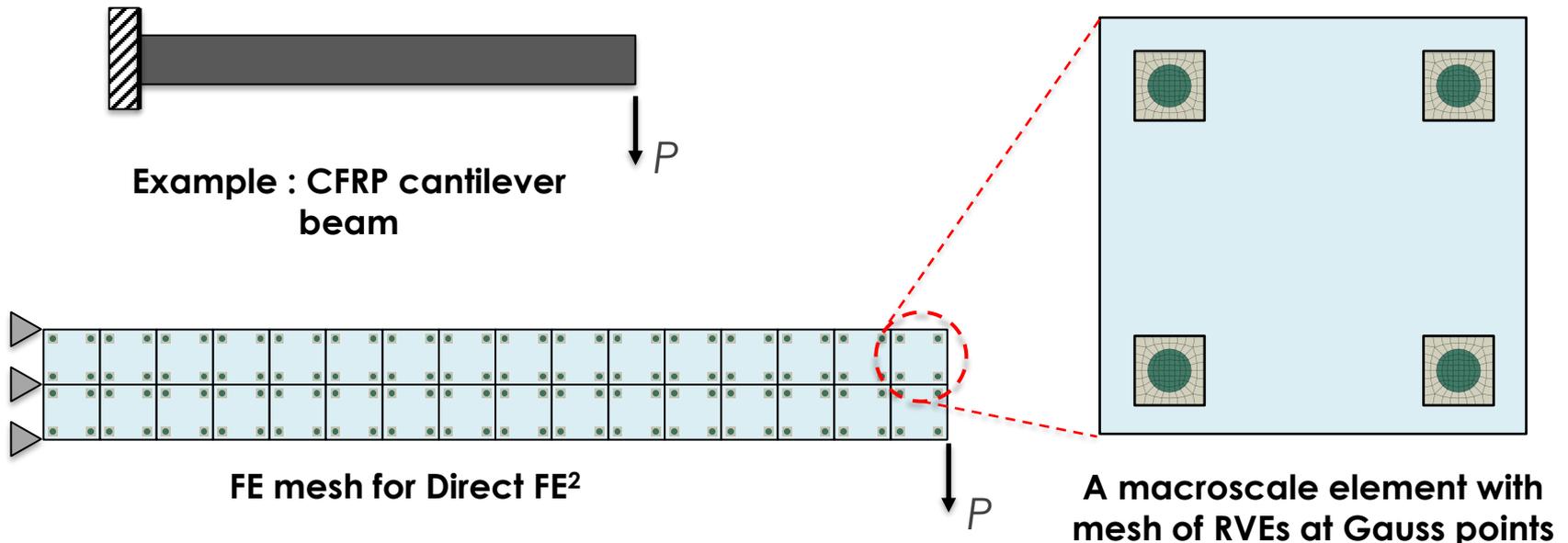
- Separate FE jobs for macroscale and RVEs
- Codes for downscaling and upscaling information exchange
- User defined material routine at macroscale including tangent stiffness,  $K_t$



# Setting up Direct FE<sup>2</sup>

## 1. Combined dual scale mesh

In Direct FE<sup>2</sup>, 2 levels of finite elements appear together as a single FE mesh



- The CFRP beam is meshed with  $2 \times 16$  macro elements. Each macro-element has the mesh of 4 RVEs at its Gauss points.
- Macro elements and RVE elements appear together as a single ABAQUS mesh and run as a single job.

# Setting up Direct FE<sup>2</sup>

## 2. Kinematic constraints

Constraints are applied so that the RVEs deform with the macro-scale elements.

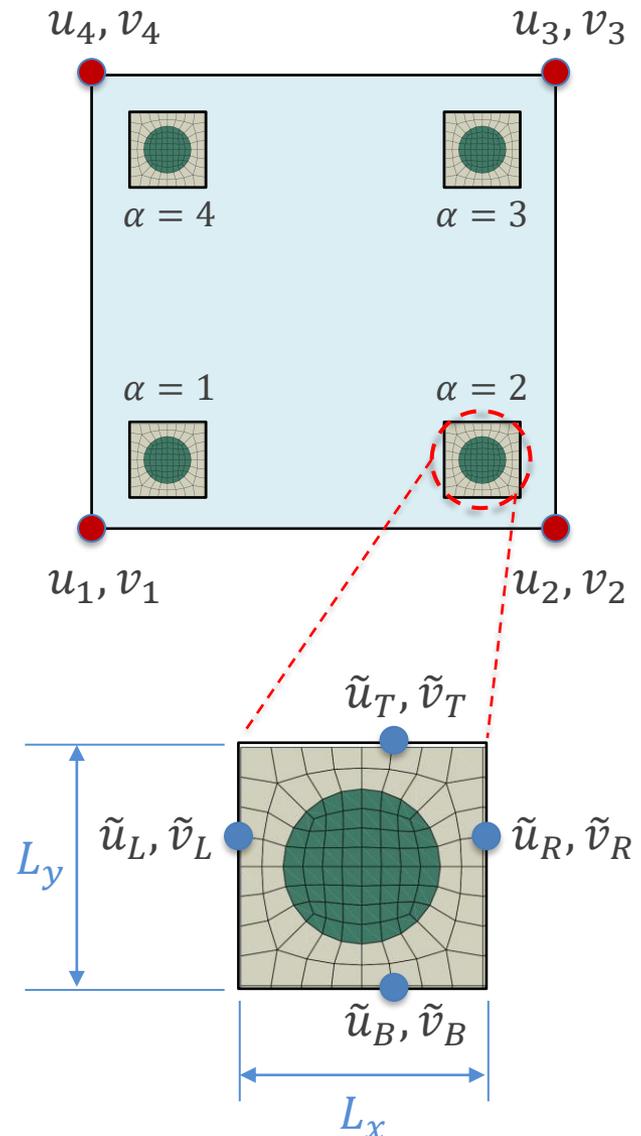
At the macroscale, the deformation gradients are,

$$\begin{aligned} u &= \sum N_I u_I \Rightarrow u_{,x} = \sum N_{I,x} u_I & u_{,y} &= \sum N_{I,y} u_I \\ v &= \sum N_I v_I \Rightarrow v_{,x} = \sum N_{I,x} v_I & v_{,y} &= \sum N_{I,y} v_I \end{aligned}$$

These are applied as Periodic Boundary Conditions to the RVEs

$$\begin{aligned} \frac{\tilde{u}_R - \tilde{u}_L}{L_x} &= \sum N_{I,x} u_I & \frac{\tilde{u}_T - \tilde{u}_B}{L_y} &= \sum N_{I,y} u_I \\ \frac{\tilde{v}_R - \tilde{v}_L}{L_x} &= \sum N_{I,x} v_I & \frac{\tilde{v}_T - \tilde{v}_B}{L_y} &= \sum N_{I,y} v_I \end{aligned}$$

The above relations between the RVE and macroscale nodes are applied only once using MPC (multipoint constraints) in ABAQUS at the pre-processing stage.



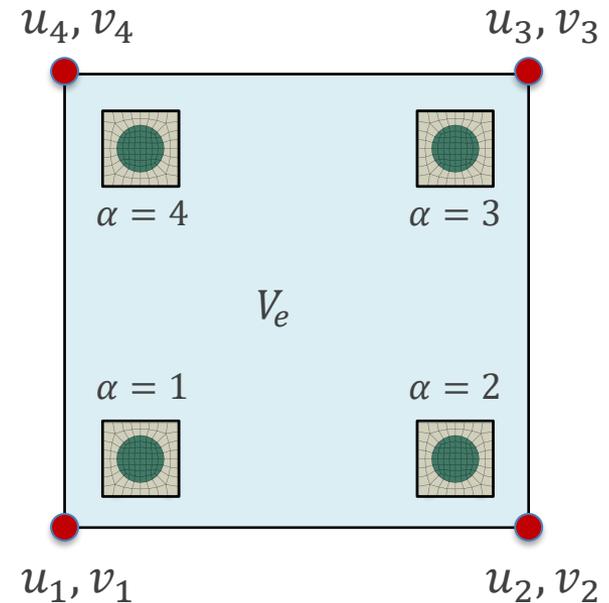
# Setting up Direct FE<sup>2</sup>

## 3. Energy consistency

Strain energy within each macroscale element is calculated using Gaussian quadrature,

$$\delta W_{int} = \int_{V_e} \delta \boldsymbol{\varepsilon} : \boldsymbol{\sigma} dV = \sum_{\alpha} w_{\alpha} J_{\alpha} \delta \boldsymbol{\varepsilon}_{\alpha} : \boldsymbol{\sigma}_{\alpha}$$

In a FE<sup>2</sup> analysis,  $\boldsymbol{\sigma}_{\alpha}$  cannot be directly determined because the constitutive relation at the macroscale is unknown.



Instead,  $\delta \boldsymbol{\varepsilon}_{\alpha} : \boldsymbol{\sigma}_{\alpha}$  is replaced by the average energy densities of the RVEs

$$\delta \boldsymbol{\varepsilon}_{\alpha} : \boldsymbol{\sigma}_{\alpha} \equiv \frac{1}{V_{\alpha}} \int_{V_{\alpha}} \delta \tilde{\boldsymbol{\varepsilon}} : \tilde{\boldsymbol{\sigma}} dV \leftarrow \text{Hill-Mandel condition}$$

$$\Rightarrow \delta W_{int} = \sum_{\alpha} \frac{w_{\alpha} J_{\alpha}}{V_{\alpha}} \int_{V_{\alpha}} \delta \tilde{\boldsymbol{\varepsilon}} : \tilde{\boldsymbol{\sigma}} dV$$

# Setting up Direct FE<sup>2</sup>

## 3. Energy consistency

In Direct FE<sup>2</sup>, the macroscale element is assigned zero material properties.

Therefore, internal energy calculated by ABAQUS is from the RVEs only, i.e.,

$$\delta W_{int}^{FE^2} = \sum_{\alpha} \int_{V_{\alpha}} \delta \tilde{\boldsymbol{\varepsilon}} : \tilde{\boldsymbol{\sigma}} dV$$

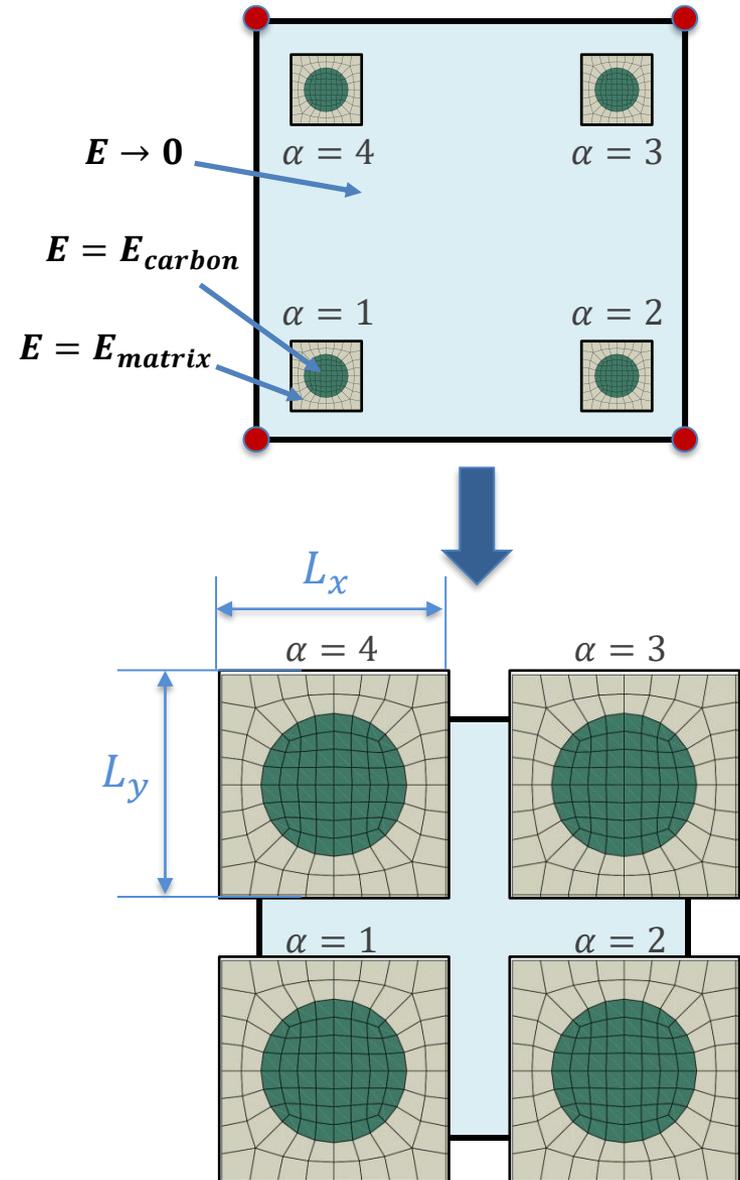
To obtain the correct internal energy, we must make

$\delta W_{int}^{FE^2}$  equal to

$$\delta W_{int} = \sum_{\alpha} \frac{w_{\alpha} J_{\alpha}}{V_{\alpha}} \int_{V_{\alpha}} \delta \tilde{\boldsymbol{\varepsilon}} : \tilde{\boldsymbol{\sigma}} dV$$

Hence, we choose the dimensions of the RVE, i.e.,  $L_x$  and  $L_y$ , so that

$$V_{\alpha} = w_{\alpha} J_{\alpha}$$



# Setting up Direct FE<sup>2</sup>

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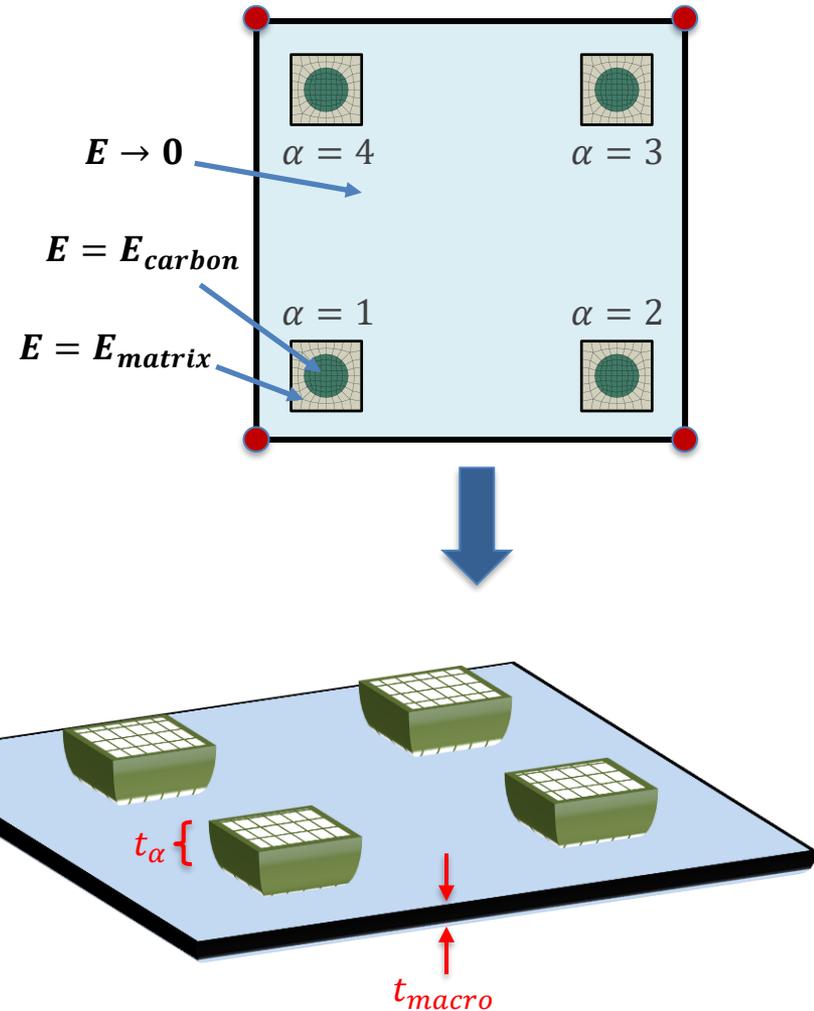
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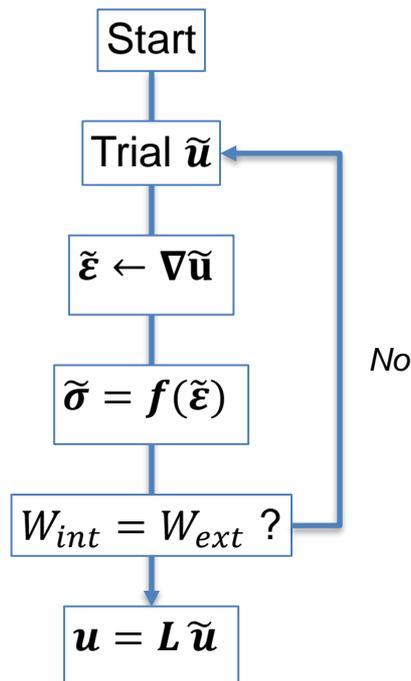
$$V_{\alpha} = w_{\alpha} J_{\alpha}$$

For 2D analysis, the thickness can be scaled instead.

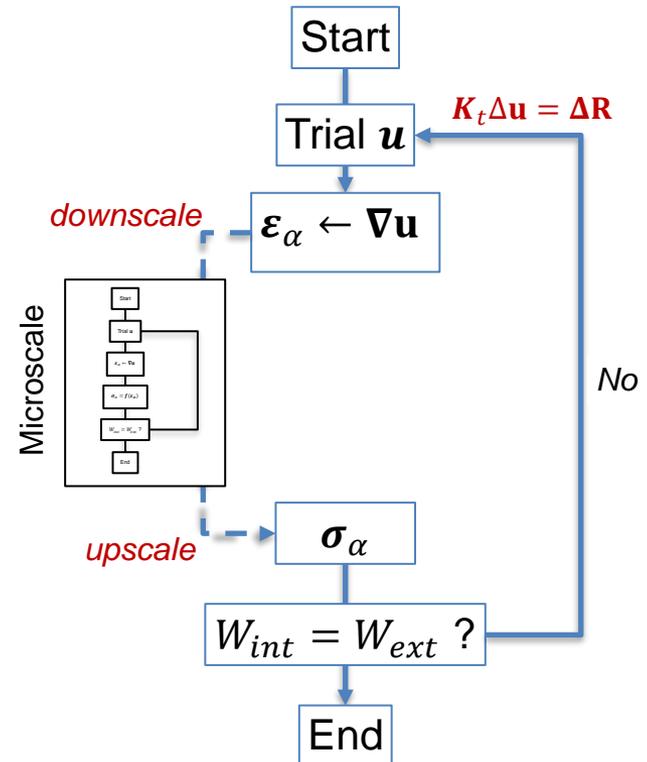


# Direct FE<sup>2</sup> vs conventional FE<sup>2</sup>

Direct FE<sup>2</sup>



Conventional FE<sup>2</sup>

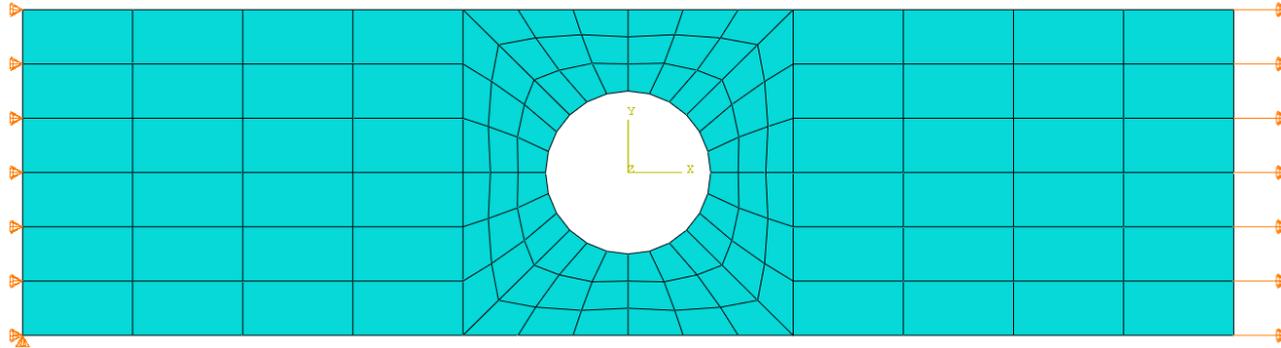


Steps :

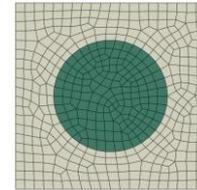
- Determine scaled volume of RVEs
- Set up macroscale and RVE mesh
- Apply MPC to establish kinematic constraints

# Python script for Direct FE<sup>2</sup>

Macro.inp

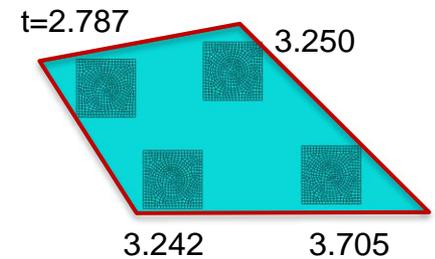
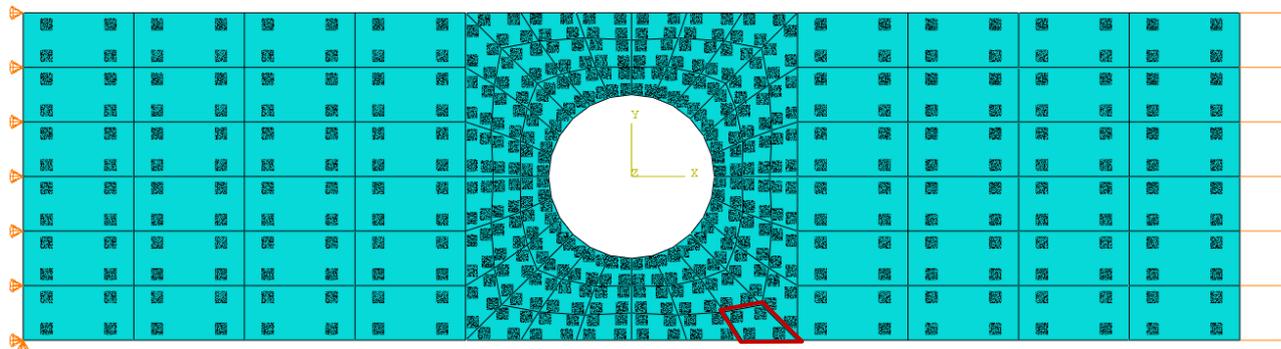


RVE.inp

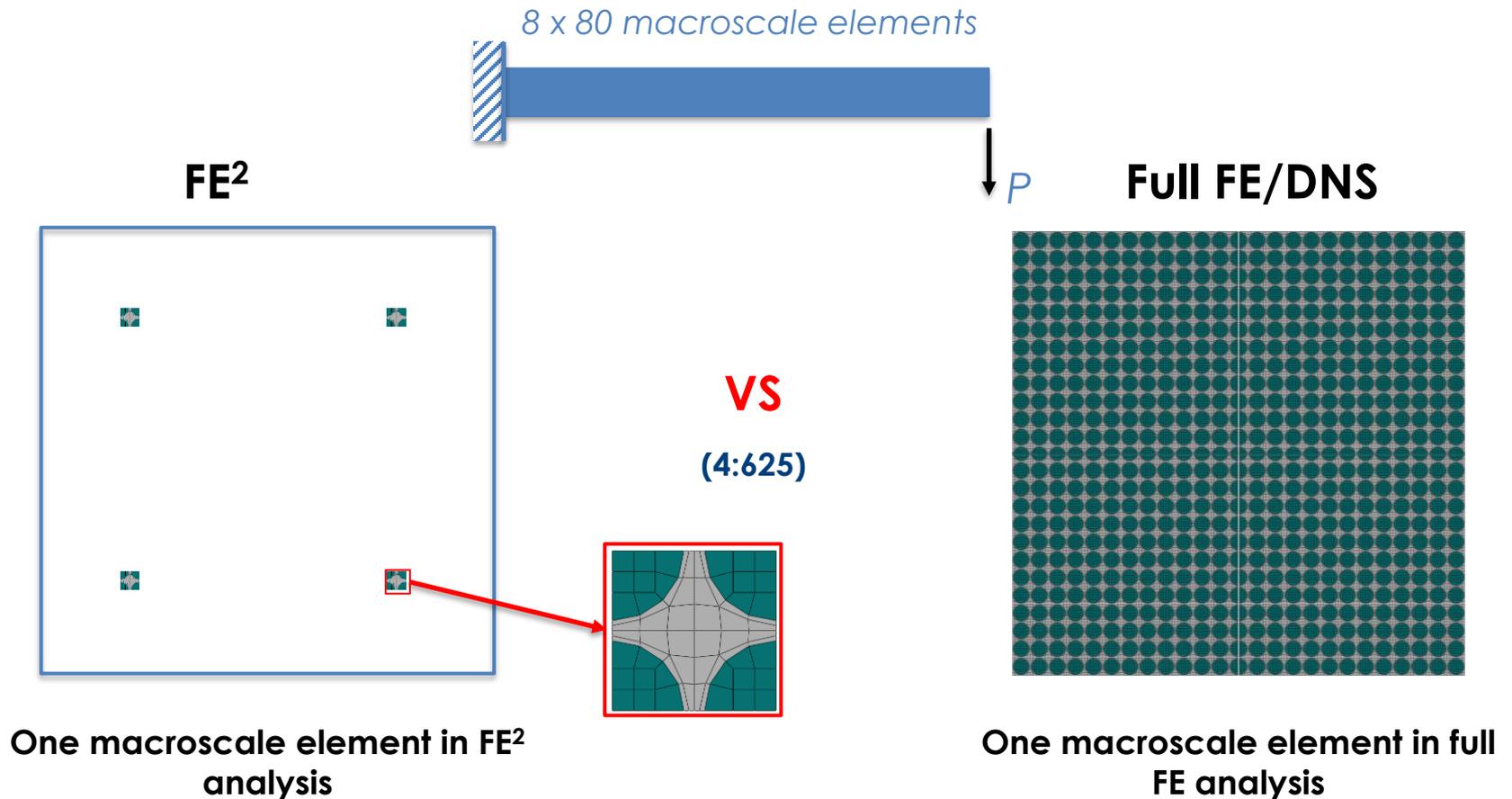


DFE2\_2to1.py

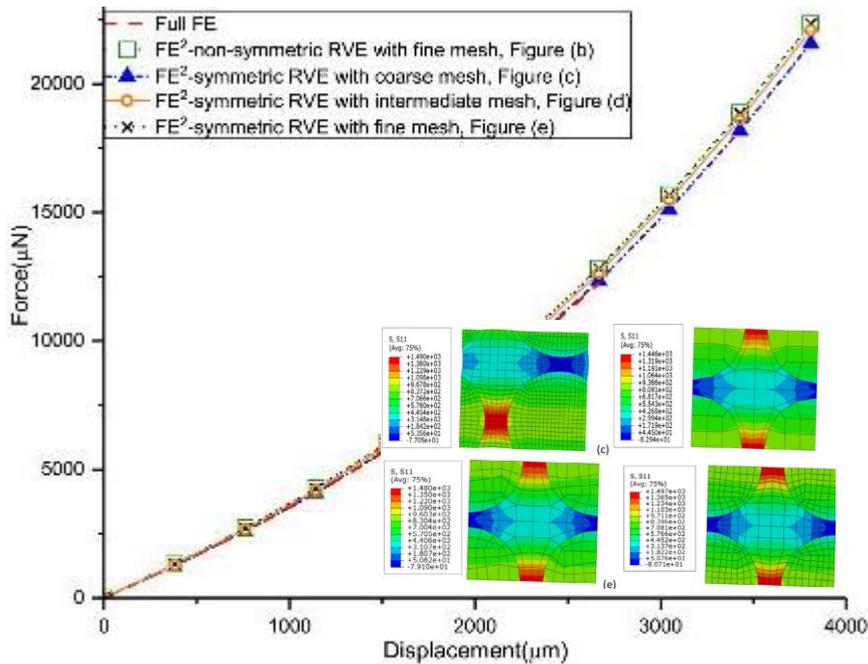
DFE2.inp



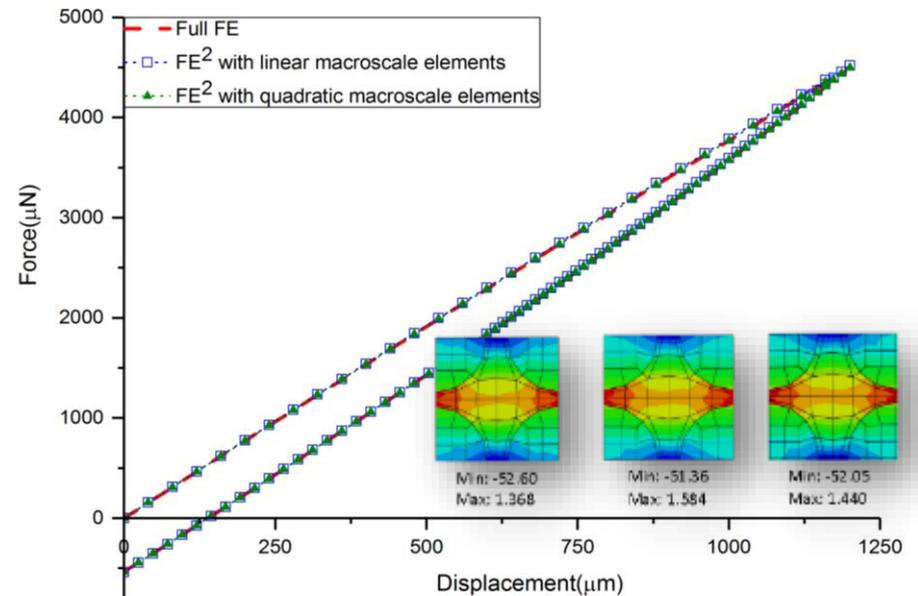
# Direct FE<sup>2</sup> for composite beam



# Direct FE<sup>2</sup> for composite beam

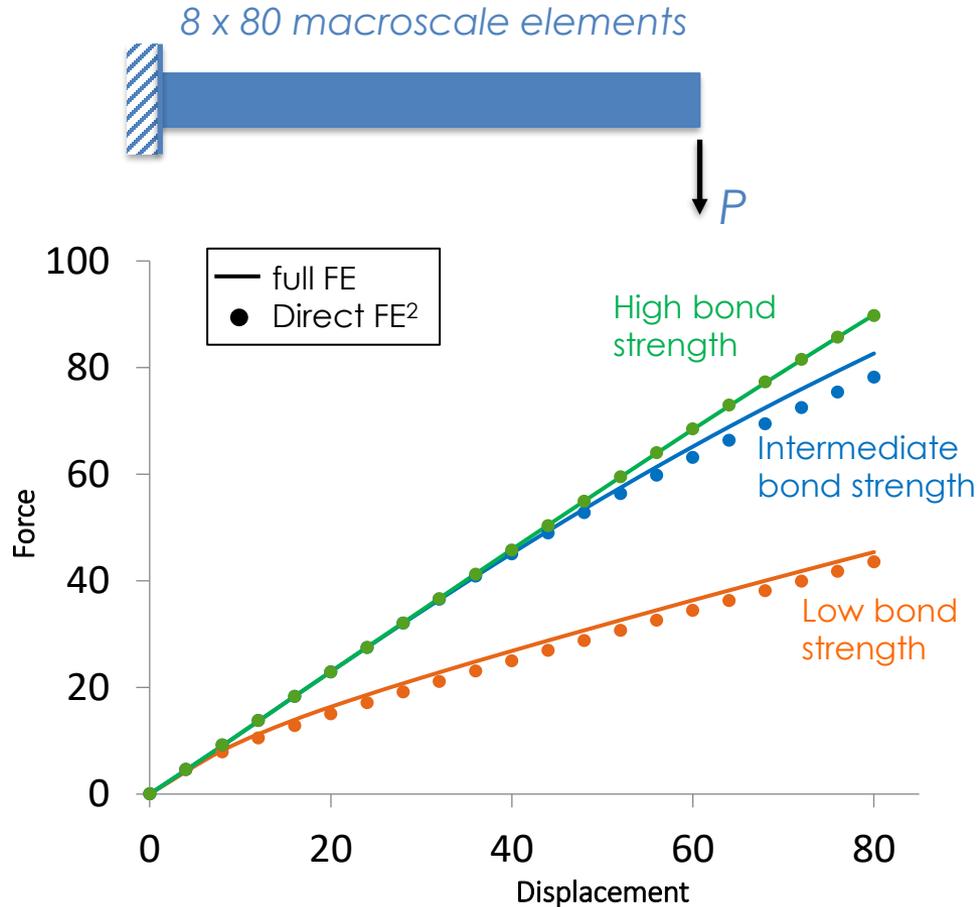


Load–displacement plots for **large deformation** elastic composite beam.



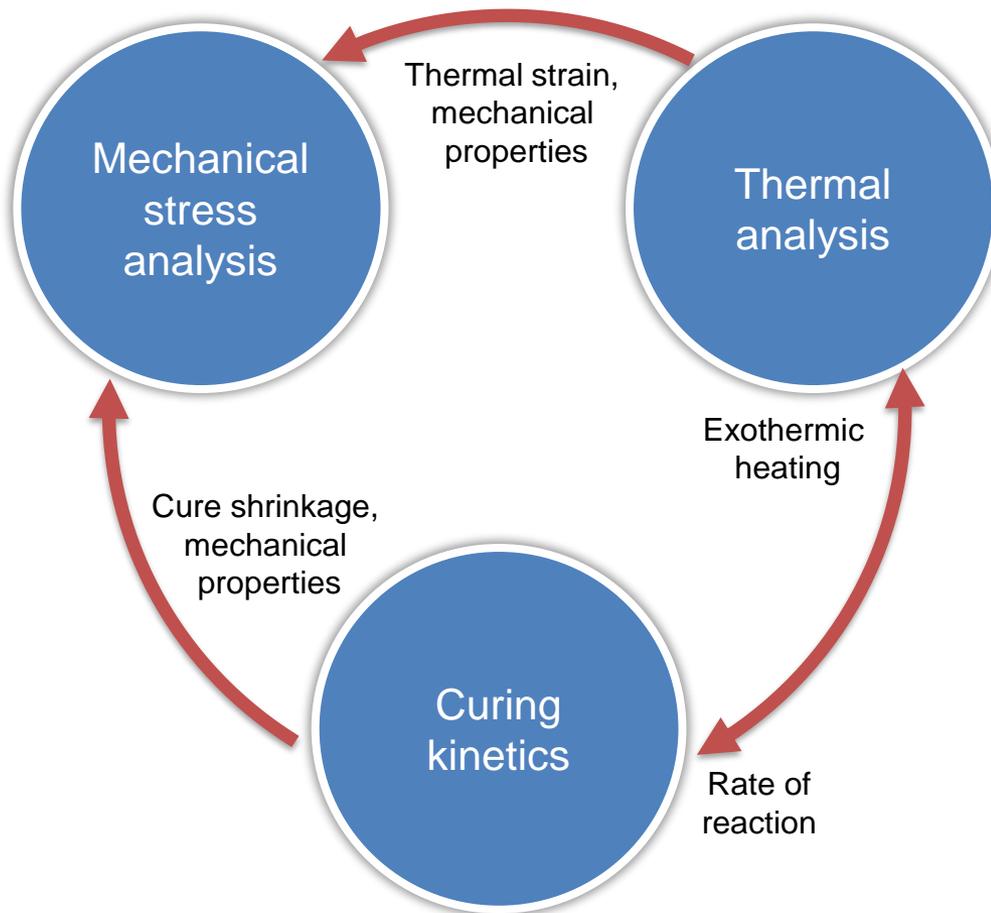
Load–displacement plots for **viscoelastic** composite beam.

# Direct FE<sup>2</sup> for composite beam



Load-displacement plots for composite beam with **fibres debond**.

# Thermo-mechanical cure-induced deformation



## Interdependencies: (3501-6 epoxy)

- Modulus

$$E = E^{\infty} + (E^u - E^{\infty}) \sum_n w_n \exp\left(-\frac{\xi(\alpha, T)}{\zeta(\alpha)}\right)$$

- Exothermic heating

$$r = \rho H \dot{\alpha}$$

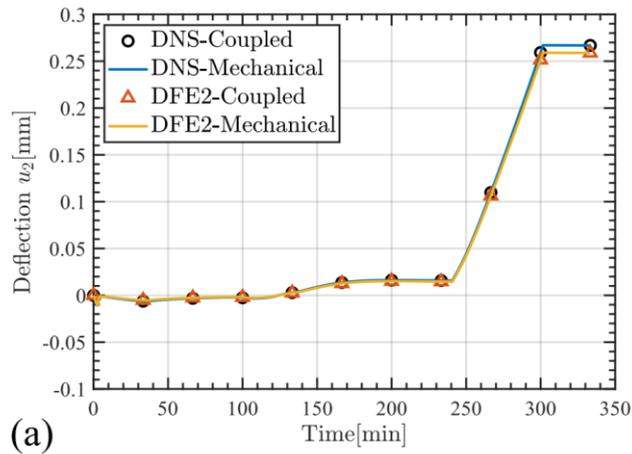
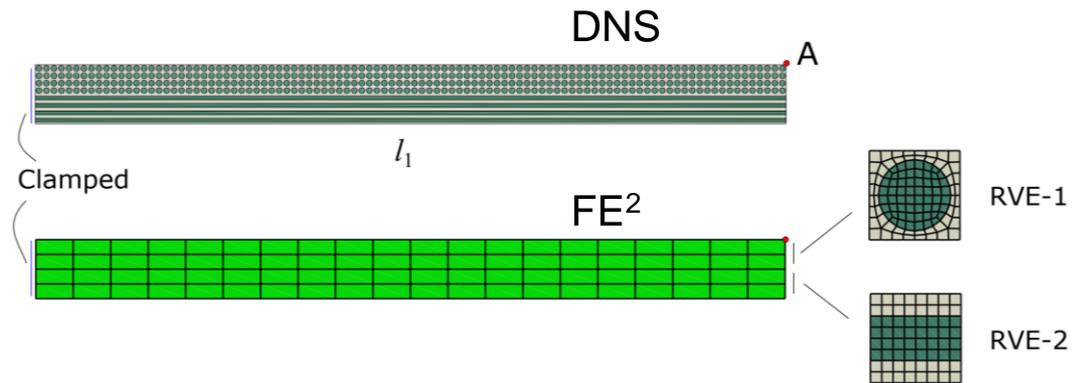
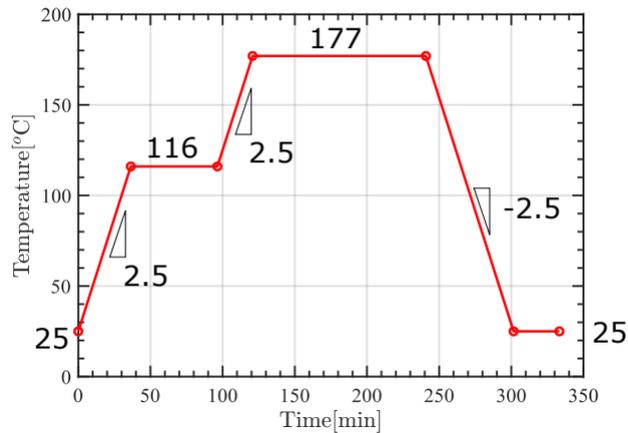
- Rate of cure

$$\dot{\alpha} = \begin{cases} (K_1 + K_2 \alpha)(1 - \alpha)(0.47 - \alpha) & \alpha \leq 0.3 \\ K_3(1 - \alpha) & \alpha > 0.3 \end{cases}$$

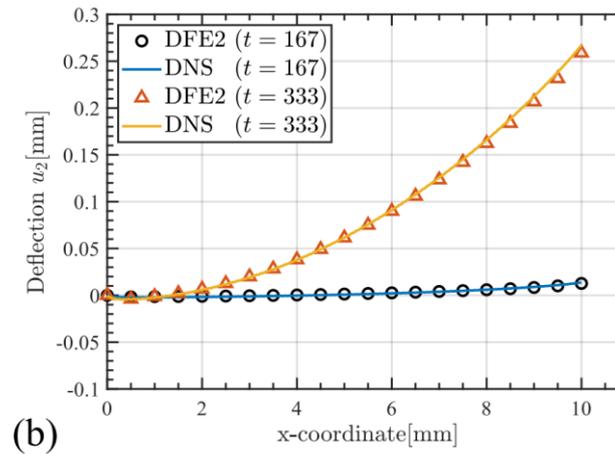
$$K_i = A_i \exp\left(-\frac{\Delta E_i}{RT}\right)$$

# Thermo-mechanical cure-induced deformation

Cure cycle

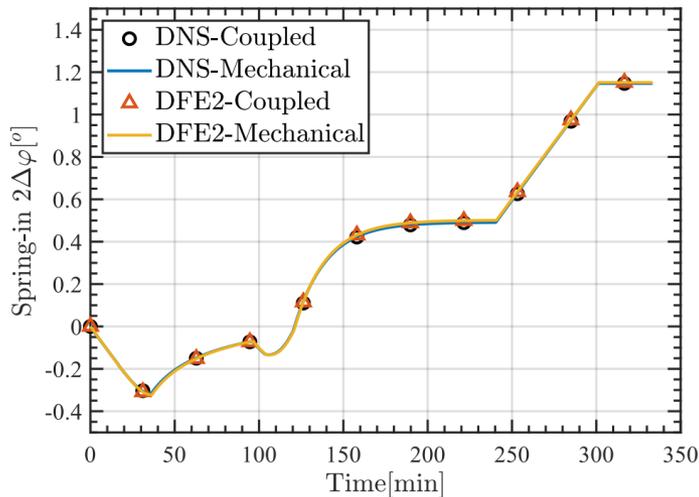
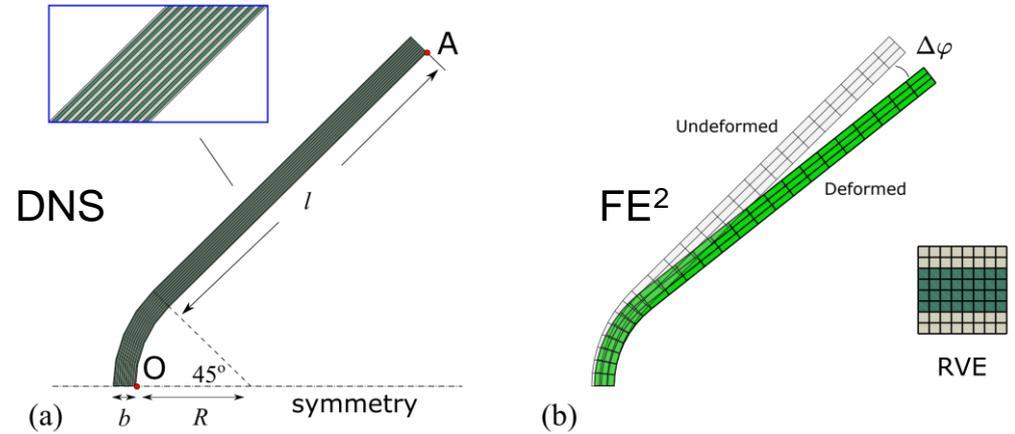
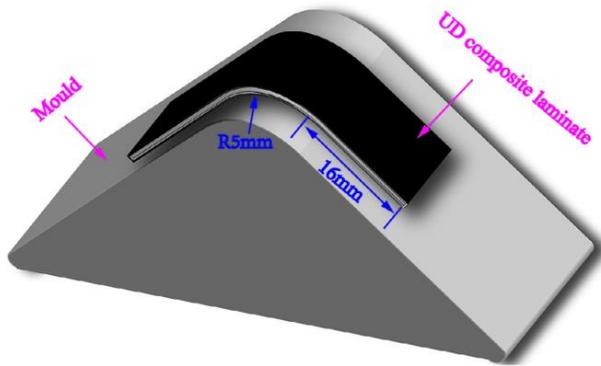


Deflection of point A vs time

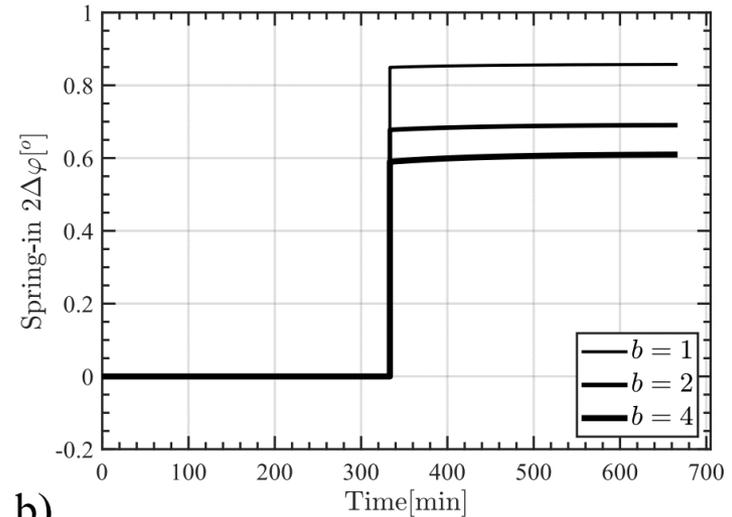


Deflection of top edge

# Thermo-mechanical cure-induced deformation

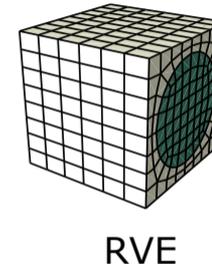
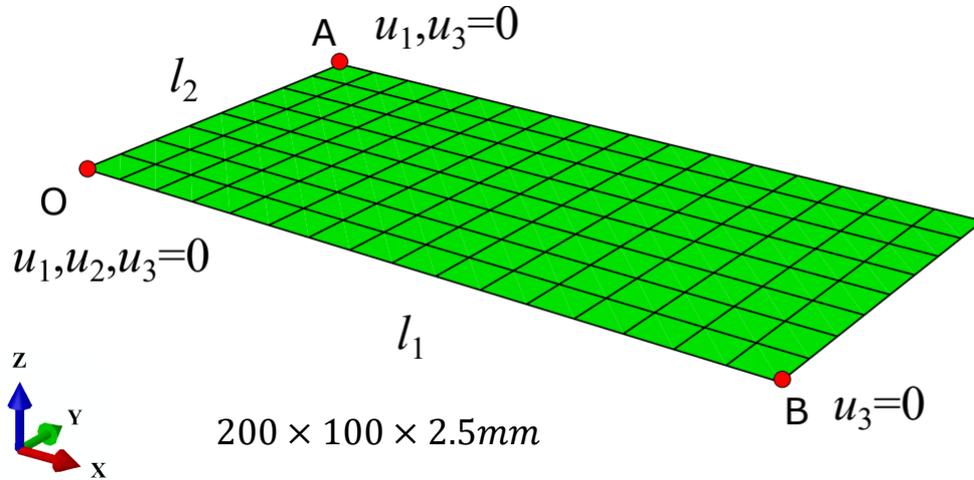


Spring-in vs time (unrestrained)

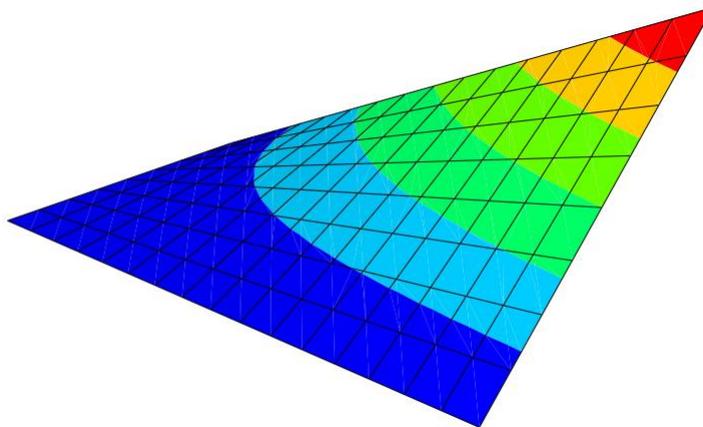
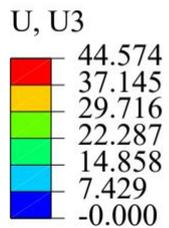


b) Spring-in vs time (restrained)

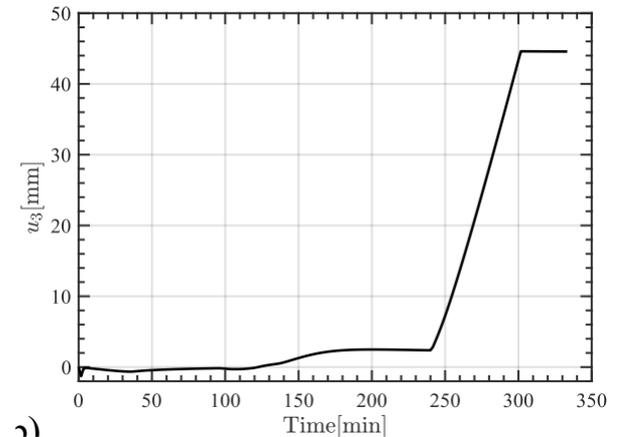
# Thermo-mechanical cure-induced deformation



[45/-45]



Final deformation (x2)

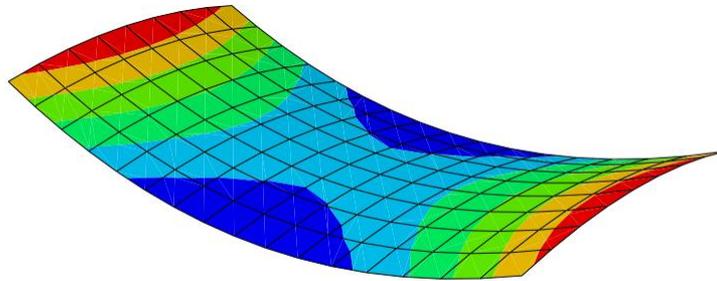
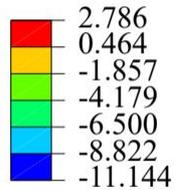


Deflection of free corner vs time

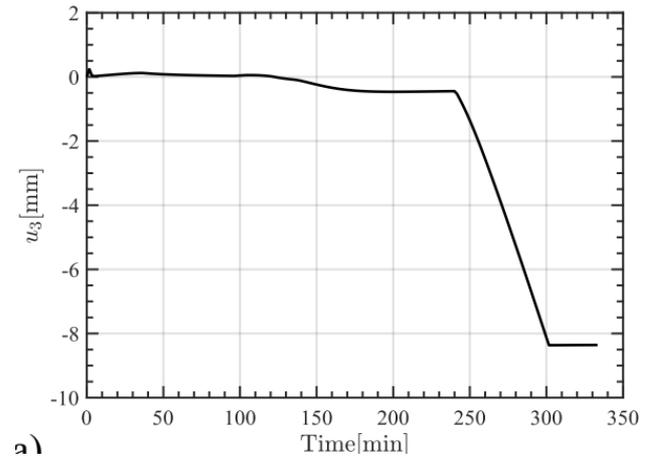
# Thermo-mechanical cure-induced deformation

[0/90]

U, U3



Final deformation (x2)

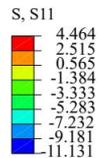


a)

Deflection of laminate center

## Internal stress

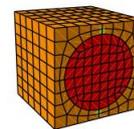
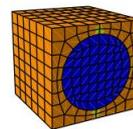
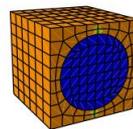
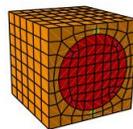
$t=167$  min



bottom



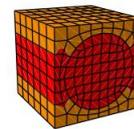
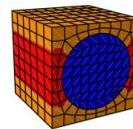
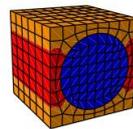
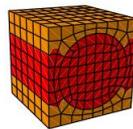
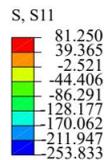
top



0-degree

90-degree

$t=333$  min



# Conclusions

- Multiscale simulations can be easily implemented as a single FEA on commercial FE codes with Direct FE<sup>2</sup>.
- The implementation is completed at the pre-processing stage. No user intervention is needed thereafter.
- All capabilities of the commercial code, including multiphysics analysis, are available with Direct FE<sup>2</sup>.

# Thank you!

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DFE2\_2to1.py

# References

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