

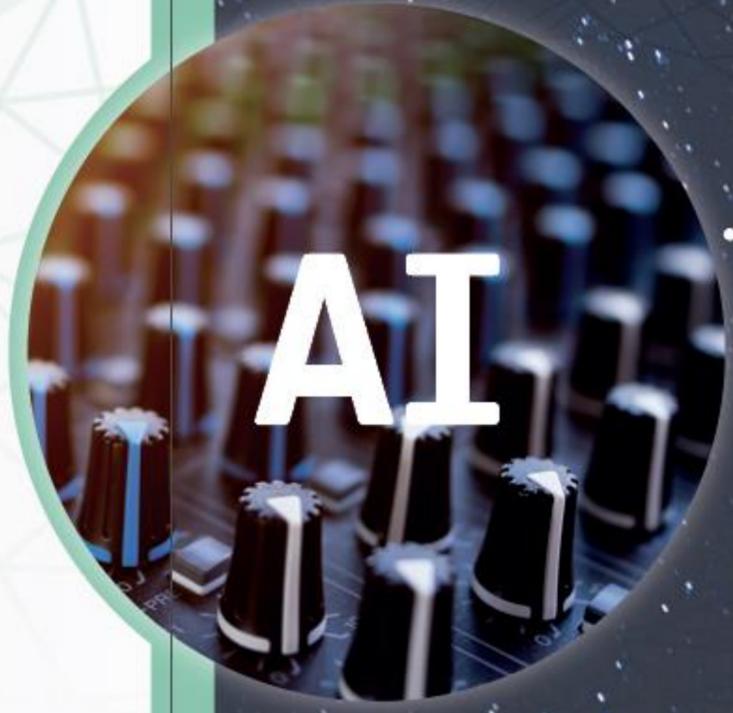
AI4EO: from big to small architecture for deployment at the edge

Φ -lab Explore office @EOP/ESRIN
by Nicolas LONGEPE

in collaboration with Pierre Philippe Mathieu, Andrzej Kucik, Bertrand le Saux (Φ -lab), Massimiliano Pastena (ESTEC)

And industries: KP Labs (BEETLES), Agenium (CORTEX), Cosine and Univ. Pisa (Phisat-1), OpenCosmos, CGI, Ubotica, Simera CH Innovative, CEiiA, GEO-K, and KP Labs (Phisat-2)

0 Stack to query our planet



Observing System

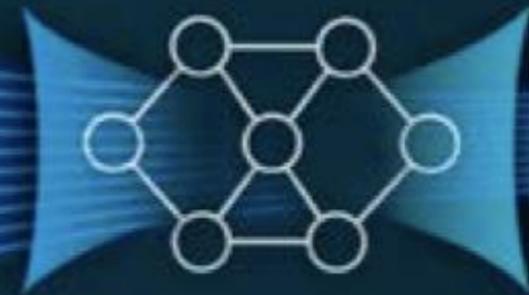


and now
AI@edge...



AI @ Edge: why?

Versatility



BrainSat
Digital Twin



Enhanced security



High responsiveness

Low data rate

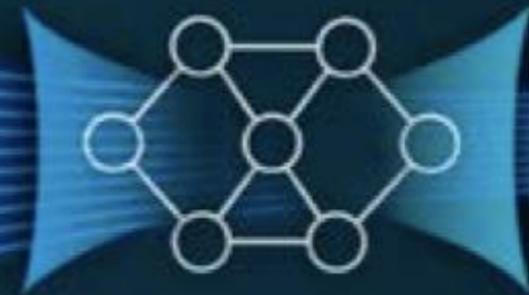


“ The value of satellite-based EO no longer grows with the ability to collect and transmit data back to Earth, it increasingly lies with the ability to transmit customer-relevant insight in real-time. ”

Peter Platzer,
Spire, Φ-week 2019

AI @ Edge: status as of 2021

Versatility
(see Ops-SAT)



BrainSat
Digital Twin



Enhanced security

High responsiveness

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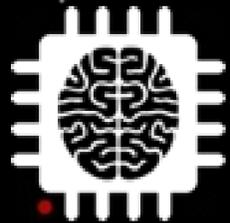
Peter Platzer,
Spire, Φ-week 2019

Low data rate
(Phisat-1)



Φ -sat-1

Training on Ground
(S-2 mimicking)
Cloud detection



Inference in Space



Hardware

This project is **technology driven**:

Visual Processing Unit (VPU) Myriad-2

Hardware accelerator for Convolution Neural Networks (CNNs)



Fast: 1 TOPS



Low power: $O(1 \text{ Watt})$

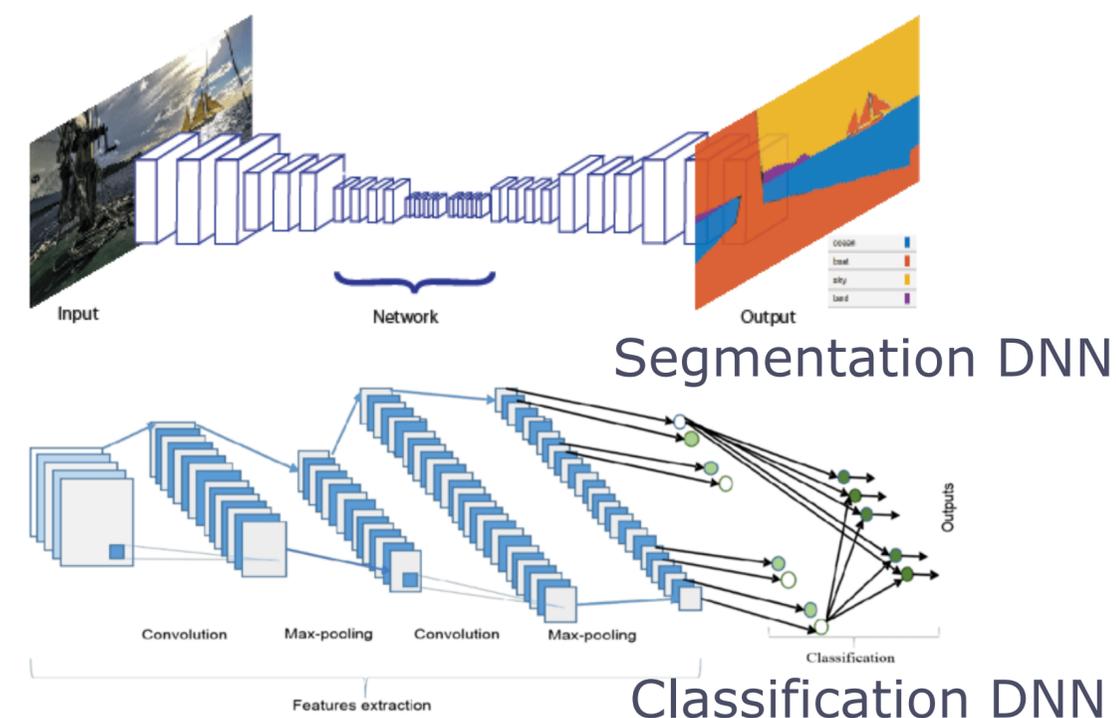
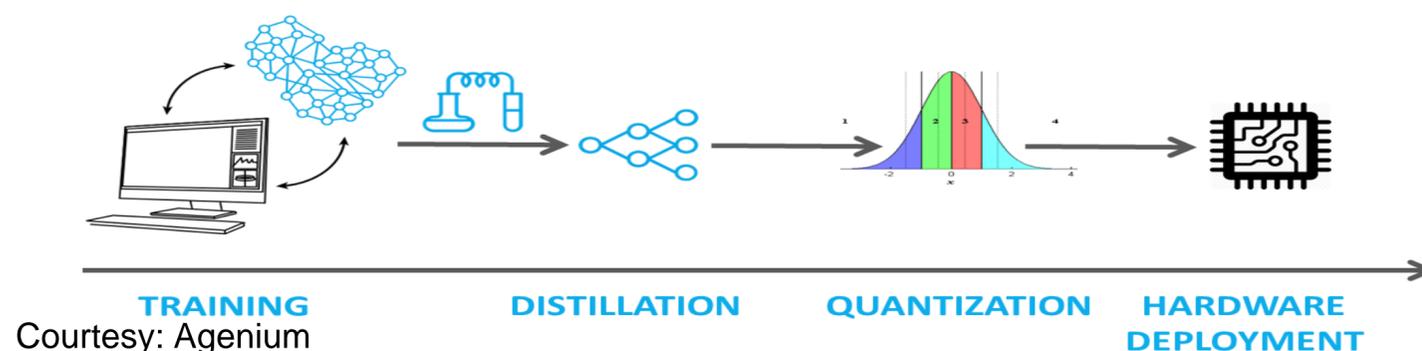


Tiny



Process for DNN on-board deployment

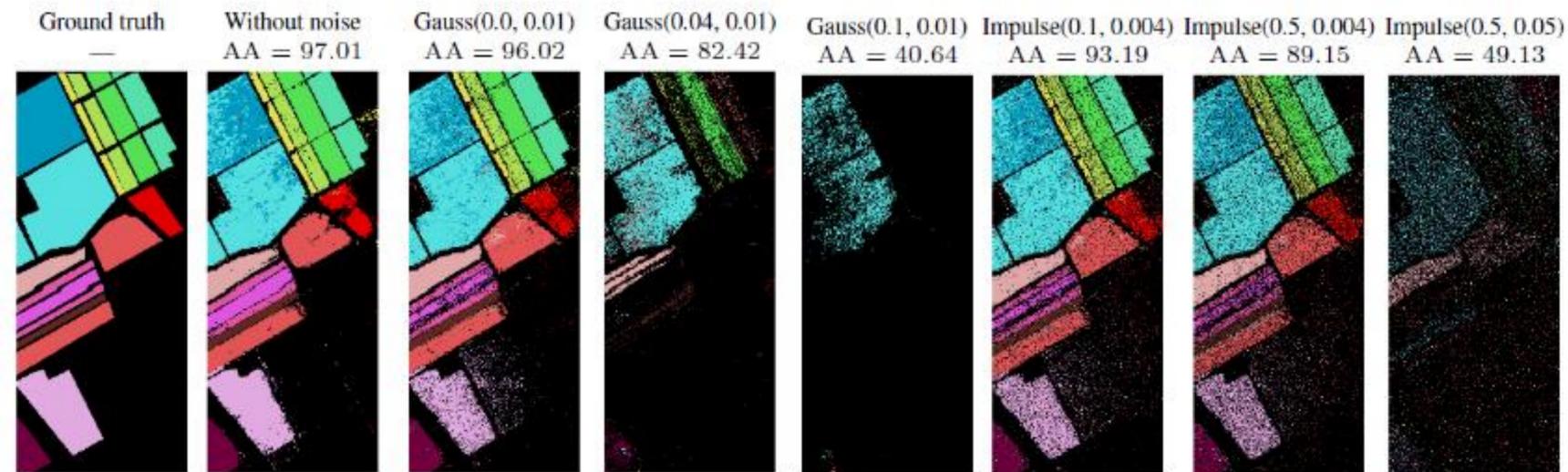
- **Training (in the cloud ... in future maybe directly @edge):**
 - Database with Ground truth
 - How to synthesize EO data mimicking the performance of the upcoming payload?
 - Ensure robustness to all uncertainties (e.g. data augmentation)
- **Fitting to onboard requirements (throughputs, power consumption...)**
 - Which NN architecture? Network Architecture Search (NAS), Knowledge Distillation
 - Network Optimization: pruning, quantization
- **Hardware deployment**



DNN training: robustness to noise

Hyperspectrometers:

- Presence of various kinds of noise (thermal noise, sensor saturation)
- ⇒ Degrade classification accuracy, a potential obstacle for deploying onboard satellite
- ⇒ Denoising and/or better regularization may help obtain high-quality classification.



J. Nalepa, M. Stanek, "Segmenting hyperspectral images using spectra convolutional neural networks in the presence of noise," Proc. IGARSS 2020, pp 1-4, 2020.

⇒ Require robustness to SNR, but also data mis-calibration, inter-band displacement, band-to-band registration

Resource-frugal quantized CNN: simplification

Knowledge Distillation :

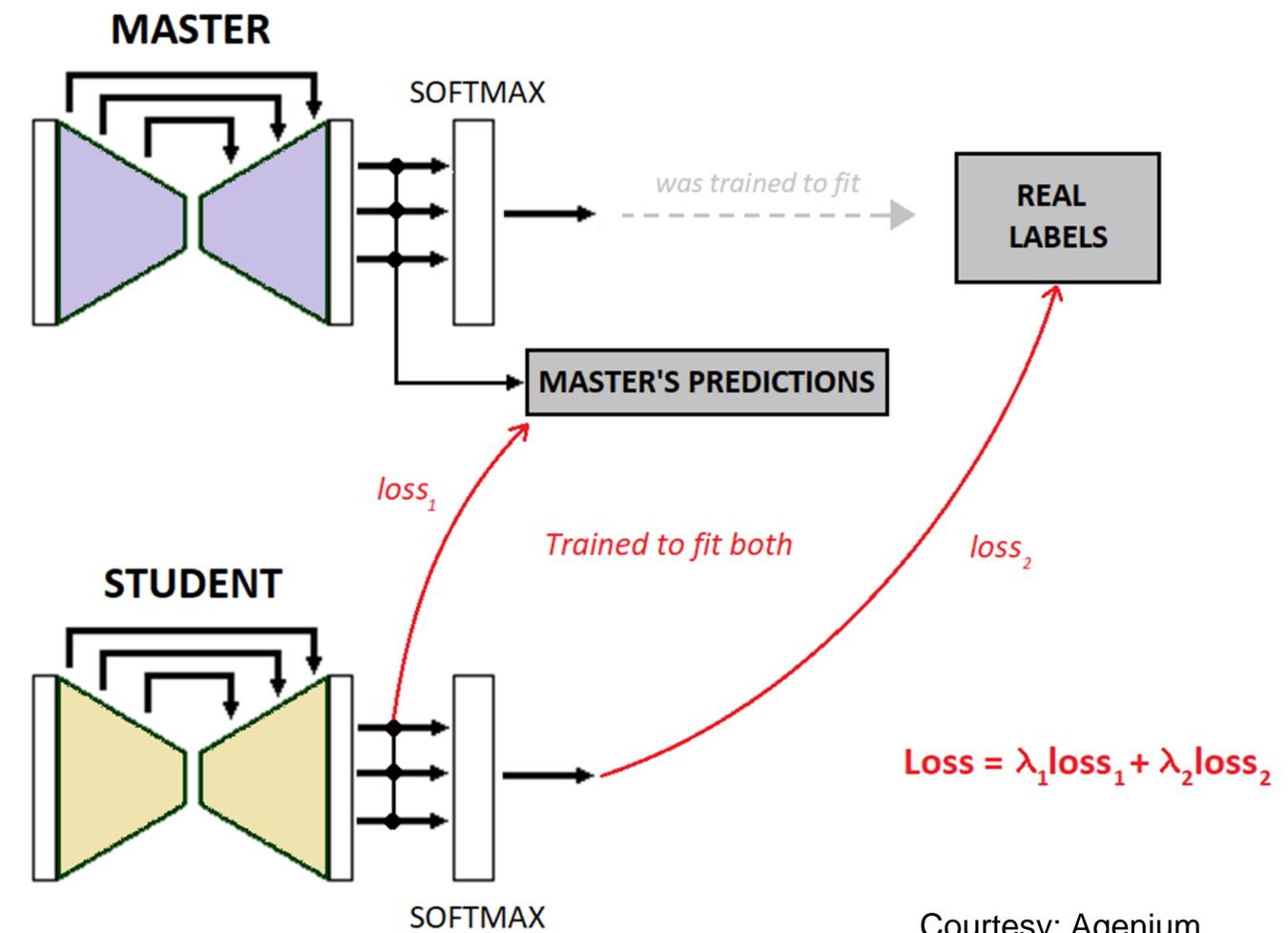
Process of transferring knowledge from a large model to a smaller one, without loss of performance

Input: high-performance DNN

Output: DNN with small target architecture

Aim:

- Reduced number of parameters for the distilled DNN



⇒ Reduction of x52 shown (136M -> 2,6M) without performance loss

⇒ Another process: Network Architecture Search (NAS)

Resource-frugal quantized CNN: quantization

Network quantization:

Reduce float32 (Model trained) -> Int8 (Quantized Model)

- > Better memory footprint (div. by 4)
- > Better throughput
- > Better energy efficiency

Table 11 : Comparison between the best distilled model for the Boat Detection DB, before quantization (32bits float) and after quantization of weights and activations with the same number of bits, spanning from 2 to 8. Bold values measure a loss smaller than 1% of the result obtained with the distilled model.

Courtesy: Agenium

Model	32bits	8bits Int	7bits Int	6bits Int	5bits Int	4bits Int	3bits Int	2bits Int
379	Float							
F1 class 0	0.977100	0.973312	0.967102	0.926616	0.839211	0.805933	0.000000	0.000000
F1 class 1	0.923300	0.913118	0.891938	0.800595	0.673939	0.643182	0.375813	0.375813

Vitis AI (Xilinx) Quantization

- Symmetric (Signed Int)
- Static (weights) & Dynamic (Activations)
- Required ~100-1000 images to calibrate activations

⇒ Reduction of x4 without performance loss

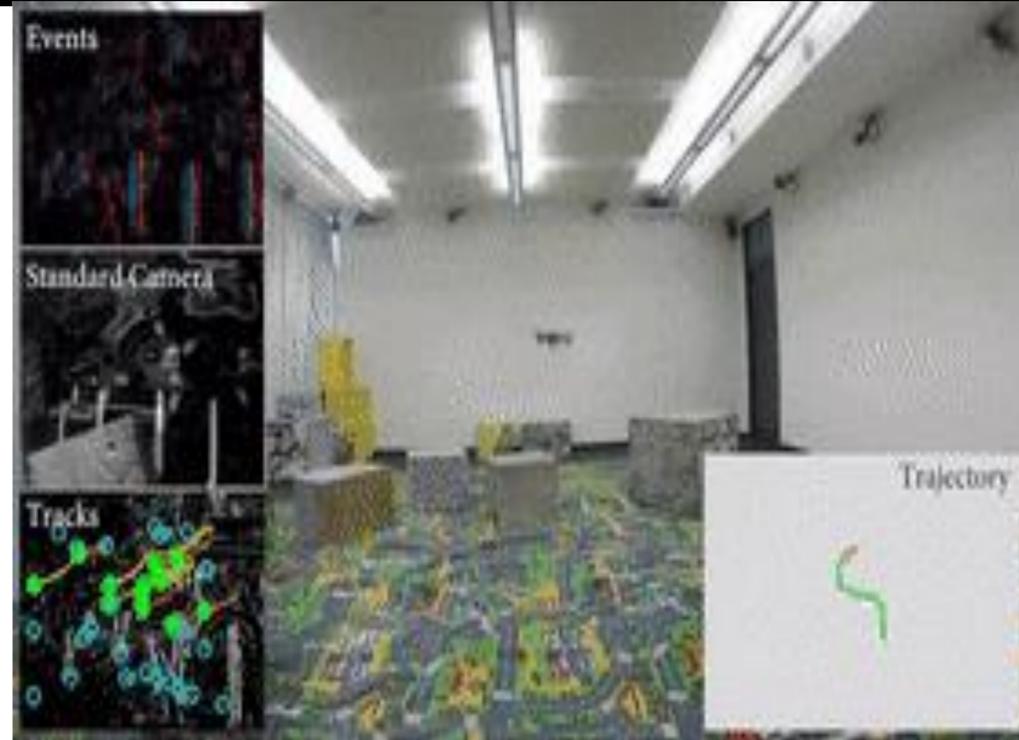
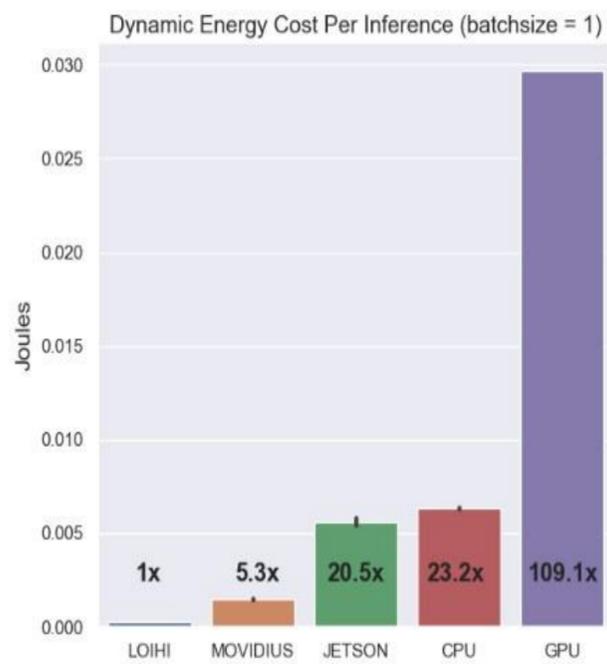
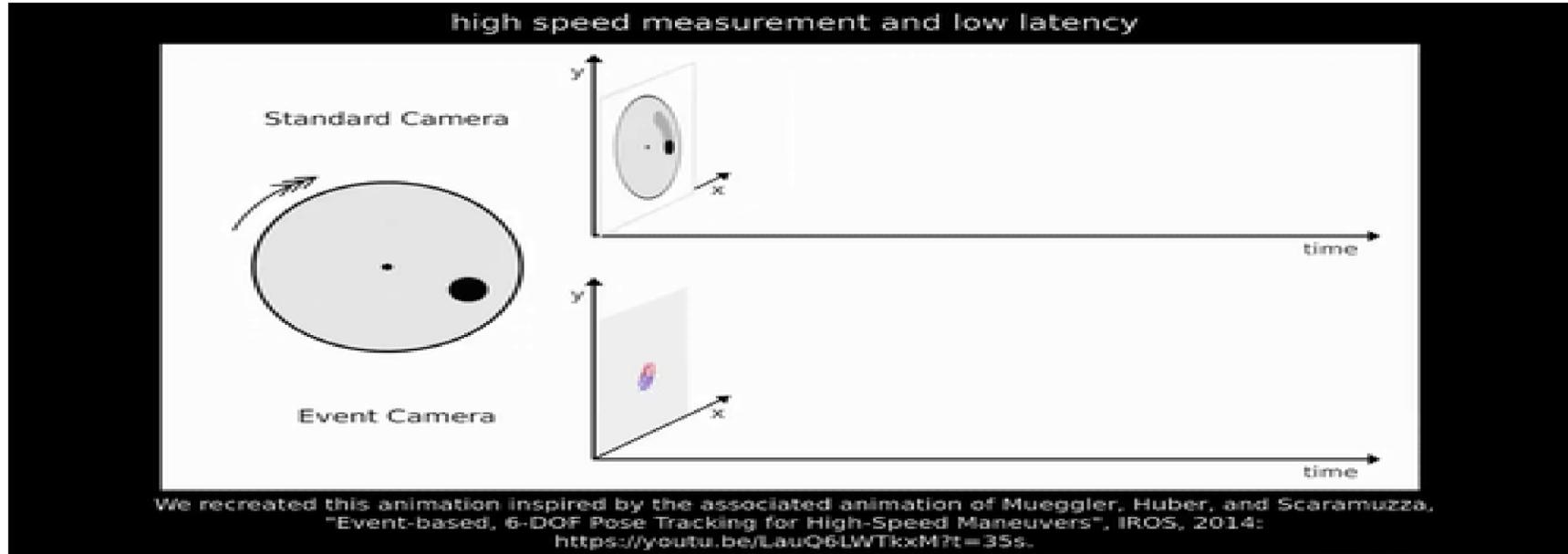
A short term prospect: Φ -sat-2

A game-changing Earth Observation CubeSat platform in space capable of running AI Apps that can be developed by its users, then easily deployed in the spacecraft, and operated from ground.

An example of longer term perspective: Neuromorphic computing for EO



Andrzej Kucik (Φ -Lab), Gabriele Meoni (ACT)



P. Blouw, X. Choo, E. Hunsberger Ch. Eliasmith, *Benchmarking Keyword Spotting Efficiency on Neuromorphic Hardware* (2019)

ETH Robotics and Perception Group

Objectives

- 1) Establish the feasibility of deploying the dynamic vision sensors to collect geospatial data:
 - Low latency
 - High dynamic range
 - Low power
- 2) Establish the feasibility of processing the geospatial data on neuromorphic chips/hardware platforms:
 - Asynchronous and massively parallel
 - Neuronal state
 - Low power
- 3) Design neuromorphic algorithms (spiking neural networks) for solving the Earth observation problems

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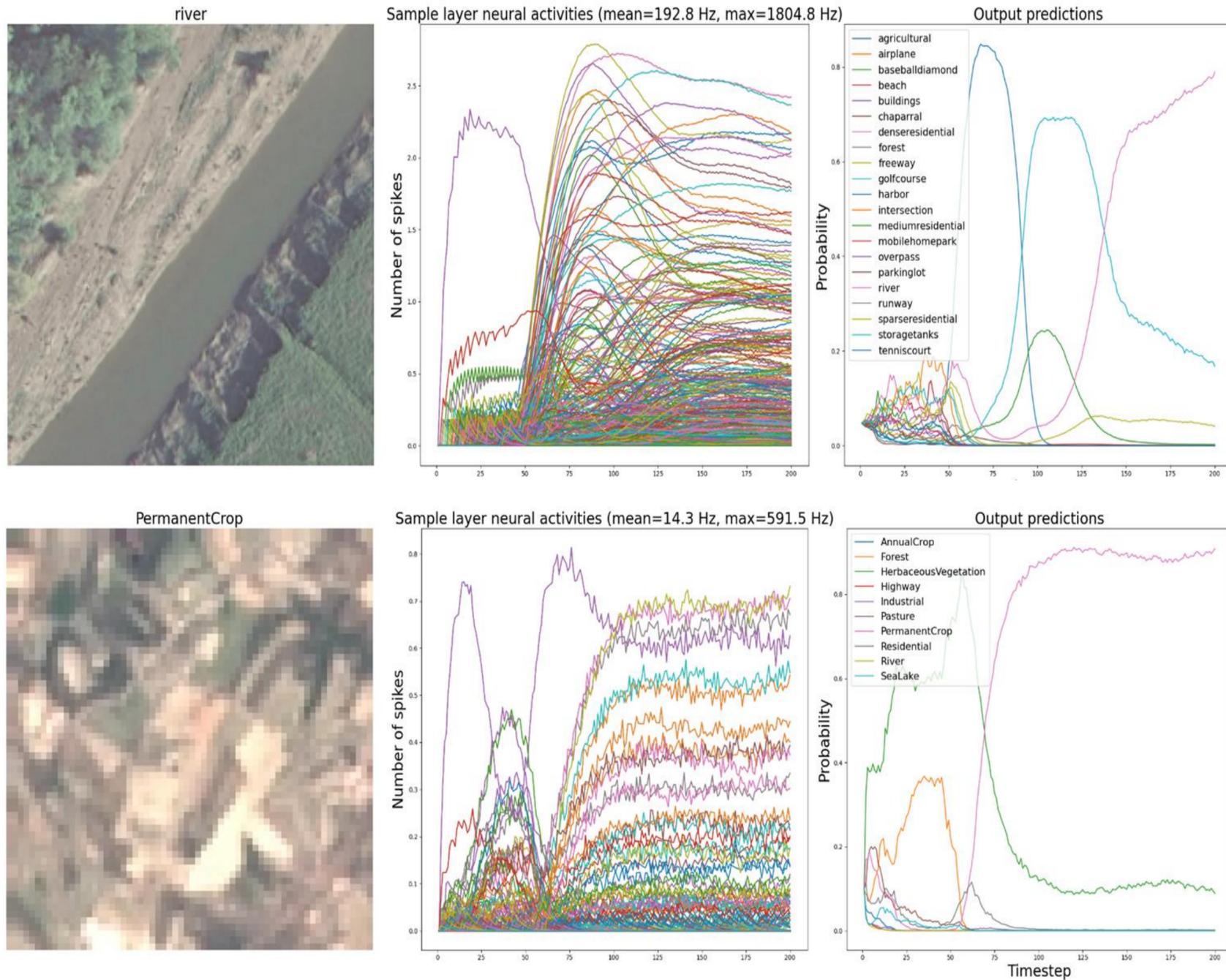


European Space Agency

An example of longer term perspective: Neuromorphic computing for EO



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Data

- UC Merced (21 classes, 100 256×256 examples each).
- EuroSAT RGB (10 classes, 27,000 64×64 images).

Methods

- Take one of the standard networks (possibly pre-trained on ImageNet).
- Train on the geospatial data.
- Convert to SNN.
- Replace elements incompatible with SNN.
- Optimise wrt accuracy and energy usage.

Results

- With the right parameters, the drop in accuracy is not very significant ($\sim 2\%$).
- 16x less energy for SNN on neuromorphic hardware than for ANN on a GPU.

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European Space Agency

“Technology... is only a magnifier of human intent and capacity. It is not a substitute.”

Kentaro Toyama
Geek Heresy: Rescuing
Social Change from the Cult
of Technology

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